

FACILITY FORM 602	<u>N69-37780</u>	_____
	(ACCESSION NUMBER)	(THRU)
	_____	_____
	(PAGES)	(CODE)
	<u>CR-152260</u>	_____
	(NASA CR OR TMX OR AD NUMBER)	(CATEGORY)

CONTRACT NUMBER NAS8-21155  
SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

**CASE I**  
**DDV**

Performed for

NATIONAL AERONAUTICS & SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

By

THE BENDIX CORPORATION  
THE BENDIX SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

THE BENDIX CORPORATION  
 BENDIX SEMICONDUCTOR DIVISION  
 HOLMDEL, NEW JERSEY

T A B L E O F C O N T E N T S

<u>Section</u>	<u>Page</u>
FOREWORD	
1.	INTRODUCTION . . . . . 1
2.	CONCLUSION . . . . . 2
3.	2N1486 MANUFACTURER A . . . . . 5
4.	2N1724 MANUFACTURER B . . . . . 17
5.	2N1016D MANUFACTURER C . . . . . 29
6.	2N1514 MANUFACTURER H . . . . . 41
7.	2N2102 MANUFACTURERS D & J . . . . . 54
	(Note: See Appendix I)
8.	2N2034A MANUFACTURER E . . . . . 67
9.	2N2126 MANUFACTURER C . . . . . 80
10.	2N657A MANUFACTURER E . . . . . 92
11.	2N697 MANUFACTURER G & E . . . . . 104
	(Note: See Appendix I)
12.	2N2880 MANUFACTURER H . . . . . 117
13.	2N4150 MANUFACTURER H . . . . . 131
14.	2N5559 BENDIX SEMICONDUCTOR . . . . . 146
15.	2N5560 BENDIX SEMICONDUCTOR . . . . . 164
16.	APPENDIX I . . . . . 182

## FOREWORD

### SAFE OPERATING AREA (SOAR)

The Bendix SOAR principle is a method of specifying the Safe Operating Area for a transistor in a given application. SOAR defines the region which encloses all of the points representing simultaneous values of the collector current and the collector-to-emitter voltage which a transistor can safely handle under specified conditions of base current, time, junction temperature and average power dissipation. With transistors specified under the Bendix SOAR technique, second breakdown is virtually eliminated.

This report characterizes the Safe Operating Area of specific power transistors. The use of these Safe Operating Areas by designers will help avoid transistor second breakdown through design and quality considerations.

## 1.0 INTRODUCTION

The purpose of this contract was to determine the true dynamic characteristics, Safe Operating Area (SOAR), of selected power transistors used in critical space applications.

Testing to determine device parameters was made in accordance with JEDEC "Suggested Standard 65" and similar to MIL-STD-750A. Reference to the aforementioned documents is made, where applicable, in the specification section of this Final Report.

Copies of the JEDEC "Suggested Standard 65" are available from:

Electronic Industries Association  
2001 Eye Street, N.W.  
Washington, D.C. 20006

The MIL-STD-750A document may be obtained from:

Commanding Officer  
Naval Publications & Forms Center  
5801 Tabor Avenue  
Philadelphia, Pennsylvania 19120

## 2.0 CONCLUSIONS

The specifications and SOAR curves generated as a result of this Contract verifies the actual power handling capability for each type of transistor. This information will serve to:

1. Provide valid derating information to establish necessary safety margins;
2. Provide guidelines for circuit analysis;
3. Provide documented Reliability Data;
4. Provide a means to improve the overall quality of devices now used by MSFC.

The individual reports contain a detailed analysis of Safe Operating Area for devices not previously characterized for SOAR. Highlights from each device are summarized here as a guide to design personnel.

- 2N1486 Manufacturer A. Suggest change of spec.  
( $\theta_{J-C} = 3 \text{ }^{\circ}\text{C/W}$ ) to extend DC power rating. 33W at  $T_C = 100^{\circ}\text{C}$  provides safety margin for continuous operation. High energy device ideal for switching inductive loads.
- 2N1724 Manufacturer B. Device can sustain the rated power for all operating conditions.
- 2N1016D Manufacturer C. Device is capable of handling the manufacturers power rating.

- 2N1514 Manufacturer H. Marginal  $h_{FE}$  at 6A. Review circuits.
- 2N2102 Manufacturers D & J. Composite SOAR curves indicate that devices may vary from lot to lot by different manufacturers.
- 2N2034A Manufacturer E. Good energy dissipating capability.
- 2N2126 Manufacturer C.  $I_{CEO}$  should be part of specification to insure forward biased condition at high  $V_{CE}$  and low collector current.
- 2N657A Manufacturer E. A small device, heats up quickly causing failure at lower than published parameters.
- 2N697 Manufacturers G & E. Composite SOAR curves indicates a specification review of manufacturers E's device.
- 2N2880 Manufacturer H. Suggest continuous maximum DC rating be reduced from 5A to 3A. ( $I_E = 5.5A$  discolors leads.)

The following devices have recently been registered by Bendix and are not specifically covered by this Contract, however the results and data are included without charge, as additional information for NASA personnel. The format used in the presentation of this data was recently developed for the registration of transistor specifications.

SOAR Characteristics:

	$T_{STG}$		$T_J$	$V_{CEX}$	$V_{EBO}$	$V_{CBO}$	$I_C$	$P_T$
	max	min						
2N5559	+200	-65°C	200°C	100V	7V	150V	10A	100W
2N5560	+200	-65°C	200°C	120V	8V	175V	30A	150W

The information obtained by this contract provides invaluable assistance to all concerned with the application, selection, performance, and most important, reliability of semiconductor devices in critical NASA systems.

The effect of SOAR evaluation is far-reaching, and should be a mandatory requirement for all power semiconductors being used by NASA in its Aeronautical and Space programs.

The Bendix Semiconductor Division hereby proposes that NASA continue this program with Bendix to further assist NASA in achieving the highest levels of Reliability in their programs.

Silicon Power Transistor  
Type 2N1486

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer A --

Performed for  
NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract No. NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

ItemTest Methods and Test Conditions1.0.0 General Description

1.1.0 Type -- NPN

1.2.0 Material -- Silicon

2.0.0 Mechanical Data

2.1.0 Outline -- TO-8

## 2.2.0 Terminal Designation

1 -- Emitter

2 -- Base

3 -- Collector

case -- Collector

3.0.0 Maximum Ratings

## 3.1.0 Temperature

3.1.1  $T_{STG(max)} = +200^{\circ}C$  JS-6-T1.2 $T_{STG(min)} = -65^{\circ}C$  JS-6-T1.13.1.2  $T_J = 200^{\circ}C$  JS-6-T2 $T_C = 100^{\circ}C, V_{CB} = 55V, P_T = 14.3W$ 

## 3.2.0 Voltage

3.2.1  $V_{CBO} = 100V$  JS-6-T3 or MIL-STD-750, method 3001.13.2.2  $V_{EBO} = 12V$  JS-6-T4 or MIL-STD-750A method 3026.13.2.3  $V_{CEX} = 100V$  JS-6-T5-2.1 $I_C = 3.0A, V_{CC} = 100V, R_L = 33\Omega,$  $L = 1mH^*, CR -- 1N1204, V_{BB1} = 12V,$  $R_{BB1} = 10\Omega, V_{BB2} = 3V, R_{BB2} = 10\Omega$ Duty Cycle = 2%,  $t_p = 1.65 ms.$ \*Miller No. 7871 in series with  
Miller No. 7825-3

## 3.3.0 Current

3.3.1  $I_C = 3A$  JS-6-T6,  $I_B = 300mA, T_C = 25^{\circ}C$

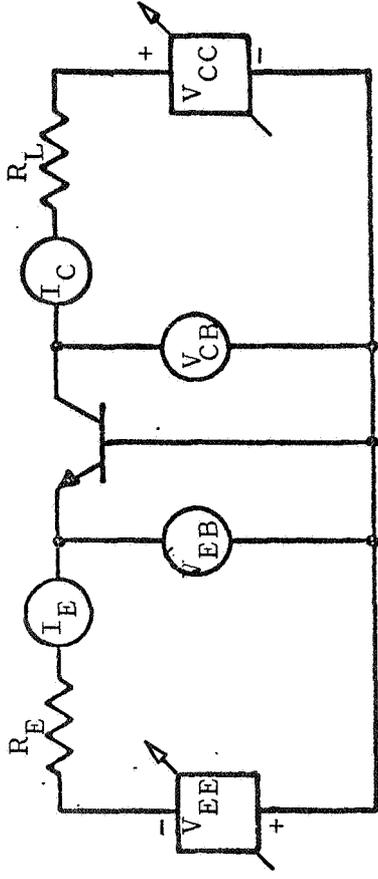
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.3.2	<u>JS-6-T8</u> $T_C = 25^{\circ}\text{C}$
3.3.3 $I_C = -3.5\text{A}$	<u>JS-6-T10</u> $I_B = 500\text{mA}, T_C = 25^{\circ}\text{C}$
3.4.0     Power	
3.4.1 $P_T = 14.3\text{W}$	<u>JS-6-T12</u> $T_C = 100^{\circ}\text{C}, V_{CB} = 55\text{V}, I_C = .26\text{A}$ Derating Factor - $.143 \text{ W}/^{\circ}\text{C}$
3.4.2 $P_{TM} = I_C V_{CC} = 150\text{W}$	<u>JS-6-T13</u> $T_C = 100^{\circ}\text{C}, V_{CC} = 50\text{V}, V_{BB} = 3\text{V}$ $R_{BB} = 10\Omega, I_C = 3\text{A}, \text{Pulse Width} = 5\text{ms},$ Duty Cycle = 5%, $t_r \leq 50\mu\text{s},$ $t_f \leq 50\mu\text{s}$
3.5.0     Maximum Operating Condition	
3.5.1     Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> (See Figure 1) <u>Test Point</u> (See 3.4.1)
3.5.2     Pulsed Forward Biased SOAR	<u>JS-6-T-14</u> (See Figure 2) <u>Test Points:</u> $T_C = 100^{\circ}\text{C}, V_{BB} = 3\text{V}, R_{BB} = 10\Omega,$ $t_r \leq 50\mu\text{s}, t_f \leq 50\mu\text{s}, I_C = 3\text{A},$ Duty Cycle $\leq 1\%, R_S = 0.1\Omega$ 1. For $t_p = 50\text{ms}: V_{CC} = 10\text{V}$ 2. For $t_p = 20\text{ms}: V_{CC} = 25\text{V}$

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.5.2	Pulsed Biased (Cont'd) Continuous DC SOAR	3. For $t_p = 10\text{ms}$ , $V_{CC} = 40\text{V}$ 4. For $t_p = 5\text{ms}$ , $V_{CC} = 50\text{V}$
3.6.0	SOAR Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<u>JS-6-T5-2.1</u> with $L = 0$ and CR disconnected. See (Figure 3)  <u>Test Points:</u>  $R_{BB1} = 10\Omega$ , $R_{BB2} = 10\Omega$ , $V_{BB1} = 12\text{V}$ , $V_{BB2} = 3\text{V}$ , $T_C = 100^\circ\text{C}$ , $t_f \leq 50\mu\text{s}$ (Coll. Current); $t_r \leq 50\mu\text{s}$ (Coll. Current), $R_S = 0.1\Omega$ , $I_C = 3\text{A}$ ,  $V_{CC} = 100\text{V}$
3.6.2	Clamped Inductive Load	<u>JS-6-T5.1</u> (See Figure 4)  Test Points: (See 3.2.3)
3.6.3	Unclamped Inductive Load	<u>JS-6-T5.1</u> and CR disconnected (See Figure 5)  <u>Test Points:</u>  1. $V_{BB1} = 12\text{V}$ , $L = 20\text{mH}^*$ $R_{BB1} = 10\Omega$ , $R_L = 4.1\Omega$ $V_{BB2} = 3\text{V}$ , $V_{CC} = 12.5\text{V}$ $R_{BB2} = 10\Omega$ , $f = 10\text{Hz}$ $R_S = 0.1\Omega$ , $d = 15\%$  *Series Stancor C-2688

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
3.7.0	Shorted Class B SOAR	(See Figure 6)
		<u>Test Points:</u>
		$I_C(\text{peak}) = .75\text{A}, V_{CC} = 55\text{V}, R_S = 0.1\Omega$
		$R_{BB1} = 10\Omega, R_{BB2} = 10\Omega, f = 20\text{Hz},$
		$T_C = 100^\circ\text{C}$
4.0.0	<u>Electrical Characteristics</u>	
	Maximum Limits unless otherwise noted.	
	Technique:	
	DC = continuous operation	
	C.T. = Curve Tracer	
	P = 300 $\mu$ s Pulse, 2% Duty Cycle	
4.1.0	Static	
4.1.1	$I_{CEV} = 10\mu\text{A}$	$V_{CEV} = 100\text{V}, V_{EB} = 1.5\text{V}, \text{Technique} = \text{C.T.}$
4.1.2	$I_{CBO} = 15\mu\text{A}$	$V_{CB} = 30\text{V}, \text{Technique} = \text{C.T.}$
4.1.3	$I_{CBO} = 750\mu\text{A}$	$V_{CB} = 30\text{V}, T_C = 150^\circ\text{C}, \text{Technique} = \text{C.T.}$
4.1.4	$I_{EBO} = 15\mu\text{A}$	$V_{EB} = 12\text{V}, \text{technique} = \text{C.T.}$
4.1.5	$I_{CEO} = 50\mu\text{A}$	$V_{CEO} = 50\text{V}, \text{technique} = \text{C.T.}$
4.1.6	$V_{CEO} = 55\text{V min.}$	$I_{CEO} = 100\text{mA}, \text{technique} = \text{C.T.}$
4.1.7	$V_{CEV} = 100\text{V}$	$I_C = 100\text{mA}, V_{EB} = 1.5\text{V}, \text{technique} = \text{C.T.}$
4.1.8	$h_{FE} = 35 \text{ min.}$ $h_{FE} = 100 \text{ max.}$	$V_{CE} = 4\text{V}, I_C = 750\text{mA}, \text{technique} = \text{C.T.}$
4.1.9	$V_{CE[\text{SAT}]} = .75\text{V}$	$I_C = 0.75\text{A}, I_B = .04\text{A}, \text{technique} = \text{C.T.}$

<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.1.10	$V_{CE[SAT]} = 2.5V$	$I_C = 3A, I_B = 300mA, \text{ technique} = C.T.$
4.1.11	$V_{BE[SAT]} = 3.0V$	$I_C = 3A, I_B = 300mA, \text{ technique} = C.T.$
4.1.12	$V_{BE} = 2.5V$	$I_C = 750mA, V_{CE} = 4V, \text{ technique} = C.T.$
4.2.0	Dynamic	
4.2.1	$f_{hfb} = 1MHz \text{ min.}$ $f_{hfb} = 10 \text{ MHz max.}$	$I_C = 5mA, V_{CE} = 28V$
4.2.2	$C_{obo} = 175pF$	$V_{CB} = 40V, \text{ MIL-STD -750 method 3236}$
5.0.0	Thermal Characteristics	
5.1.0	$\tau_J = 40mS \text{ min.}$	$I_C = 1A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD -750 method 3146.1
5.2.0	$\theta_{J-C} = 7.0 \text{ }^\circ C/W$	$I_C = 1A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD -750 method 3136
5.3.0	$\theta_{J-A} = 100 \text{ }^\circ C/W$	$I_C = .5A, V_{CE} = 3.5V, \text{ MIL-STD -750}$ method 3151

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

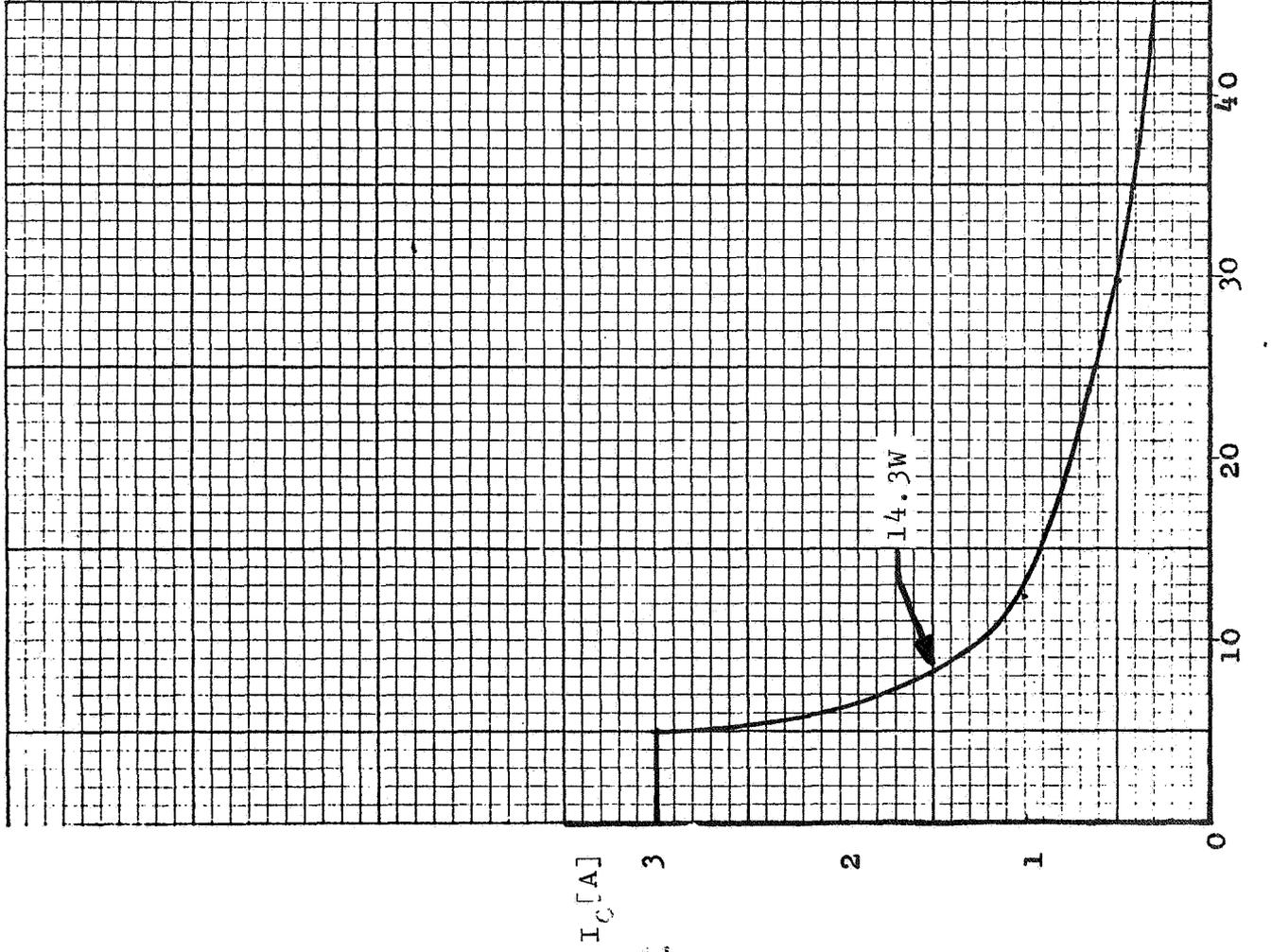
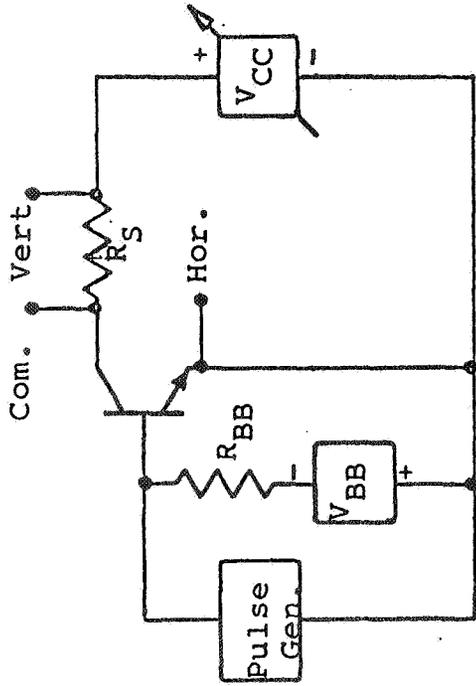


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

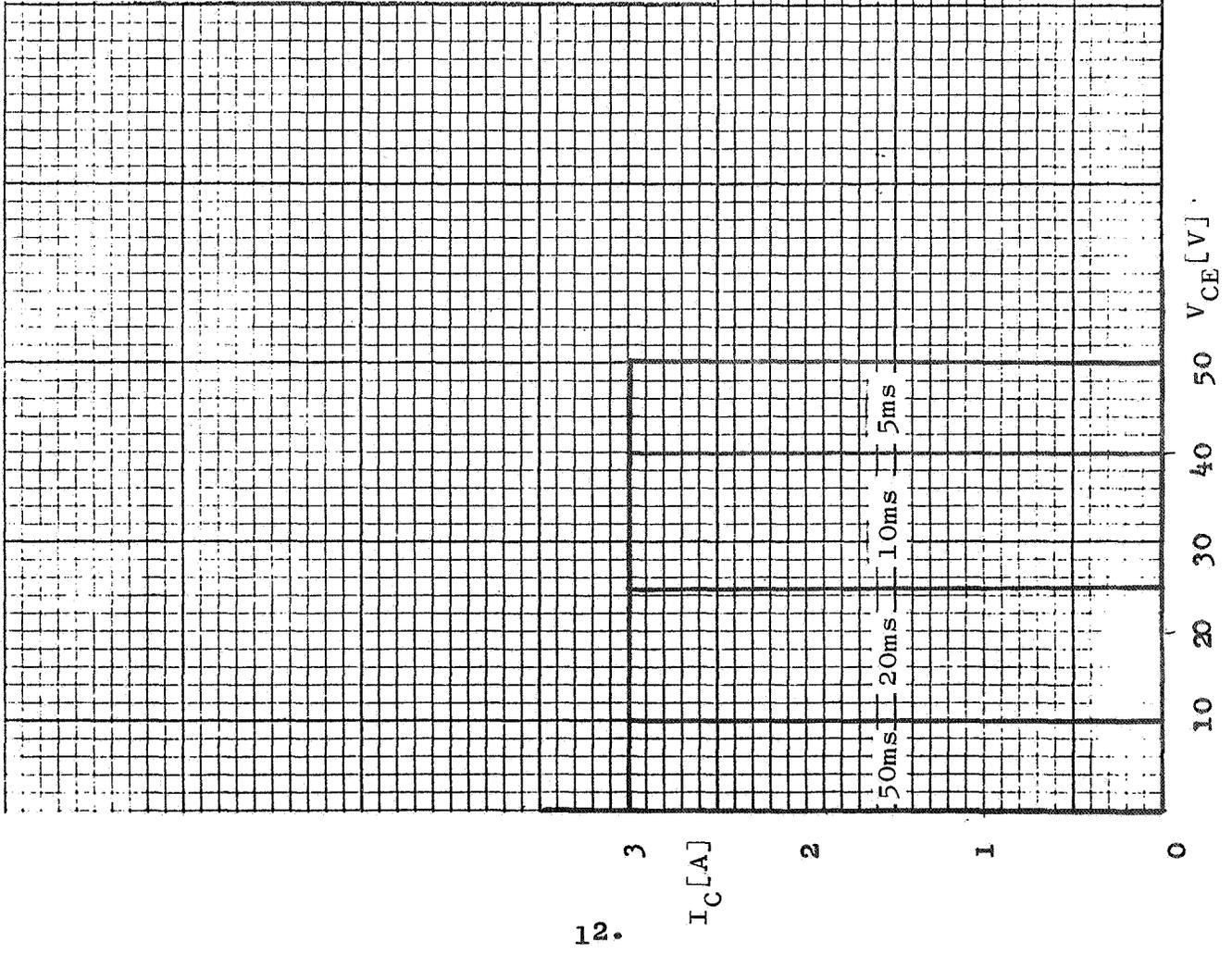
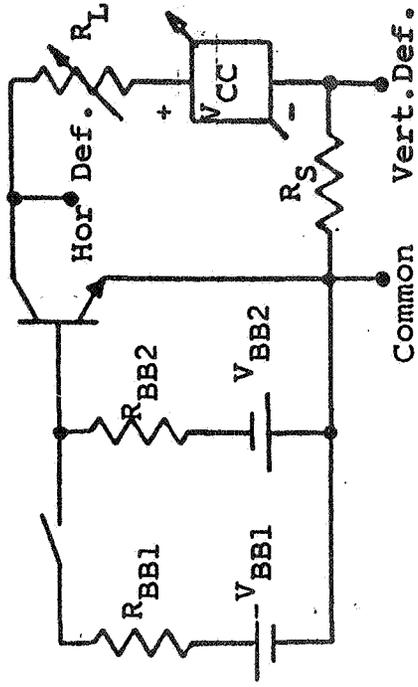


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

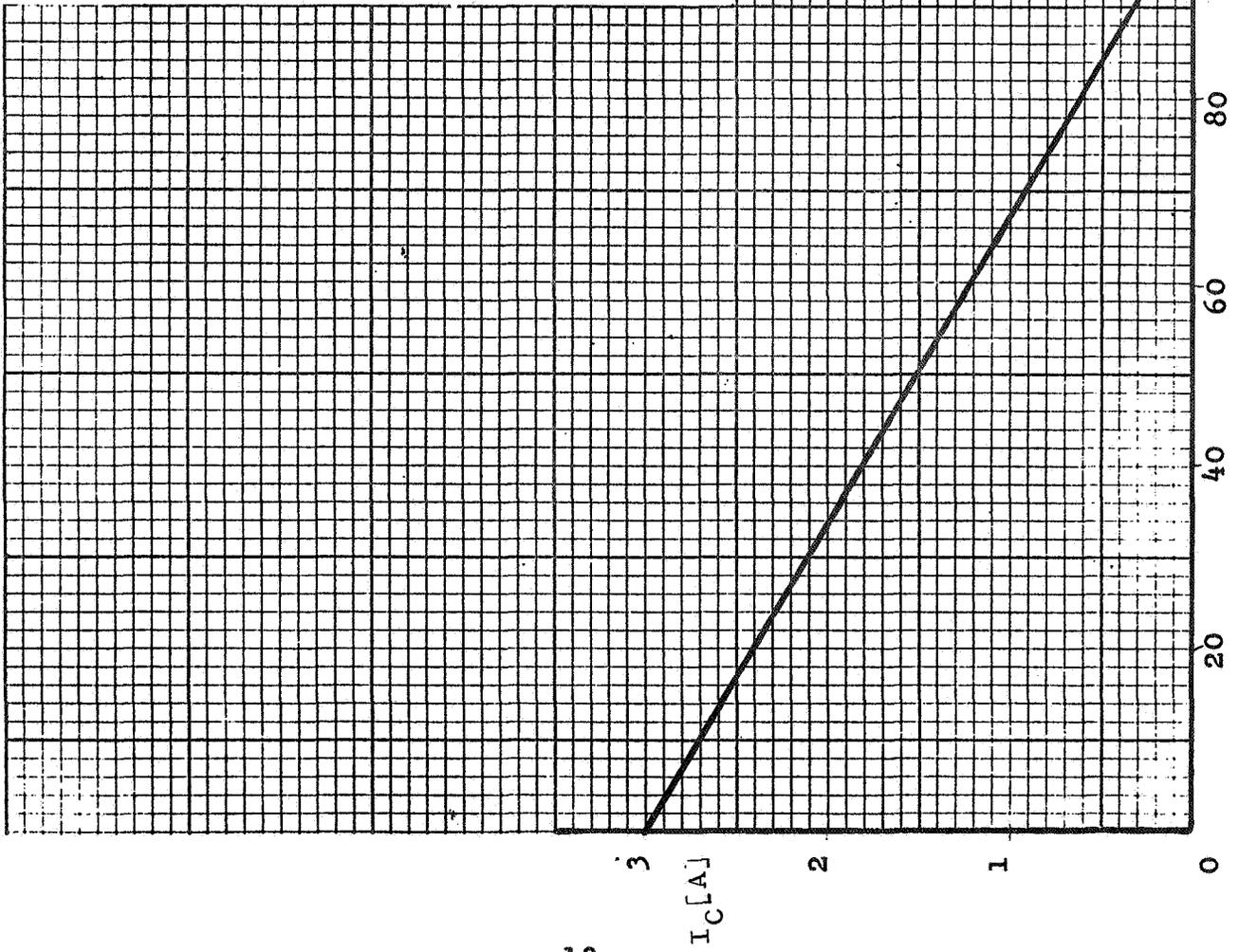
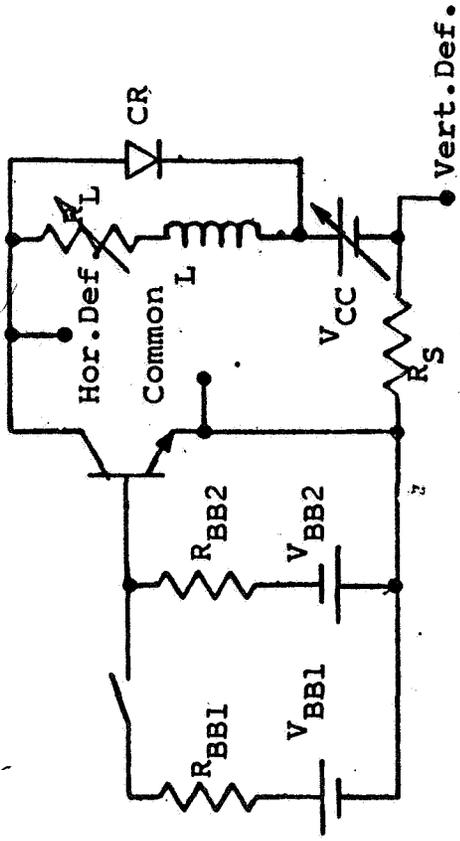


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

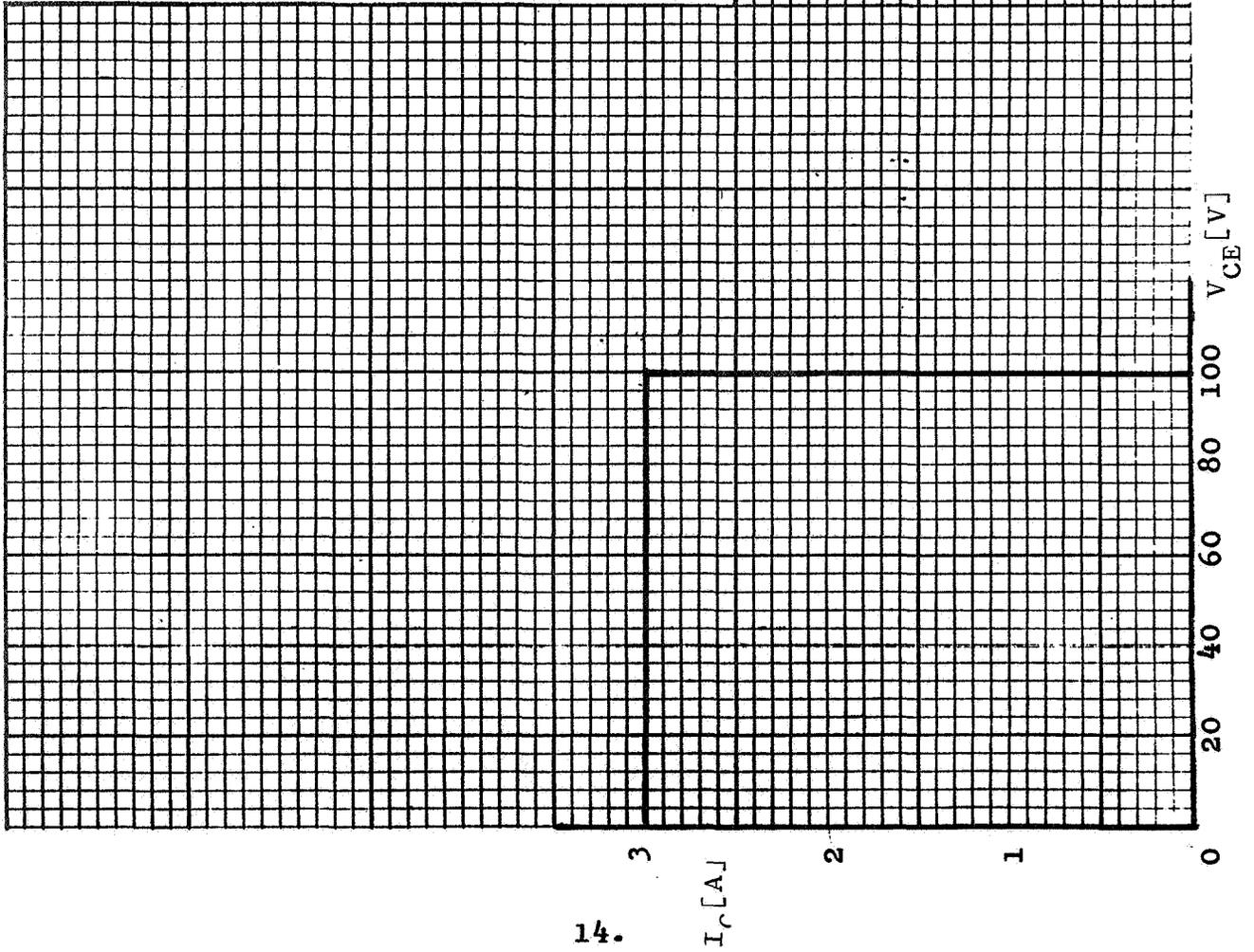
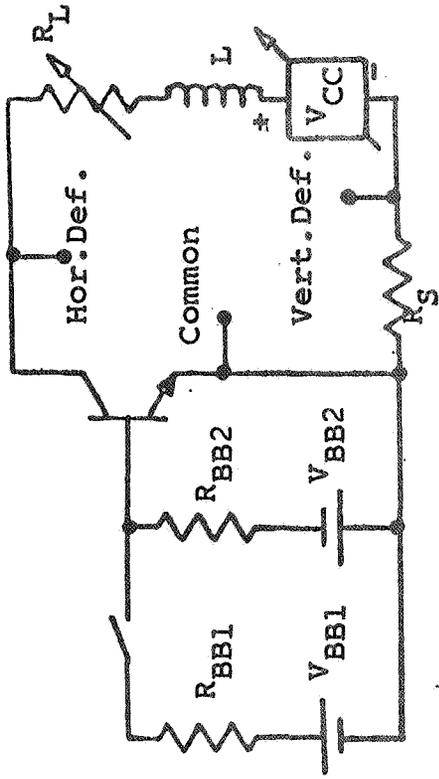


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

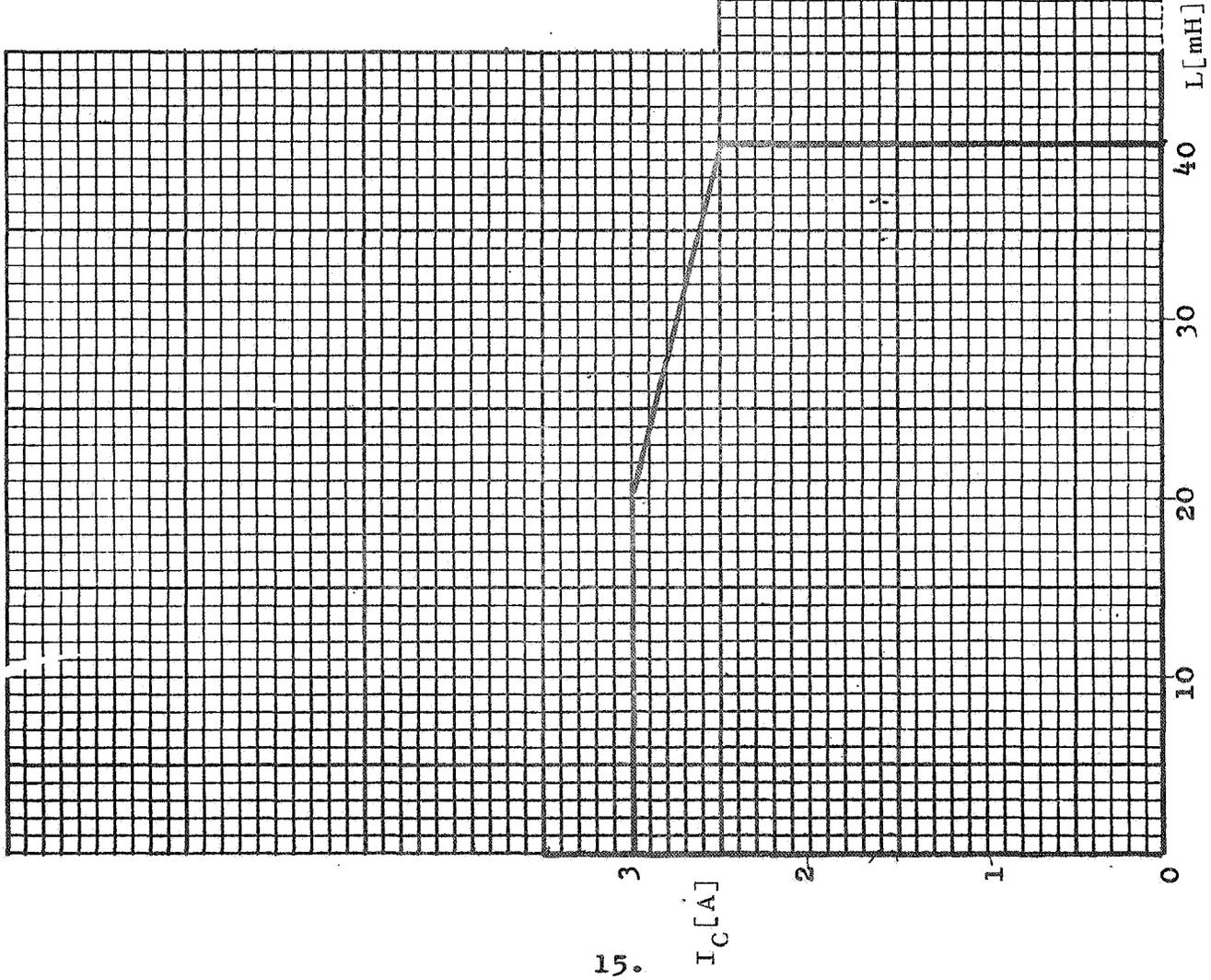


Figure 5

SHORTED CLASS B SOAR

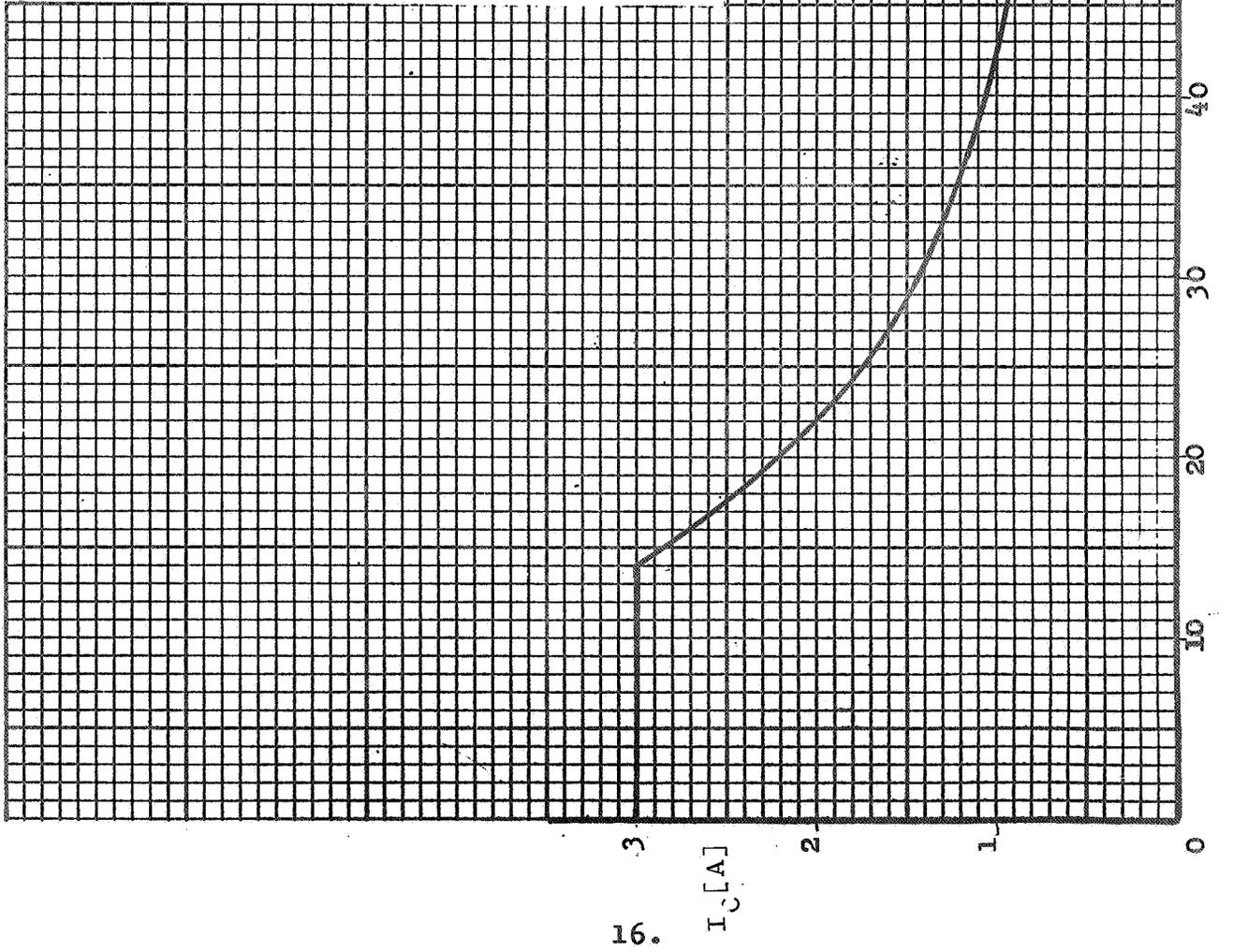
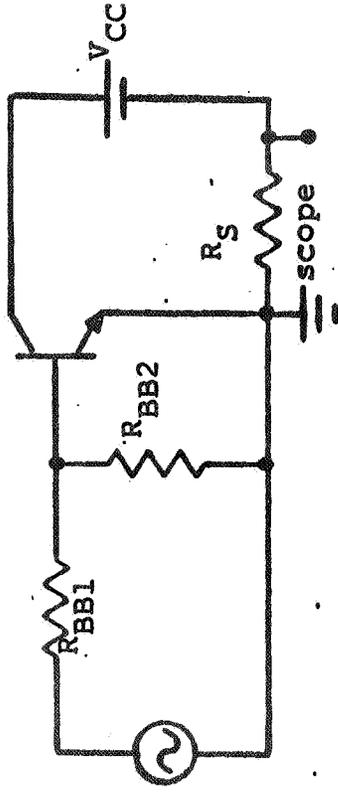


Figure 6

SILICON POWER TRANSISTOR

< Type 2N1724 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer B --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Method and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type -- NPN	
1.2.0	Material -- Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline -- TO-61	
2.2.0	Terminal Designation	
	1 -- Emitter	
	2 -- Base	
	3 -- Collector	
	case -- Collector	
2.2.1	Maximum Stud Torque -- 30 in. lb.	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = +200^{\circ}C$	<u>JS-6-T1.1</u> (JEDEC Suggested Standard: "Test Procedures for Verifications of Maximum Ratings")
	$T_{STG(min)} = -65^{\circ}C$	<u>JS-6-T1.2</u>
3.1.2	$T_{J(max)} = +175^{\circ}C$	<u>JS-6-T2</u> $T_C = 100^{\circ}C, V_{CB} = 10V, I_C = 5A$
3.1.3	$T(Lead) = 230^{\circ}C$	Distance from case = $\frac{1}{4}$ in. Time = 10s
3.2.0	Voltage	$T_C = 25^{\circ}C$
3.2.1	$V_{CBO} = 120V$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1
3.2.2	$V_{EBO} = 10V$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1

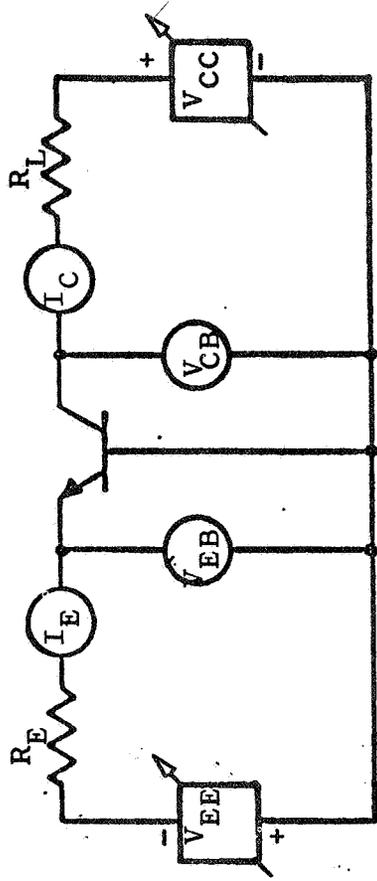
<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.2.3	$V_{CEV} = 80V$	<u>JS-6-T5-2.1</u> $I_C (V_{CE} = V_{CEX}) = 7.5A$ $V_{CC} = 80V, R_L = 10.3\Omega, L = 1mH,$ (Miller #7870), $CR = 1N1204, V_{BB1} = 15V,$ $R_{BB1} = 5\Omega, V_{BB2} = 5V, R_{BB2} = 10\Omega,$ Pulse width = 10ms, Duty Cycle = 10%, $R_S = 0.1\Omega$
3.3.0	Current	
3.3.1	$I_C = 5A$	<u>JS-6-T6</u> $I_B = 1A, T_C = 25^\circ C$
3.3.2	$I_{CM} = 7.5A$	<u>JS-6-T7</u> $T_C = 25^\circ C, R_S = 0.1\Omega, V_{BB} = 5V,$ $R_{BB} = 10\Omega$ Pulse Amplitude = 5.3V, R source = $1\Omega$ Pulse Width = 20ms, Duty Cycle = 20% $t_r \leq 50\mu s, t_f \leq 50\mu s$
3.3.3	$I_B = 2A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.4	$I_E = 6A$	<u>JS-6-T10</u> $I_B = 1A, T_C = 25^\circ C$
3.4.0	Power	
3.4.1	$P_T = 50W$	<u>JS-6-T12</u> $T_C = 100^\circ C, V_{CB} = 80V, I_C = 625mA$ Derating factor = $0.667W/^\circ C$



<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.2	<p>Clamped Inductive Load</p> <p><u>JS-6-T5-2.1</u> (See Figure 4)</p> <p><u>Test Point:</u> (See 3.2.3)</p>
3.6.3	<p>Unclamped Inductive Load</p> <p><u>JS-6-T5-2.1</u> and CR disconnected (See Figure 5)</p> <p><u>Test Point:</u></p> <p>[1.] <math>R_{BB1} = 5\Omega</math>, <math>R_{BB2} = 10\Omega</math>,  <math>V_{BB1} = 15V</math>, <math>V_{BB2} = 5V</math>,  <math>L = 5mH</math>, <math>0.03\Omega</math> (Stancor #C-2689)  <math>I_C = 7.5A</math>, <math>V_{CC} = 18V</math>, <math>R_L = 2\Omega</math>,  <math>R_S = 0.1\Omega</math>, <math>d \leq 10\%</math>, <math>T_C = 25^\circ C</math>, <math>t_p = 10ms</math></p> <p>[2.] <math>R_{BB1} = 5\Omega</math>, <math>R_{BB2} = 10\Omega</math>,  <math>V_{BB1} = 8V</math>, <math>V_{BB2} = 5V</math>, <math>L = 20mH</math>,  <math>0.22\Omega</math> (two in series Stancor #C-2688)</p> <p><math>I_C = 2.5A</math>, <math>V_{CC} = 13.5V</math>, <math>R_L = 5\Omega</math>,  <math>R_S = 0.1\Omega</math>, <math>T_C = 25^\circ C</math>, <math>d \leq 10\%</math>, <math>t_p = 10ms</math></p>
3.7.0	<p>Shorted Class B SOAR (See Figure 6)</p> <p><u>Test Point:</u></p> <p><math>I_C \text{ peak} = 1.88A</math>, <math>V_{CC} = 80V</math>, <math>R_S = 0.1\Omega</math>,  <math>R_{BB1} = 1\Omega</math>, <math>R_{BB2} = 10\Omega</math>, <math>f=20Hz</math>,  <math>T_C = 100^\circ C</math></p>
4.0.0	<p><u>Electrical Characteristics</u></p> <p>Maximum limits unless otherwise noted</p> <p>Technique:</p> <p>DC - Continuous Operation</p> <p>C.T. - Curve Tracer</p> <p>P - <math>300\mu s</math> Pulse, 2% Duty Cycle</p> <p><math>T_C = 25^\circ C</math> (unless otherwise noted)</p>

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.1.0	Static	
4.1.1	$I_{CBO} = 0.5\text{mA}$	$V_{CB} = 3\text{V}$ Technique - C.T.
4.1.2	$V_{EBF} = 10\text{V}$	$V_{CB} = 80\text{V}$ Technique - C.T.
4.1.3	$I_{CES} = 1.0\text{mA}$	$V_{CE} = 60\text{V}$ Technique - C.T.
4.1.4	$I_{CES} = 2.0\text{mA}$	$T_C = 150^\circ\text{C}$ , $V_{CE} = 60\text{V}$ Technique - C.T.
4.1.5	$I_{CES} = 10\text{mA}$	$T_C = 150^\circ\text{C}$ , $V_{CE} = 120\text{V}$ Technique - C.T.
4.1.6	$I_{CEO} = 10\text{mA}$	$T_C = 25^\circ\text{C}$ , $V_{CE} = 80\text{V}$ Technique - C.T.
4.1.7	$I_{EBO} = 10\text{mA}$	$V_{EB} = 10\text{V}$ Technique - C.T.
4.1.8	$V_{CEO} = 80\text{V min.}$	$I_C = 0.2\text{A}$ Technique - C.T.
4.1.9	$h_{FE} = 20 \text{ min}$	$V_{CE} = 15\text{V}$ , $I_C = 0.1\text{A}$ Technique - C.T.
4.1.10	$h_{FE} = 20 \text{ min, } 90 \text{ max}$	$V_{CE} = 15\text{V}$ , $I_C = 2\text{A}$ Technique - P
4.1.11	$h_{FE} = 10 \text{ min}$	$V_{CE} = 2\text{V}$ , $I_C = 5\text{A}$ Technique - P
4.1.12	$V_{CE(sat)} = 1\text{V}$	$I_C = 2\text{A}$ , $I_B = 0.2\text{A}$ , Technique - C.T.
4.1.13	$V_{CE(sat)} = 2\text{V}$	$I_C = 7.5\text{A}$ , $I_B = 1.5\text{A}$ Technique - P
4.1.14	$V_{BE(sat)} = 2\text{V}$	$I_C = 2\text{A}$ , $I_B = 0.2\text{A}$ , Technique - C.T.
4.1.15	$V_{BE(sat)} = 2.5\text{V}$	$I_C = 7.5\text{A}$ , $I_B = 1.5\text{A}$ Technique - P
4.2.0	Dynamic	
4.2.1	$h_{fe} = 2.0 \text{ min}$ $= 10.0 \text{ max}$	$V_{CE} = 15\text{V}$ , $I_C = 0.5\text{A}$ , $f = 5 \text{ MHz}$
4.2.2	$C_{obo} = 550 \text{ pF max}$	$V_{CB} = 15\text{V}$ , $f = 1\text{MHz}$
5.0.0	Thermal Characteristics	
5.1.0	$\tau_J \text{ min} = 10\text{ms}$	$V_{CE} = 10\text{V}$ , $I_C = 2\text{A}$ , $T_C = 25^\circ\text{C}$ , MIL-STD-750, Method 3146.1
5.2.0	$\theta_{JC} = 1.5 \text{ }^\circ\text{C/W}$	$V_{CE} = 10\text{V}$ , $I_C = 2\text{A}$ , $T_C = 25^\circ\text{C}$ MIL-STD-750, Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

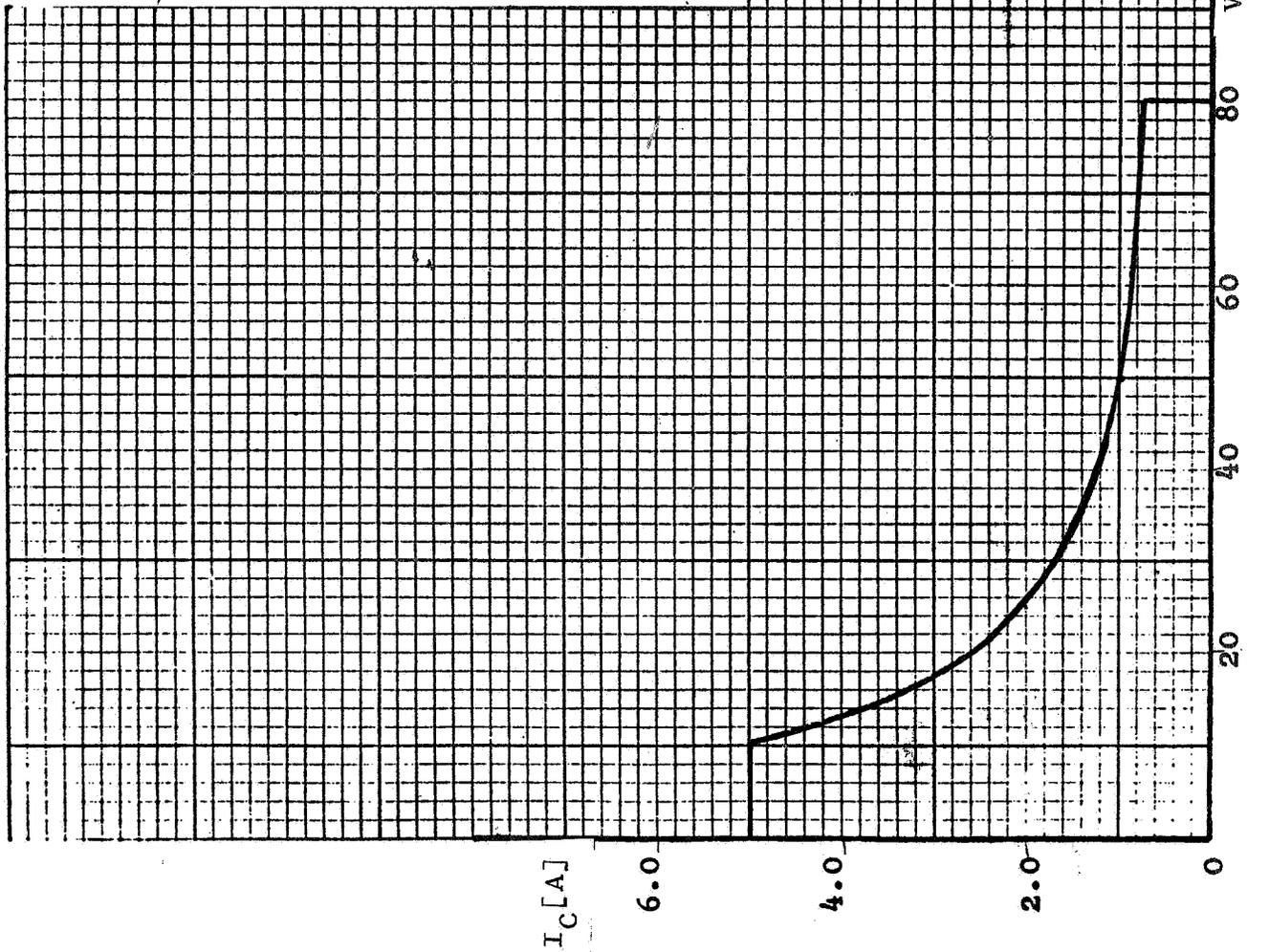
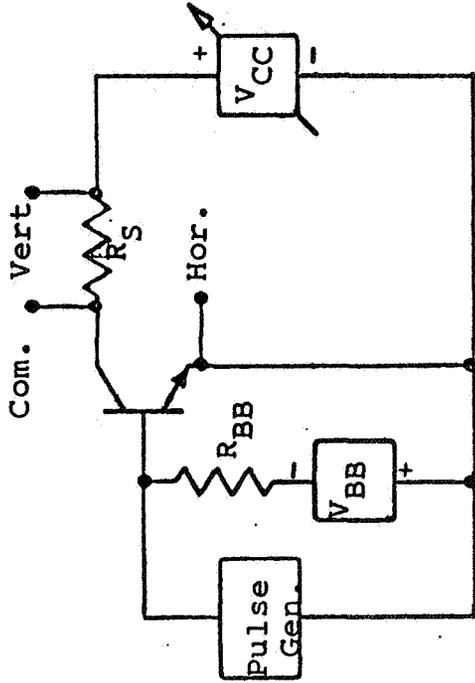


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

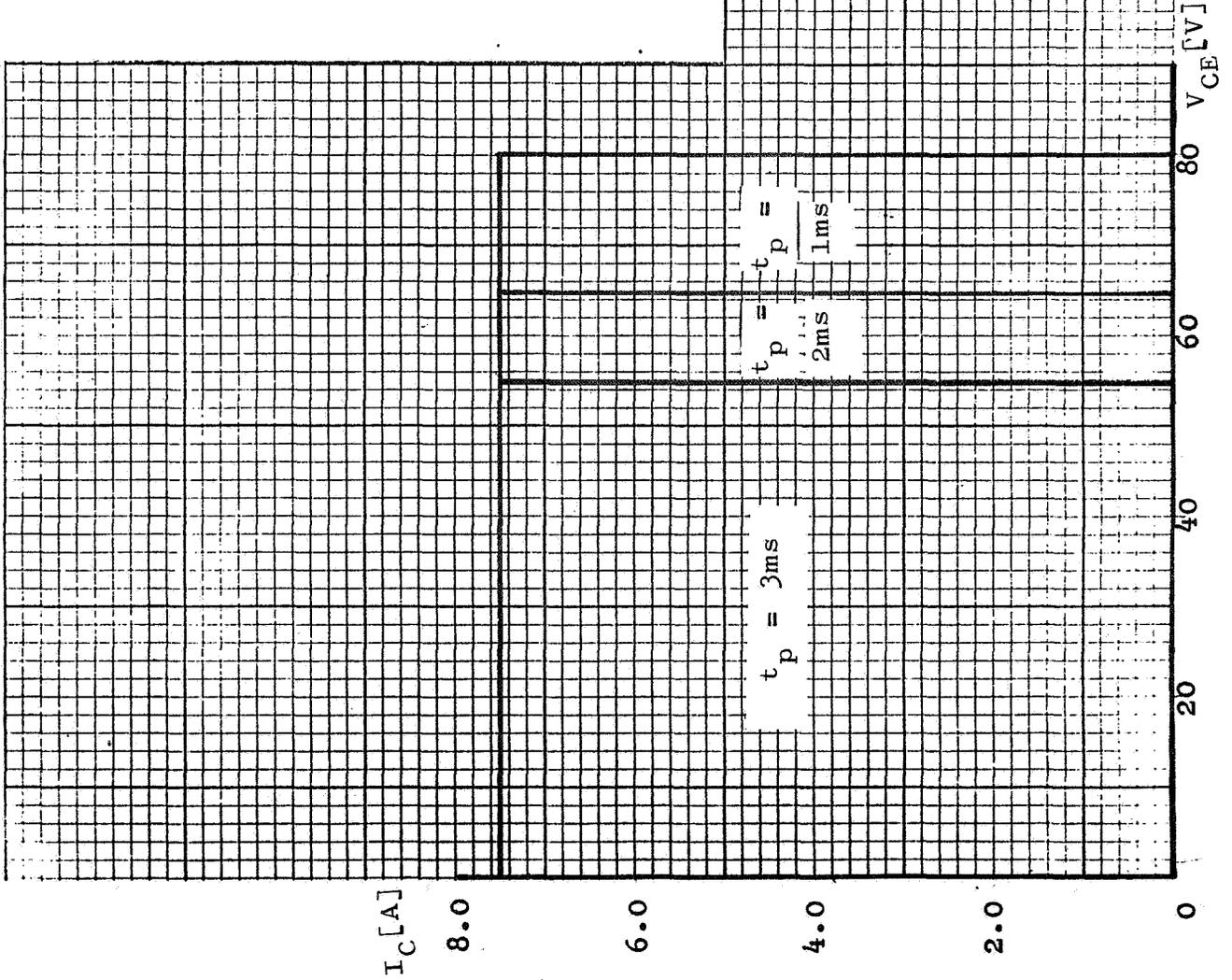
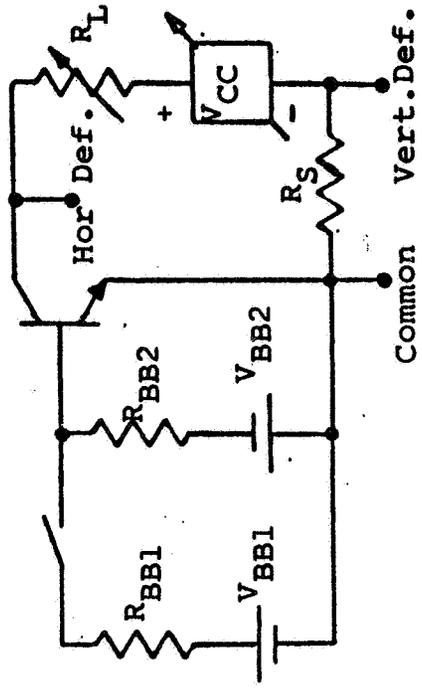


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

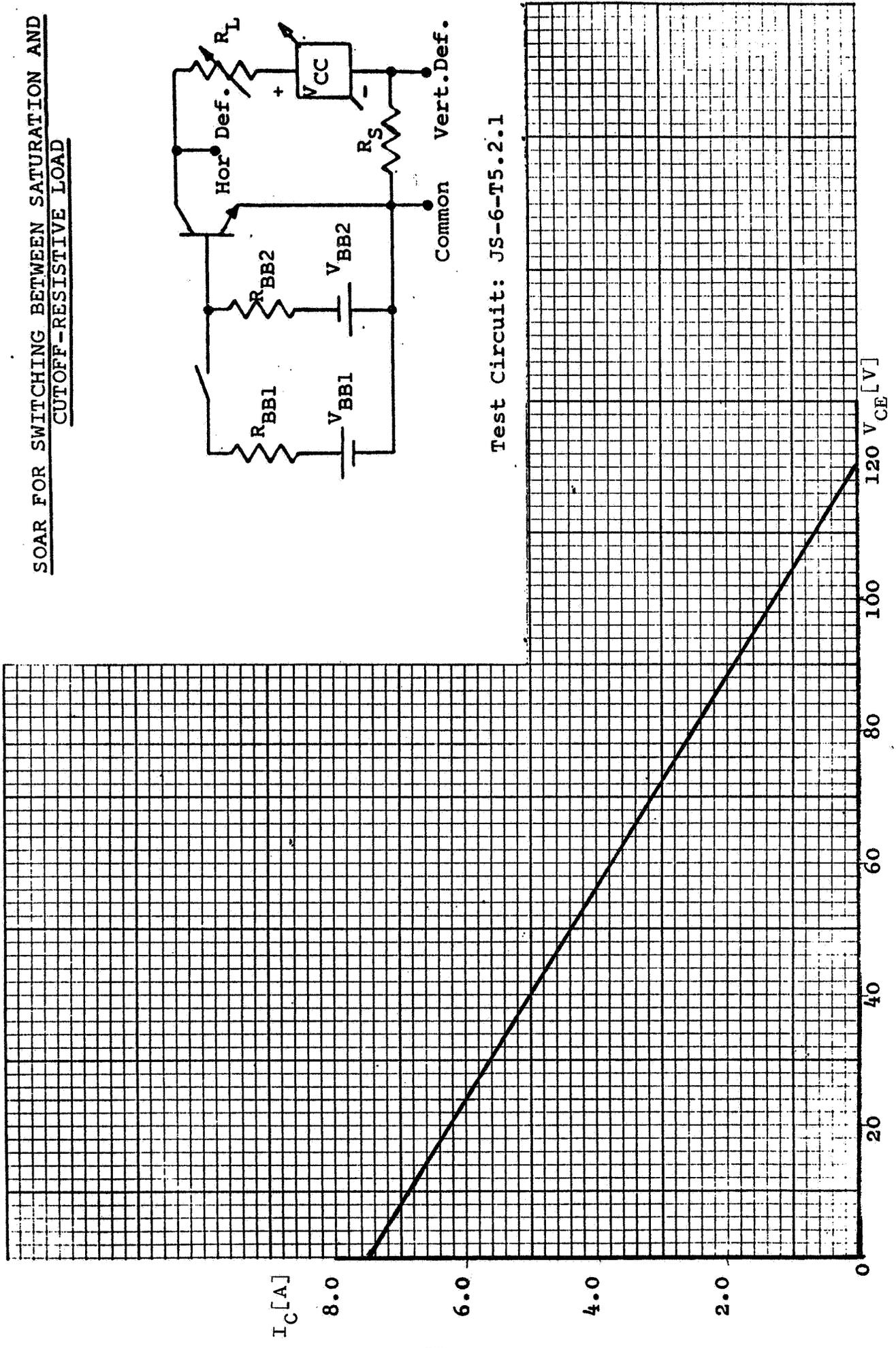
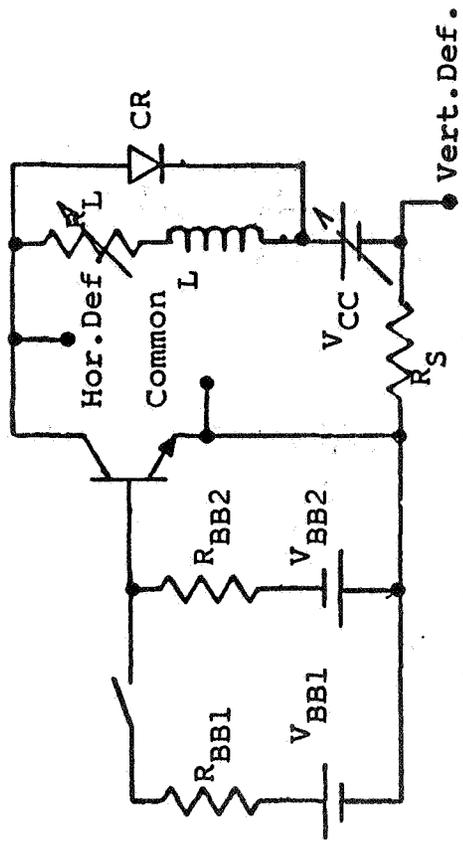


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

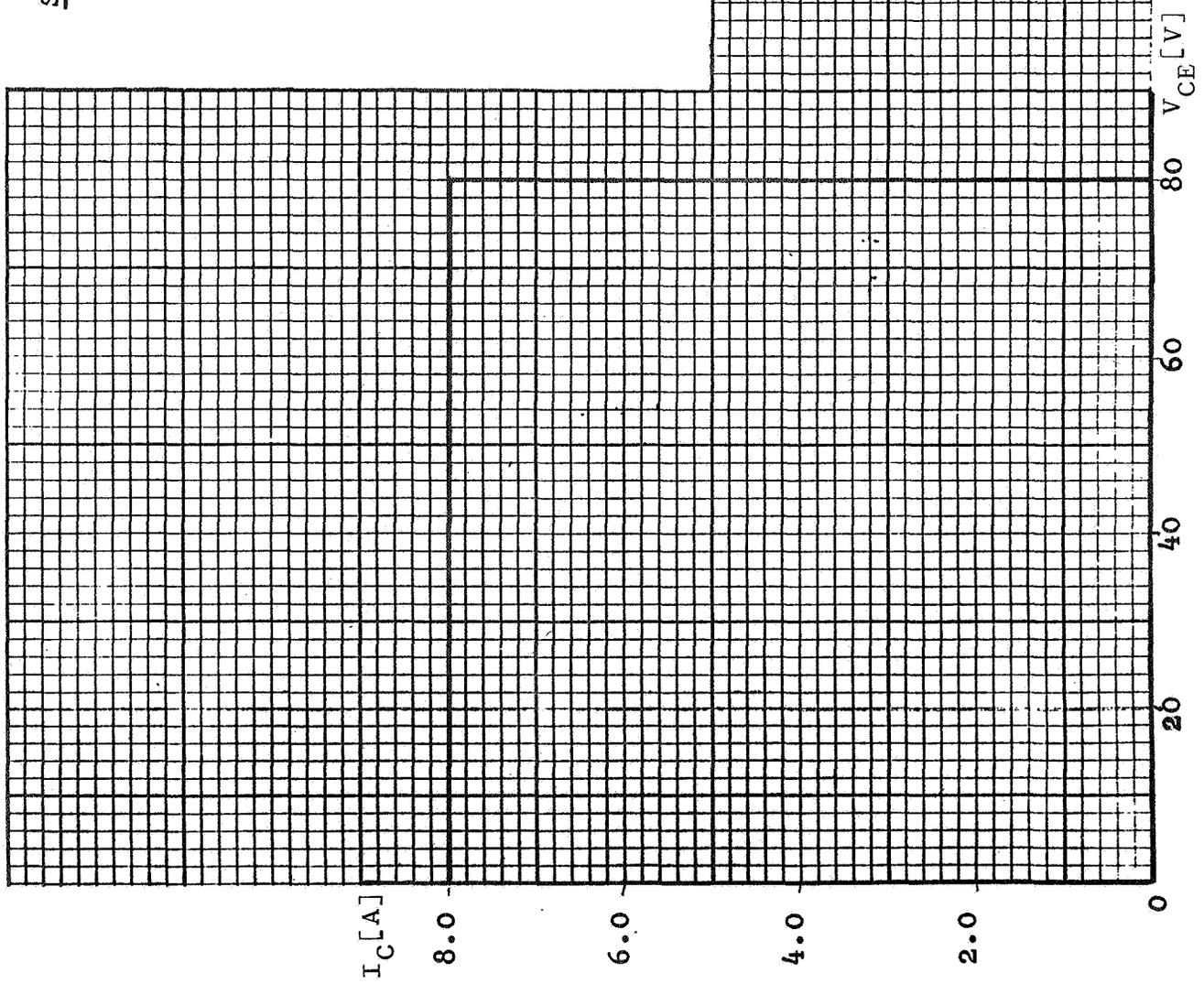
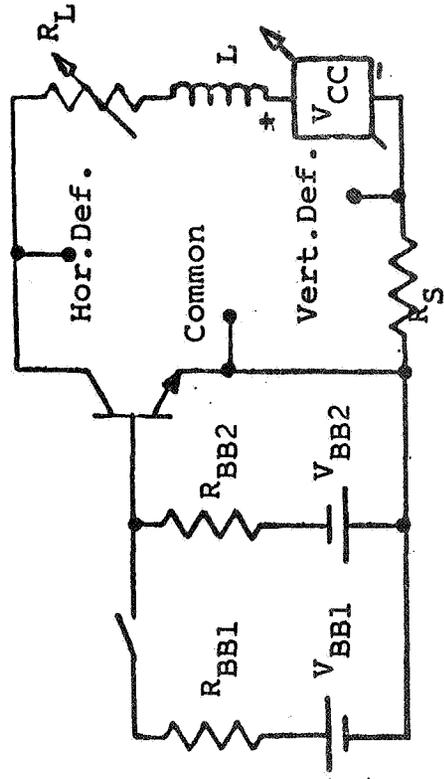


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

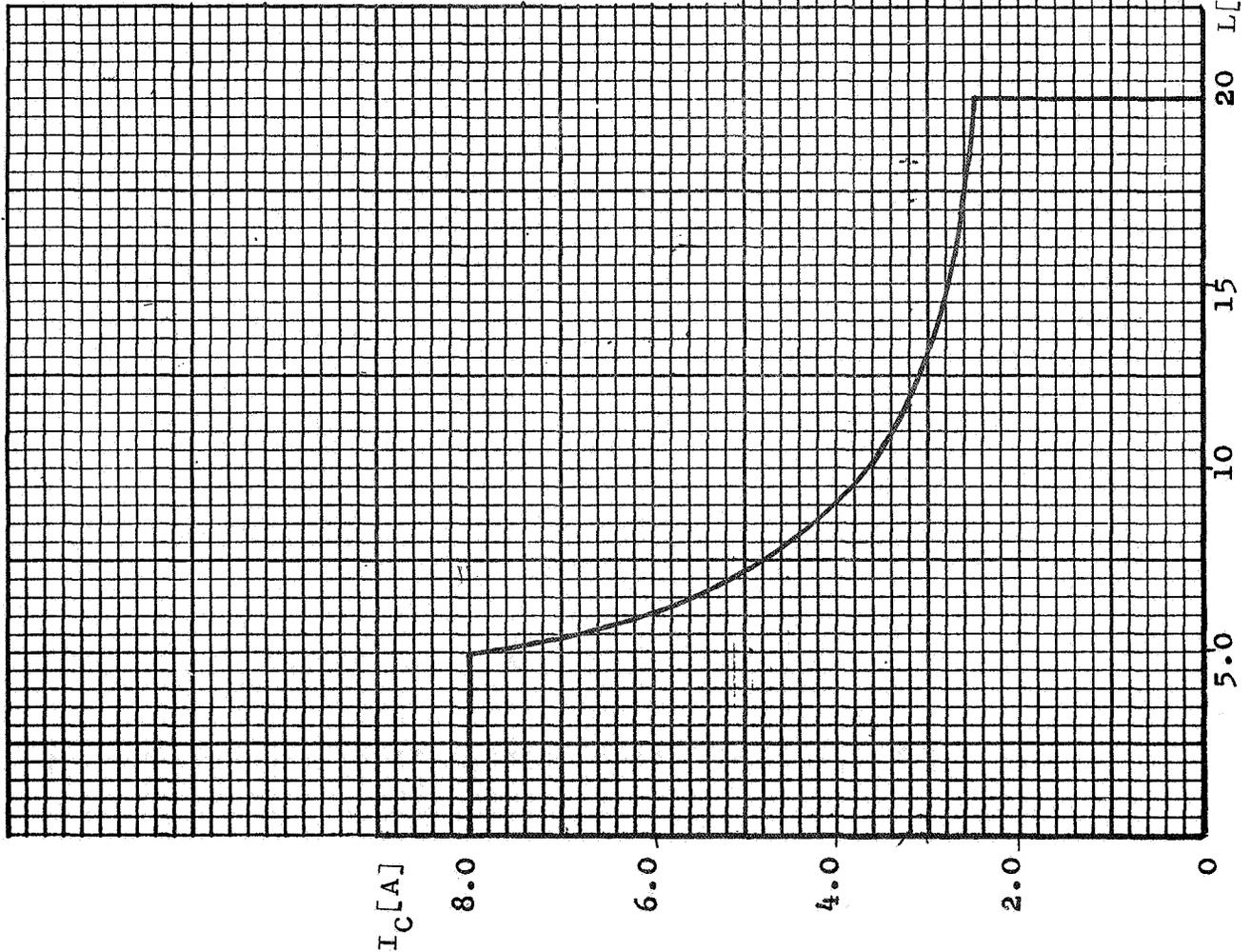


Figure 5

SHORTED CLASS B SOAR

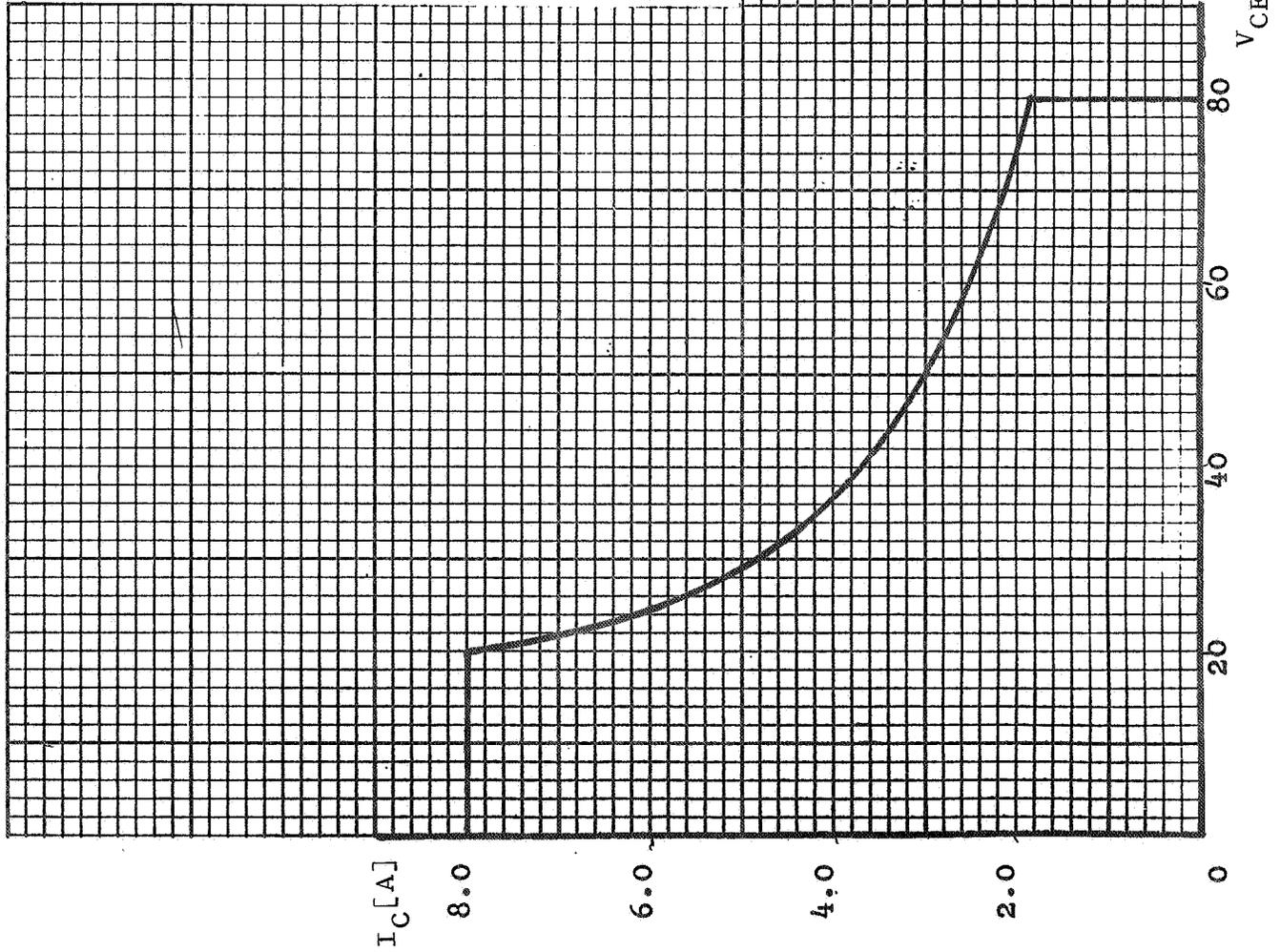
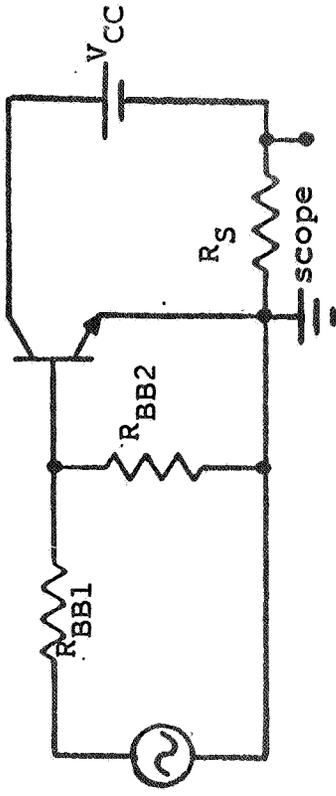


Figure 6

SILICON POWER TRANSISTOR

< Type 2N1016D >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer C --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

ItemTest Methods and Test Conditions1.0.0 General Description

1.1.0 Type -- NPN

1.2.0 Material -- Silicon

2.0.0 Mechanical Data

2.1.0 Outline -- TO-82

2.2.0 Terminal Designation

1 -- Base

2 -- Emitter

3 -- Collector

Case -- Collector

2.2.1 Maximum Stud Torque -- 50 in lbs.

Minimum Stud Torque -- 40 in lbs.

3.0.0 Maximum Ratings

3.1.0 Temperature

3.1.1  $T_{STG(max)} = +150^{\circ}C$  JS-6-T1.1 (JEDEC Suggested Standard:  
"Test Procedures for Veri-  
fications of Maximum Ratings") $T_{STG(min)} = -65^{\circ}C$  JS-6-T1.23.1.2  $T_J = 150^{\circ}C$  JS-6-T2 $T_C = 100^{\circ}C$ ,  $V_{CB} = 100V$ ,  $I_C = 0.71A$ 3.1.3  $T(Lead) = 230^{\circ}C$ 

Distance from case = 1/4 in., Time = 10s

3.2.0 Voltage

3.2.1  $V_{CBO} = 200V$  JS-6-T3 or MIL-STD-750A  
Method 3001.13.2.2  $V_{EBO} = 25V$  JS-6-T4 or MIL-STD-750A  
Method 3026.13.2.3  $V_{CEX} = 200V$  JS-6-T5-2.1 $I_C (V_{CE} = V_{CEX}) = 7.5A$ ,  $V_{CC} = 200V$  $R_L = 26.6\Omega$ ,  $L = 1mH^*$ , CR - 1N1204.\*Miller No. 7871 in series with  
Miller No. 7825-3

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.3 continued .....	$V_{BB1} = 12.5V, R_{BB1} = 3\Omega, V_{BB2} = 3V,$ $R_{BB2} = 3\Omega$ Duty Cycle = 1%, $t_p = 1 \text{ ms}, R_s = 0.1\Omega$
3.3.0 Current	
3.3.1 $I_C = 7.5A$	<u>JS-6-T6</u> $I_B = 1.5A, T_C = 25^\circ C$
3.3.2 $I_B = 5A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3 $I_E = 9.0A$	<u>JS-6-T10</u> $I_B = 1.5A, T_C = 25^\circ C$
3.4.0 Power	
3.4.1 $P_T = 71.4W$	<u>JS-6-T12</u> $T_C = 100^\circ C, V_{CB} = 200V, I_C = 0.355A$ Derating factor = $1.43 \text{ W}/^\circ C$
3.4.2 $P_{TM} = I_C V_{CC} = 1125W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 150V, V_{BB} = 3V$ $R_{BB} = 3\Omega, I_C = 7.5A, \text{Pulse Width } 1\text{ms}$ Duty Cycle = 1%, $t_r \leq 50\mu s, t_f \leq 50\mu s$ of Collector Current
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> (See Figure 1) Test Point: (See 3.4.1)
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14</u> (See Figure 2) <u>Test Points:</u> $T_C = 100^\circ C, V_{BB} = 3V, R_{BB} = 3\Omega, \text{Coll. Cu}$ $t_r \leq 50\mu s, t_f \leq 50\mu s, I_C = 7.5A$ Duty Cycle $\leq 1\%, R_s = 0.1\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.2	Continued .....
	1. For $t_p = 20\text{ms}$ : $V_{CC} = 90\text{V}$
	2. For $t_p = 10\text{ms}$ : $V_{CC} = 110\text{V}$
	3. For $t_p = 5\text{ms}$ : $V_{CC} = 125\text{V}$
	4. For $t_p = 1\text{ms}$ : $V_{CC} = 150\text{V}$
3.6.0	SOAR Switching between Saturation and Cutoff
3.6.1	Resistive Load
	<u>JS-6-T5.1</u> with $L = 0$ and CR disconnected (See Figure 3)
	<u>Test Points:</u>
	$R_{BB1} = 3\Omega$ , $R_{BB2} = 3\Omega$ , $V_{BB1} = 12.5\text{V}$
	$V_{BB2} = 3\text{V}$ , $T_C = 100^\circ\text{C}$ , $t_f \leq 50\text{us}$ Coll.
	Current, $t_r \leq 50\text{us}$ Coll. Current,
	$R_S = 0.1\Omega$ , $I_C = 7.5\text{A}$ , $V_{CC} = 200\text{V}$
3.6.2	Clamped Inductive Load
	<u>JS-6-T5.1</u> (See Figure 4)
	<u>Test Points:</u> (See 3.2.3)
3.6.3	Unclamped Inductive Load
	<u>JS-6-T5-2.1</u> and CR disconnected (See Figure 5)
	<u>Test Points:</u>
	1. $V_{BB1} = 12.5\text{V}$ $L = 1.4\text{mH}^*$
	$R_{BB1} = 3\Omega$ $R_L = 3\Omega$
	$V_{BB2} = 3\text{V}$ $V_{CC} = 25\text{V}$
	$R_{BB2} = 3\Omega$ $f = 60\text{Hz}$
	$R_S = 0.1\Omega$ $d = 10\%$
	2. $V_{BB1} = 3.0\text{V}$ $L = 10\text{mH}^{**}$
	$R_{BB1} = 10\Omega$ $R_L = 7.5\Omega$
	$V_{BB2} = 1.5\text{V}$ $V_{CC} = 25.0\text{V}$
	$R_{BB2} = 30\Omega$ $f = 60\text{Hz}$
	$R_S = 0.1\Omega$ $d = 30\%$

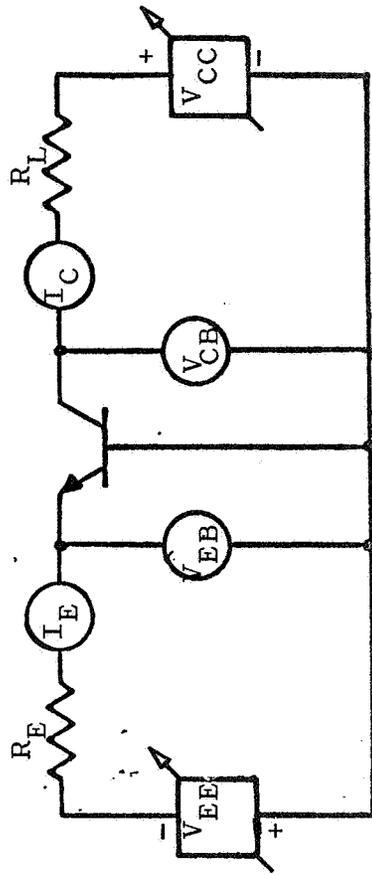
\*Miller #7871 in series with Miller #7825-3    \*\*Series Stancor C-2688

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.7.0 Shorted Class B SOAR	(See Figure 6)  <u>Test Points:</u>  $I_C \text{ peak} = 1.1A, V_{CC} = 200V, R_S = 0.1\Omega$ $R_{BB_1} = 5\Omega, R_{BB_2} = 10\Omega, f = 20Hz,$ $T_C = 100^\circ C$
4.0.0 <u>Electrical</u> <u>Characteristics</u>	$T_C = 25^\circ C$ (unless otherwise noted)
Maximum limits unless otherwise noted	
Technique:	
DC - Continuous Operation	
C.T. - Curve Tracer	
P - 300 $\mu$ s Pluse, 2% Duty Cycle	
4.1.0 Static	
4.1.1 $I_{CEX} = 20mA$	$V_{CEX} = 200V, V_{BE} = -1.5V,$ Technique - C.T., $T_C = 150^\circ C$
$I_{CES} = 100\mu A$	$V_{CE} = 240V$ Technique - C.T.
4.1.2 $I_{CEO} = 10mA$	$V_{CEO} = 200V,$ Technique - C.T.
4.1.3 $I_{EBO} = 20mA$	$V_{EBO} = 25V,$ Technique - C.T. $T_C = 150^\circ C$
4.1.4 $V_{CEO} = 200V \text{ min}$	<u>JS-6-T5-2.1</u> and CR disconnected $I_C = 1A, R_{BB_1} = 3\Omega, V_{BB_1} = 3V,$ $R_{BB_2} = \infty\Omega, d = 50\%, f = 60Hz$ $L = 10mH, R_L = 0.1\Omega, R_S = 0.1\Omega$ Adjust $V_{CC}$ for specified $I_C$ .

ItemTest Methods and Test Conditions

4.1.5	$h_{FE} = 10 \text{ min}$	$V_{CE} = 4V, I_C = 5A, \text{Technique - C.T.}$
	$h_{FE} = 7.5 \text{ min}$	$V_{CE} = 4V, I_C = 7.5A \text{ Technique - C.T.}$
4.1.6	$V_{CE(sat)} = 2.5V$	$I_C = 5A, I_B = .75A, \text{Technique - C.T.}$
4.2.0	Dynamic	
4.2.1	$f_{hfe} = 10KHz \text{ min,}$ $40KHz \text{ max}$	$I_C = 1A, V_{CE} = 5V$
5.0.0	Thermal Characteristics	
5.1.0	$T_J \text{ min} = 70ms$	$I_C = 2A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD-750 Method 3146.1
5.2.0	$\theta_{JC} = 0.7 \text{ }^\circ C/W$	$I_C = 2A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD-750 Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ;  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

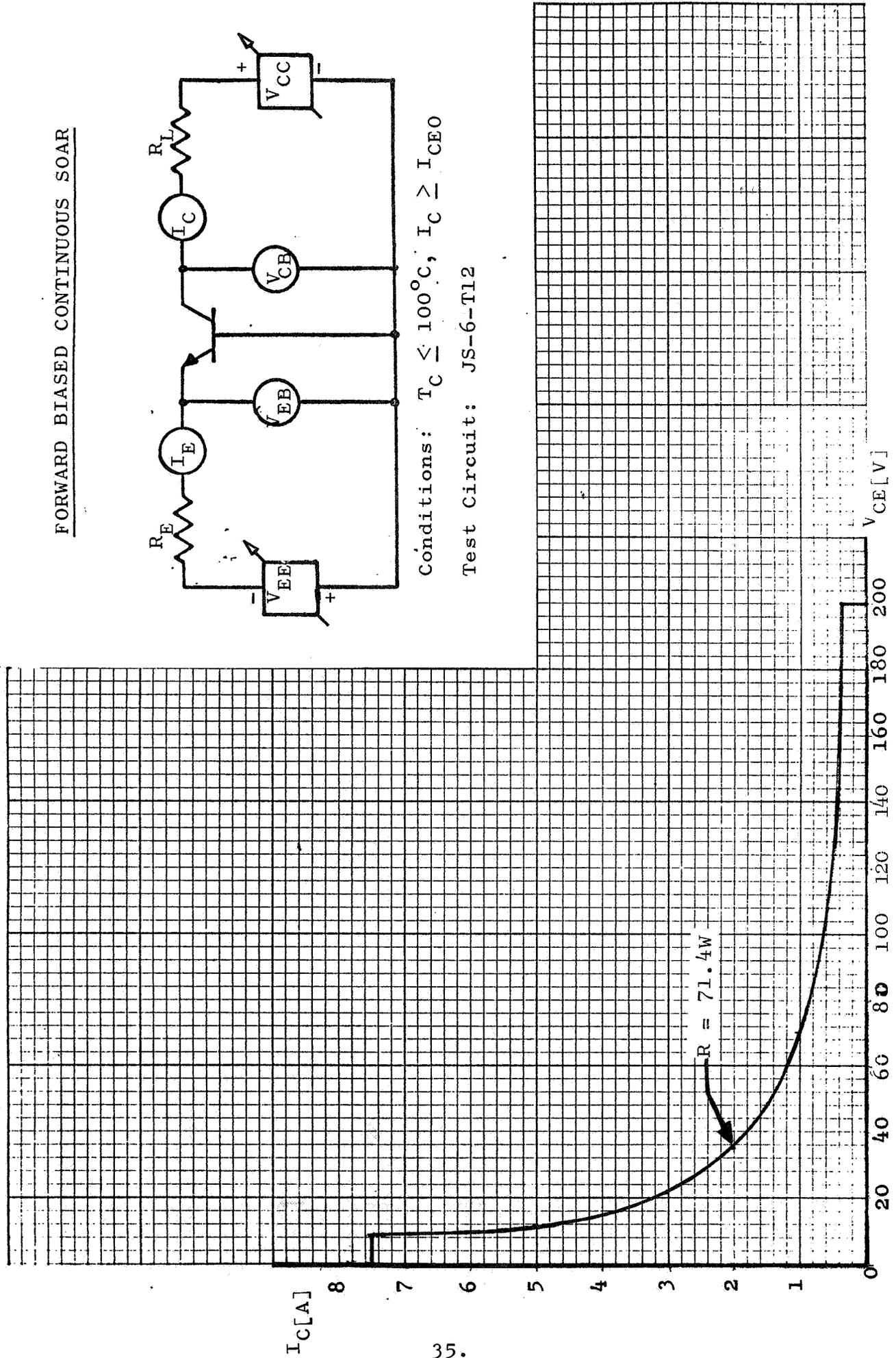
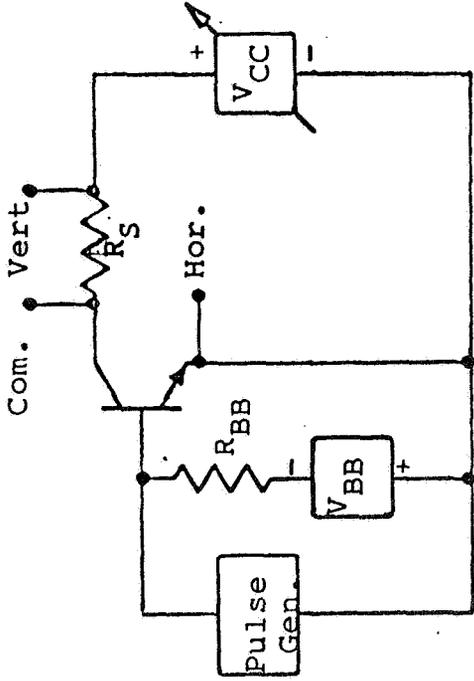


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

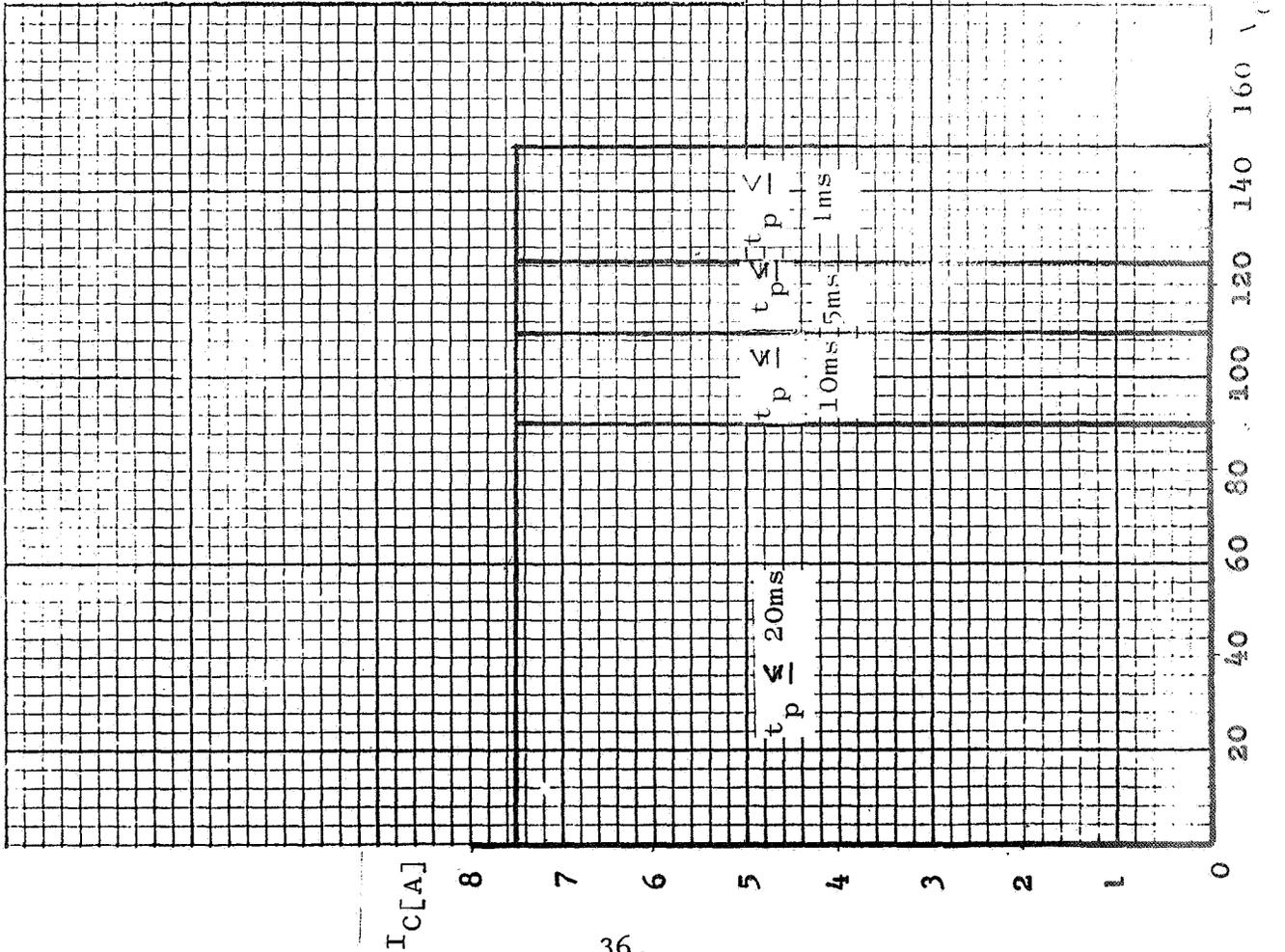
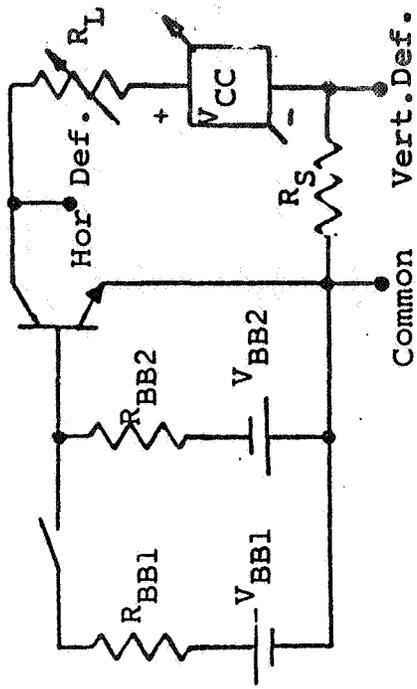


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

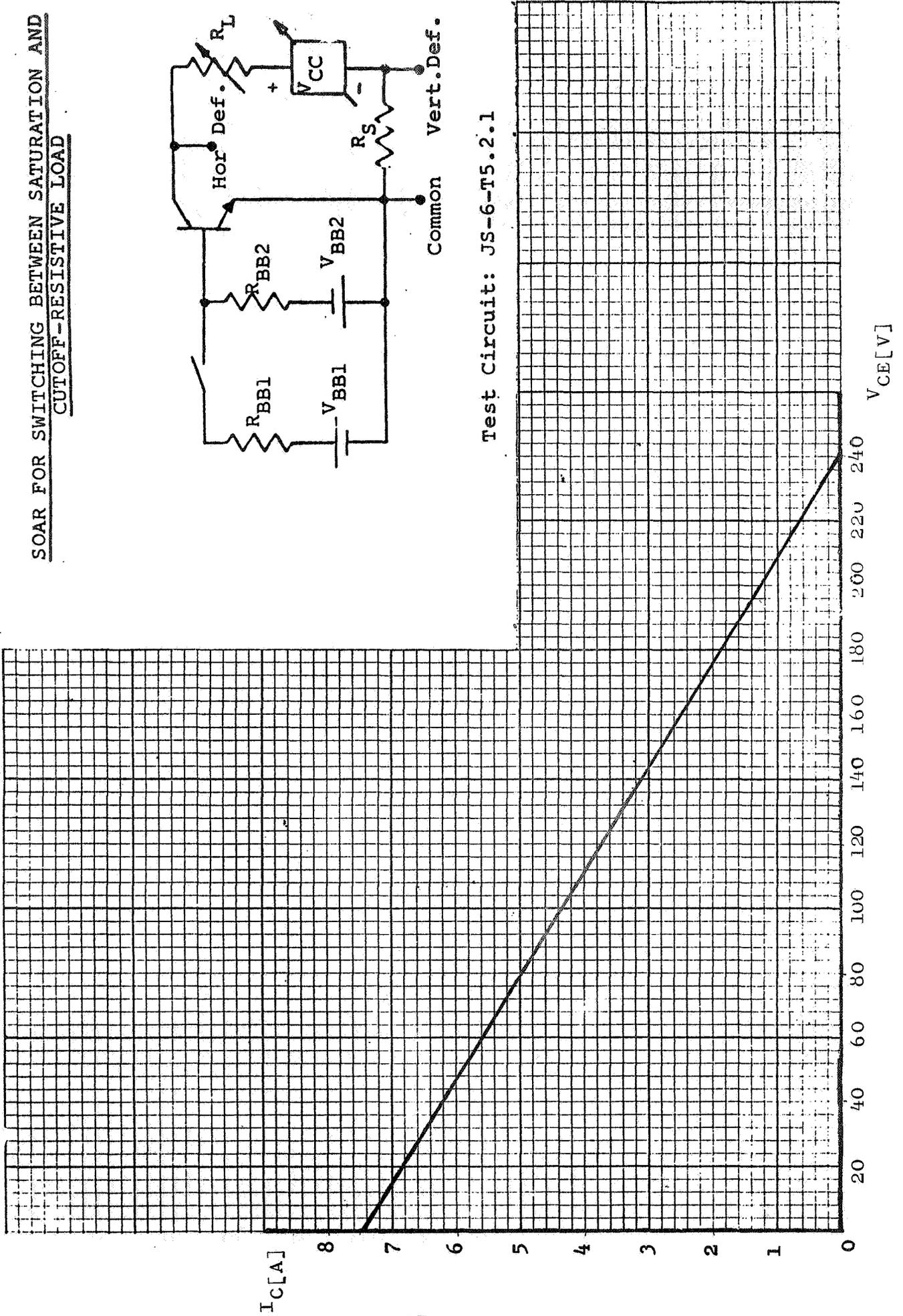
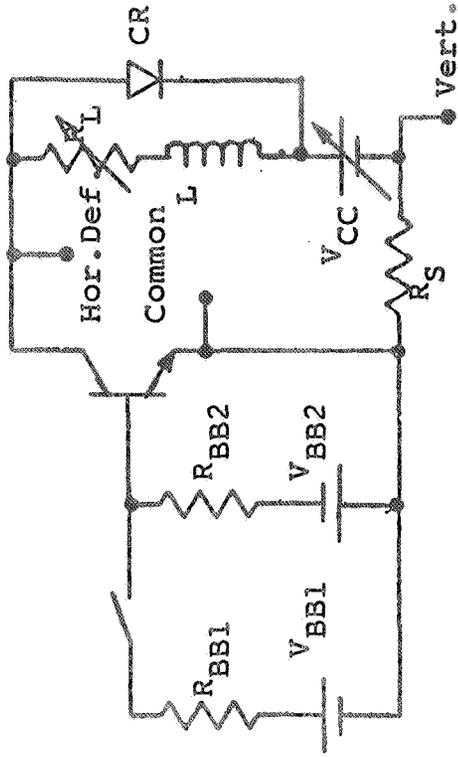


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

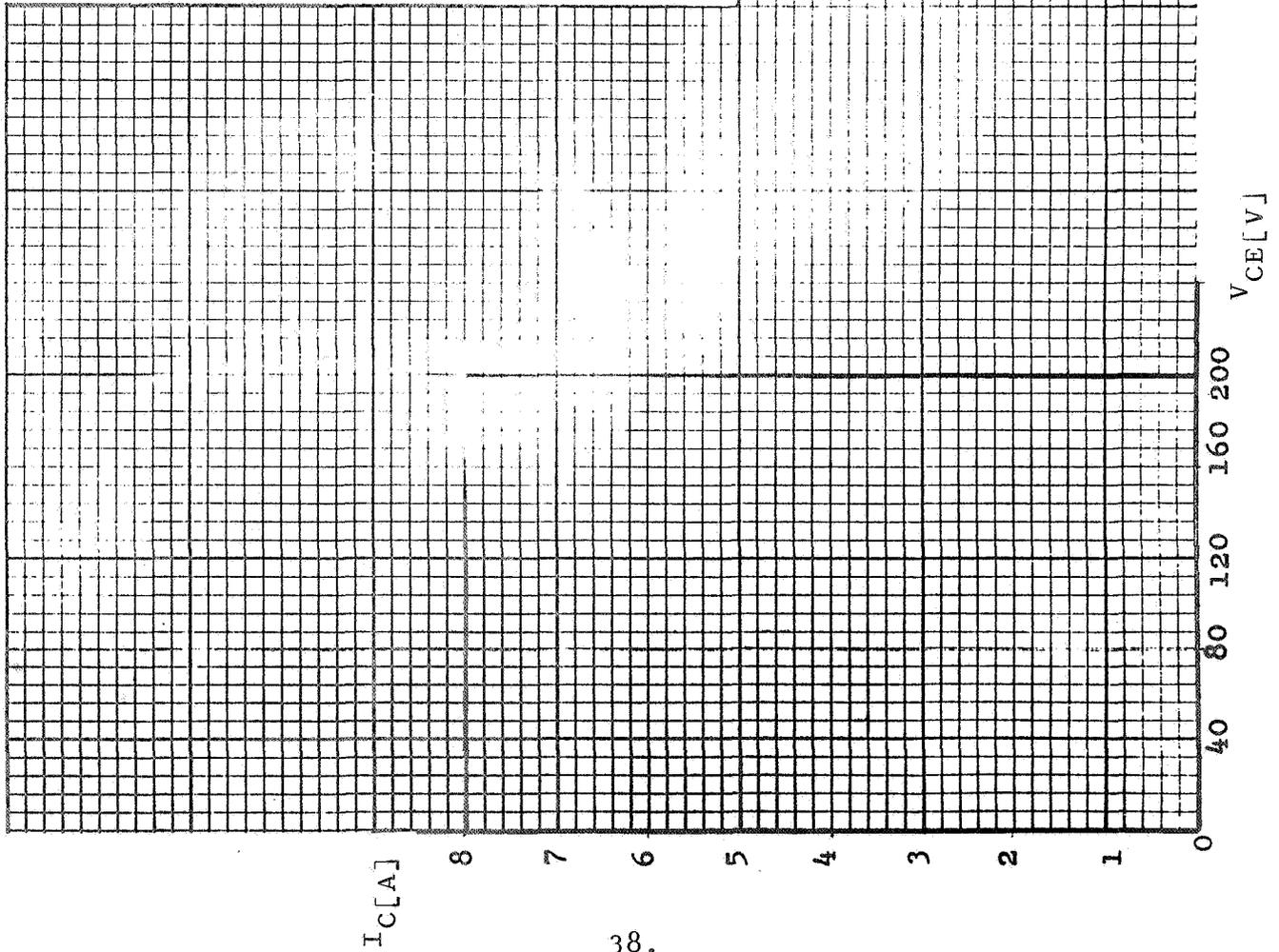
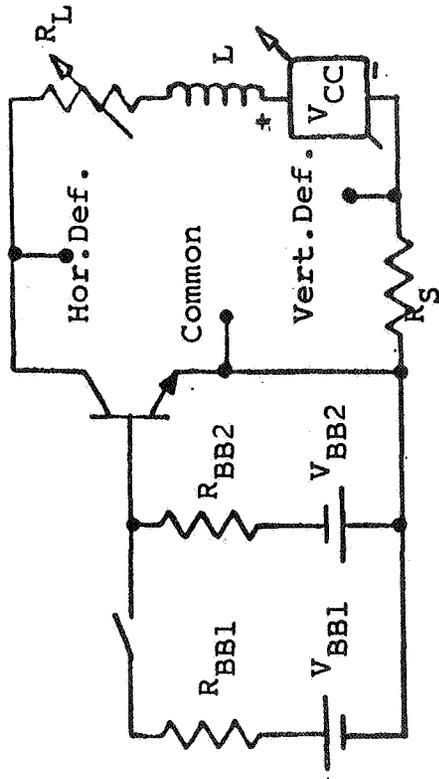


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

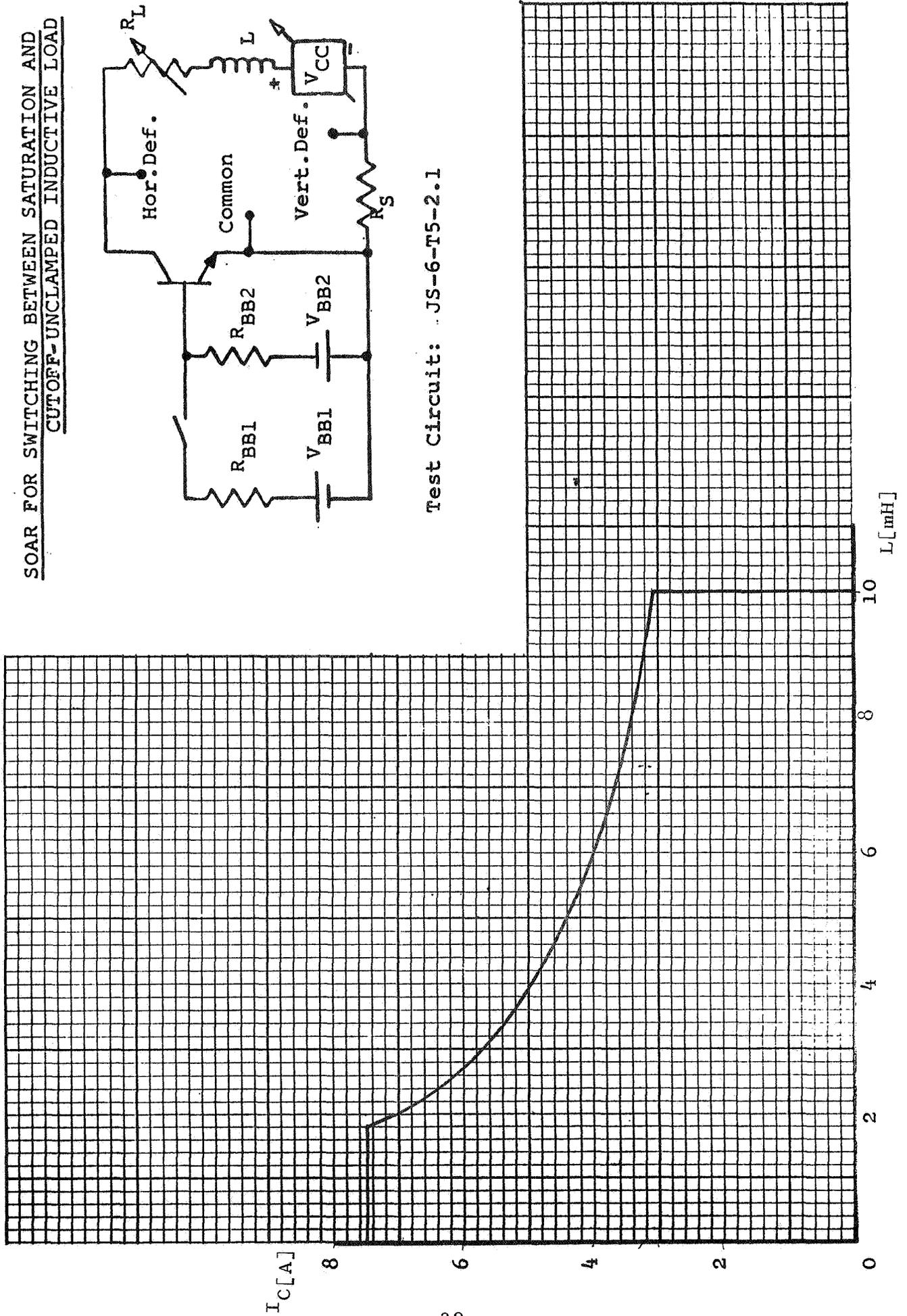


Figure 5

SHORTED CLASS B SOAR

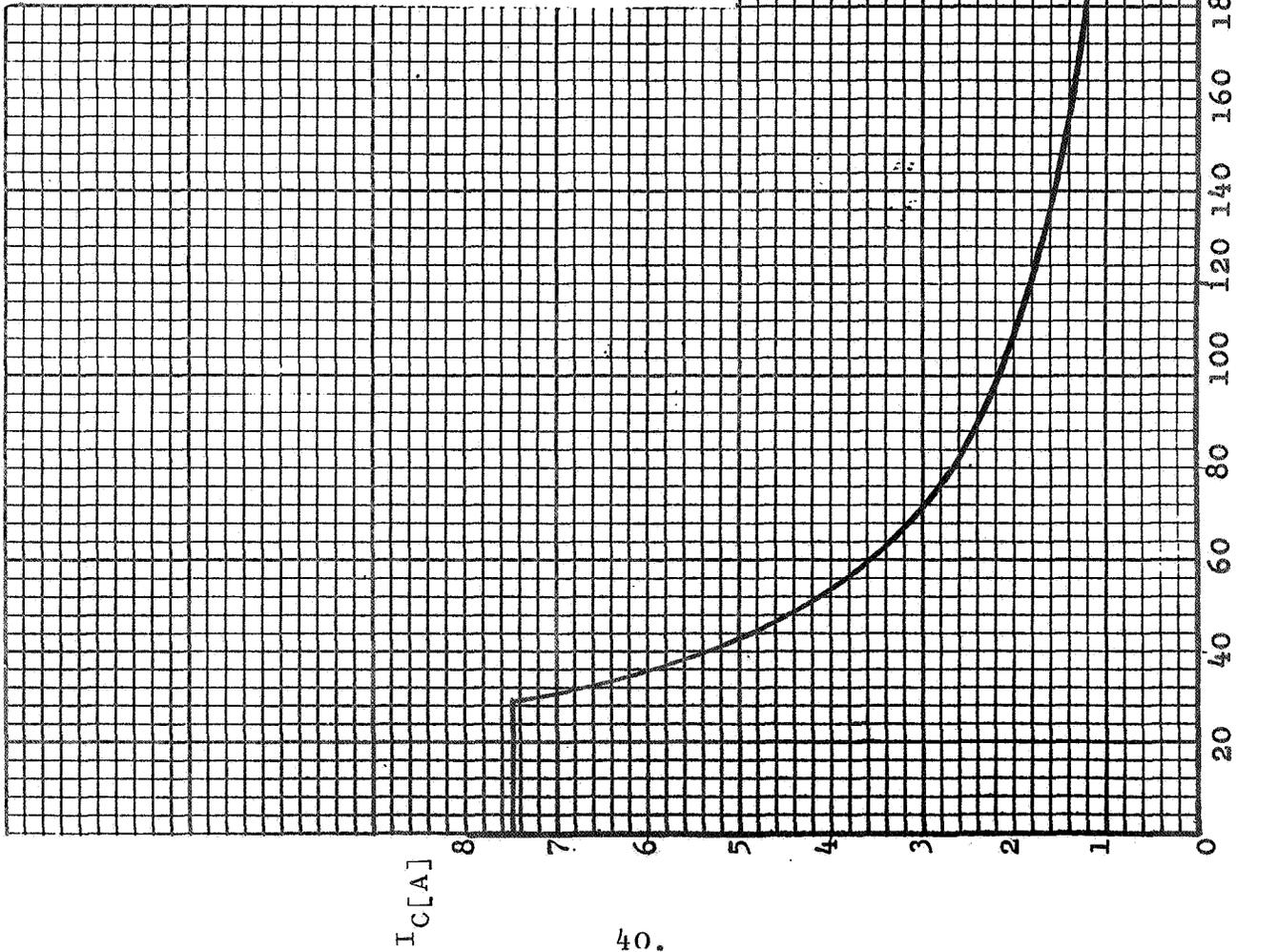
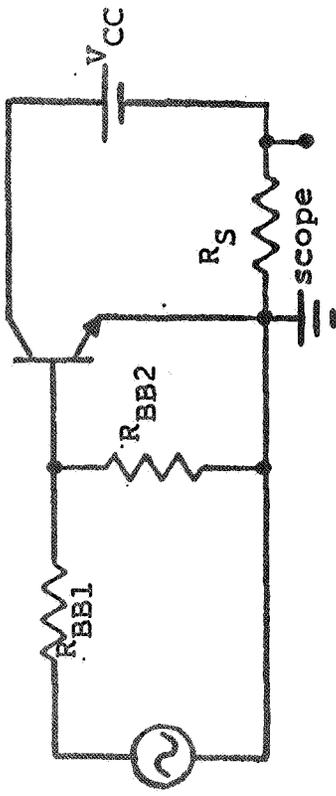


Figure 6

Silicon Power Transistor  
< Type 2N1514 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer H --

Performed for  
NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract No. NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type NPN	
1.2.0	Material -- Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline -- TO-36	
2.2.0	<u>Terminal Designation</u>	
	1 -- Base	
	2 -- Emitter	
	3 -- Collector	
	case -- Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = +200^{\circ}C$	<u>JS-6-T1.1</u> (JEDEC suggested Standard: "Test Procedures for Verification of Maximum Ratings.")
	$T_{STG(min)} = -65^{\circ}C$	<u>JS-6-T1.2</u>
3.1.2	$T_J(max) = 200^{\circ}C$	<u>JS-6-T2</u>
		$T_C = 100^{\circ}C$
		$V_{CB} = 10V, I_C = 4.3A$
3.1.3	$T(Lead) = 230^{\circ}C$	Distance from case - 0.25 in
		Time - 10s
3.2.0	Voltage	$T_C = 25^{\circ}C$
3.2.1	$V_{CBO} = 100V$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.2.2	$V_{EBO} = 10V$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1
3.2.3	$V_{CEX} = 70V$	<u>JS-6-T5.1</u> $I_C (V_{CE} = V_{CEX}) = 6A$ $V_{CC} = 100V, R_L = 16.0\Omega$ $L = 1mH^*, CR - 1N1204$ $V_{BB1} = 7.5V, R_{BB1} = 1\Omega$ $V_{BB2} = 8V, R_{BB2} = 5\Omega$ $R_S = 0.1\Omega$ $t_p = 1ms, \text{Duty Cycle} \leq 1\%$ *Miller No. 7871 in series with Miller No. 7825-3
3.3.0	Current	
3.3.1	$I_C = 6A$	<u>JS-6-T6</u> $I_B = 2A, T_C = 25^\circ C$
3.3.2	$I_B = 3A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3	$I_E = 8A$	<u>JS-6-T10</u> $I_B = 2A, T_C = 25^\circ C$
3.4.0	Power	
3.4.1	$P_T = 43W$	<u>JS-6-T12</u> $T_C = 100^\circ C$ $V_{CB} = 10V, I_C = 4.3A$ Derating factor - $0.43W/^\circ C$

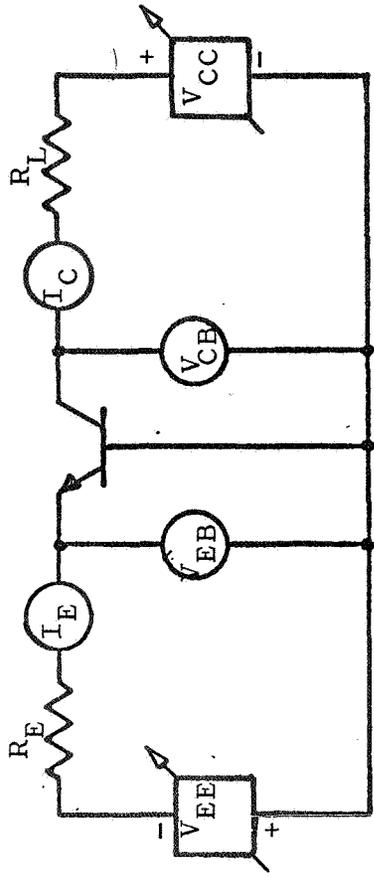
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.4.2	$P_{TM} = I_C V_{CC} = 330W$ <u>JS-6-T13</u> $T_C = 100^{\circ}C$ $V_{CC} = 55V, I_C = 6A$ $V_{BB} = 8V, R_{BB} = 5\Omega$ <u>Input Pulse Characteristics</u> Pulse Width = 10 ms Duty Cycle $\leq 1\%$ $t_r \leq 50\mu s, t_f \leq 50\mu s$ Coll. Current
3.5.0	Maximum Operating Conditions
3.5.1	Forward Biased Continuous DC-SOAR <u>JS-6-T12</u> (See Figure 1) Test Point: (See 3.4.1)
3.5.2	Pulsed Forward Biased SOAR <u>JS-6-T14</u> (See Figure 2) <u>Test Points:</u> $T_C = 100^{\circ}C, V_{BB} = 8V; R_{BB} = 5\Omega$ $t_r \leq 50\mu s, t_f \leq 50\mu s, I_C = 6A$ Duty Cycle $\leq 1\%, R_S = 0.1\Omega$ 1. For $t_p = 20ms; V_{CC} = 30V$ 2. For $t_p = 10ms; V_{CC} = 55V$
3.6.0	SOAR  Switching between Saturation and Cutoff
3.6.1	Resistive Load  <u>JS-6-T5-2.1</u> with L = 0 and CR disconnected (See Figure 3)

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.1	Resistive Load (Cont'd)  <u>Test Point:</u> $I_C = 6A, V_{CC} = 100V, R_{BB1} = 1\Omega,$ $R_{BB2} = 5\Omega, R_S = 0.1\Omega, V_{BB1} = 7.5V,$ $V_{BB2} = 8V, T_C = 100^\circ C, (\text{Coll. Current})$ $t_r \leq 50\mu s, t_f \leq 50\mu s$
3.6.2	Clamped Inductive Load <u>JS-6-T5-2.1</u> (See Figure 4) <u>Test Point:</u> (See 3.2.3)
3.6.3	Uclamped Inductive Load <u>JS-6-T5-2.1</u> and CR disconnected (See Figure 5)  <u>Test Points:</u> $R_{BB1} = 1\Omega, R_{BB2} = 5\Omega, R_S = 0.1\Omega,$ $V_{BB1} = 7.5V, V_{BB2} = 8V, T_C = 25^\circ C,$ $f = 60\text{Hz}, d = 10\%$ 1. $I_C = 6A, V_{CC} = 18V, R_L = 2\Omega, L=10\text{mH}^*$ 2. $I_C = 2.5A, V_{CC} = 28V, R_L = 10\Omega, L=40\text{mH}$ *Stancor - C-2688 **Series Stancor-C-2688
3.7.0	Shorted Class B SOAR (See Figure 6) <u>Test Point:</u> $I_C \text{ peak} = 2.6A, V_{CC} = 55V, R_S = 0.1\Omega,$ $R_{BB1} = 1\Omega, R_{BB2} = 3\Omega, f = 20\text{Hz},$ $T_C = 100^\circ C$

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.0.0	Electrical Characteristics	$T_C = 25^{\circ}\text{C}$ [unless otherwise noted]
	Maximum limits unless otherwise noted	
	Technique:	
	DC - Continuous Operation	
	C.T. - Curve Tracer	
	P - 300 $\mu\text{s}$ Pulse, 2% Duty Cycle	
4.1.0	Static	
4.1.1	$I_{CEO} = 100\text{mA}$	$V_{CE} = 55\text{V}$ Technique - C.T.
4.1.2	$I_{CBO} = 2\text{mA}$	$V_{CB} = 30\text{V}$ , $T_C = 200^{\circ}\text{C}$ Technique - C.T.
4.1.3	$V_{EBF} = 1.5\text{V}$	$V_{CB} = 30\text{V}$ , $T_C = 200^{\circ}\text{C}$ Technique - C.T.
4.1.4	$I_{EBO} = 25\mu\text{A}$	$V_{EB} = 10\text{V}$ , Technique - C.T.
4.1.5	$V_{(BR)CEO} = 55 \text{ minV}$	$I_C = 100\text{mA}$ Technique - C.T.
4.1.6	$h_{FE} = 25 \text{ min}$ " = 75 max	$V_{CE} = 4\text{V}$ , $I_C = 1.5\text{A}$ Technique - C.T.
4.1.7	$h_{FE} = 7 \text{ min}$	$V_{CE} = 8\text{V}$ , $I_C = 6\text{A}$ Technique - P
4.1.8	$V_{CE(sat)} = 6 \text{ max V}$	$I_C = 6\text{A}$ , $I_B = 2\text{A}$ Technique - C.T.
4.1.9	$V_{BE} = 7.8 \text{ max V}$	$I_C = 6\text{A}$ , $V_{CE} = 8\text{V}$ Technique - P

<u>Item</u>		<u>Test Methods and Test Conditions</u>
5.0.0	Thermal Characteristics	
5.1.0	$T_{J \text{ min}} = 5\text{ms}$	$I_C = 2\text{A}, V_{CE} = 10\text{V}, T_C = 25^\circ\text{C}$ MIL-STD-750 Method 3146.1
5.2.0	$\theta_{JC \text{ max}} = 2.33^\circ\text{C/W}$	$I_C = 2\text{A}, V_{CE} = 10\text{V}, T_C = 25^\circ\text{C}$ MIL-STD-750 Method 3136
6.0.0	$f_{hfe} = 10\text{KHz}(\text{min})$ $40\text{KHz}(\text{max})$	$I_C = 100\text{mA}, V_{CE} = 6\text{C}$ MIL-STD-750 Method

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ C$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

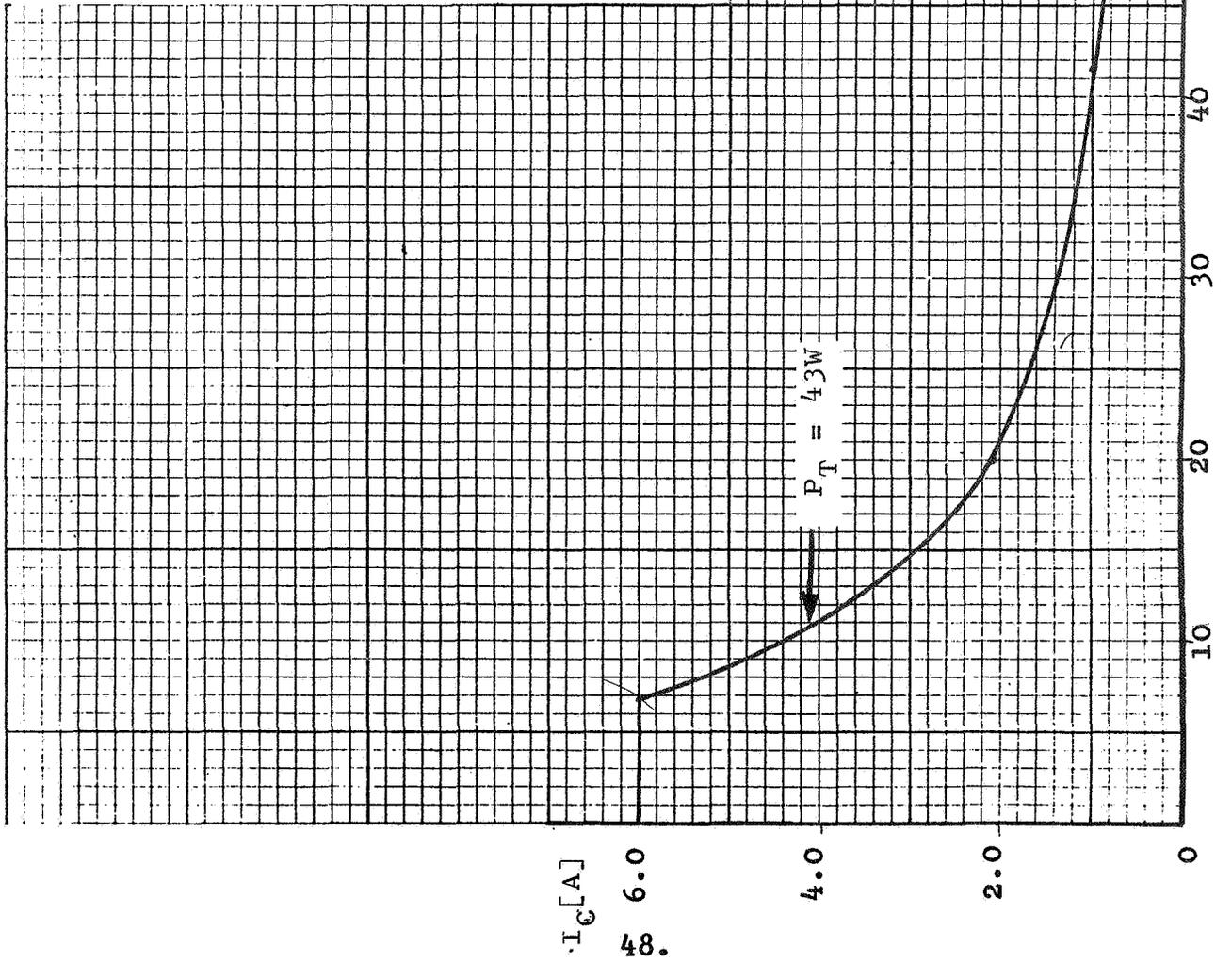
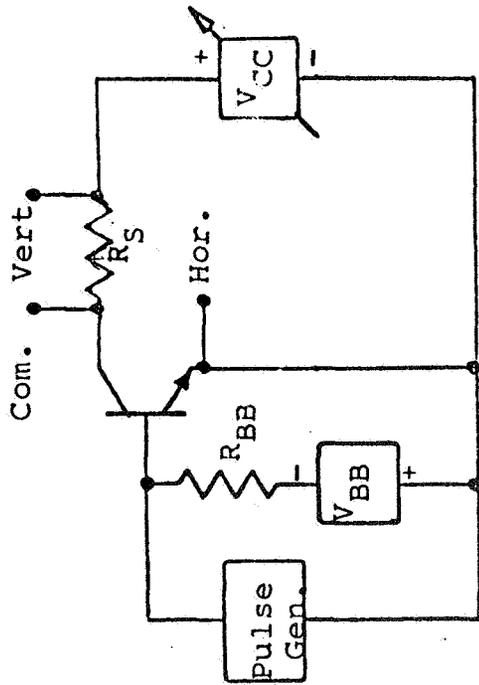


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

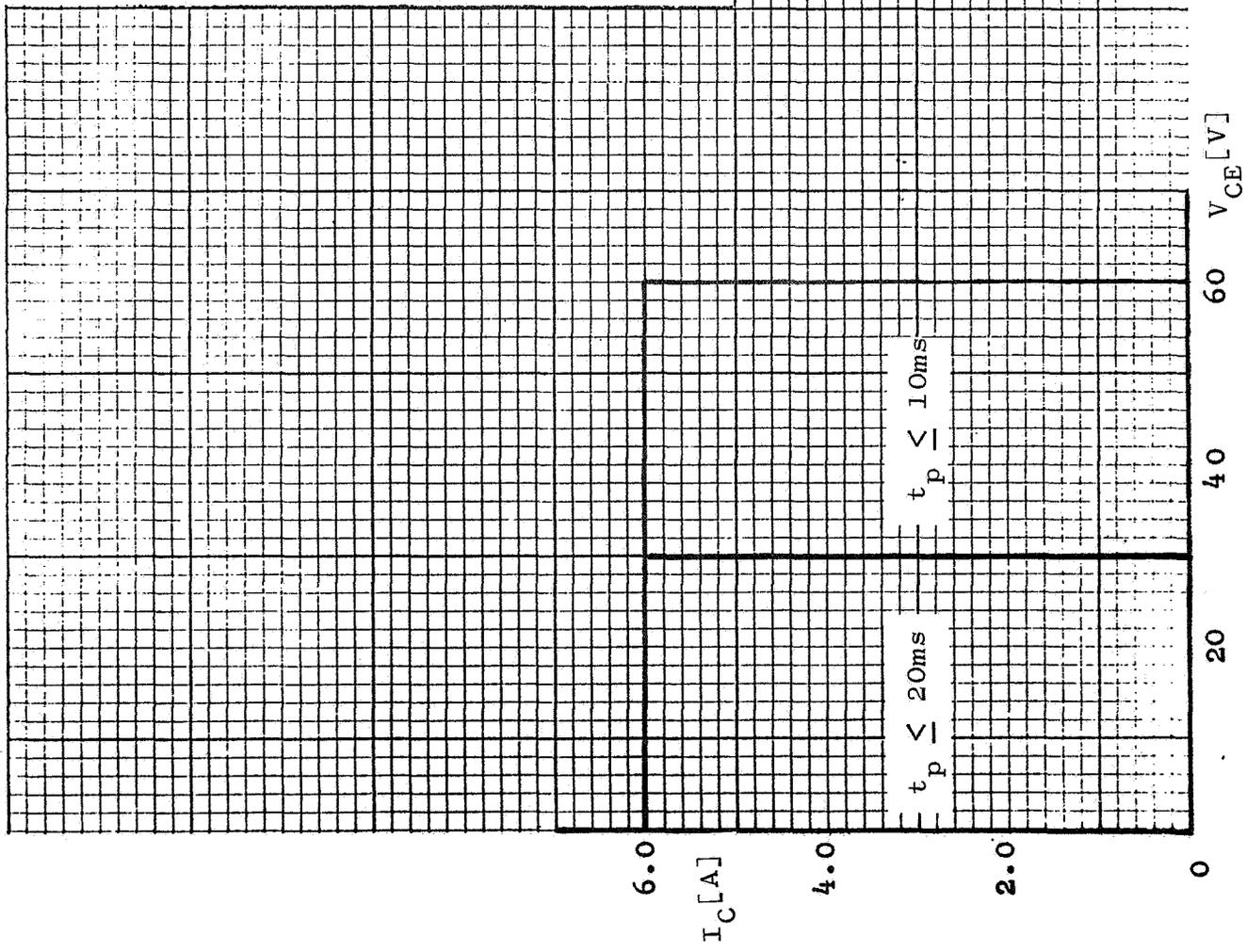
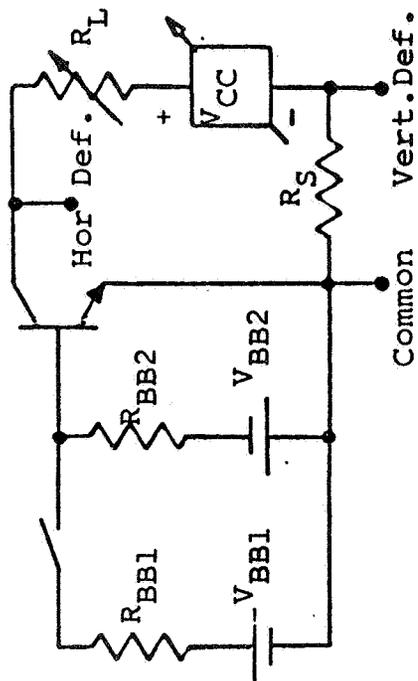


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

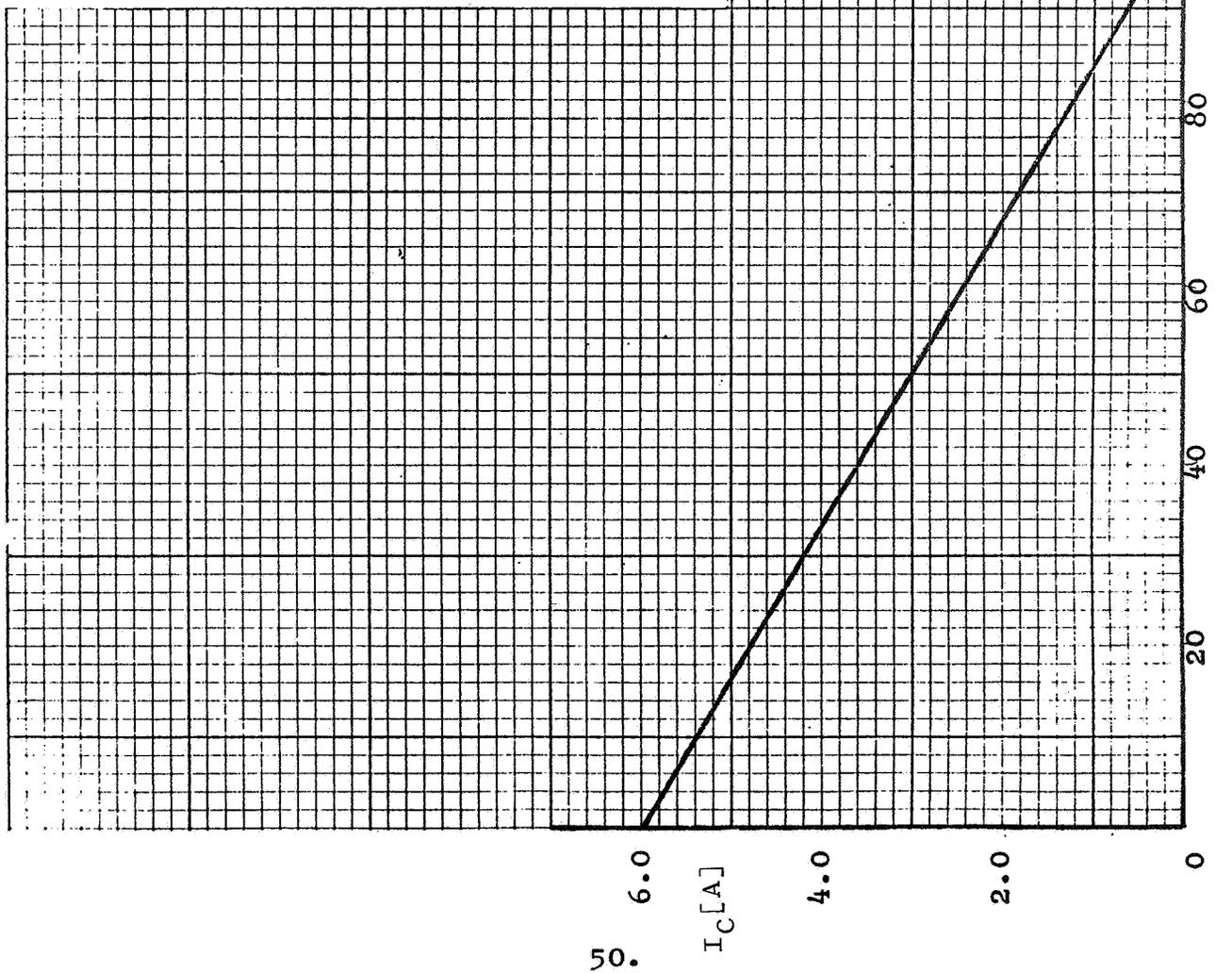
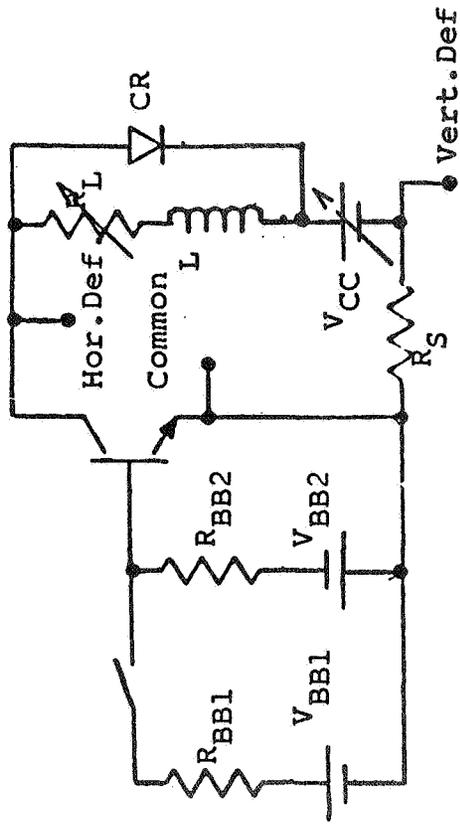


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

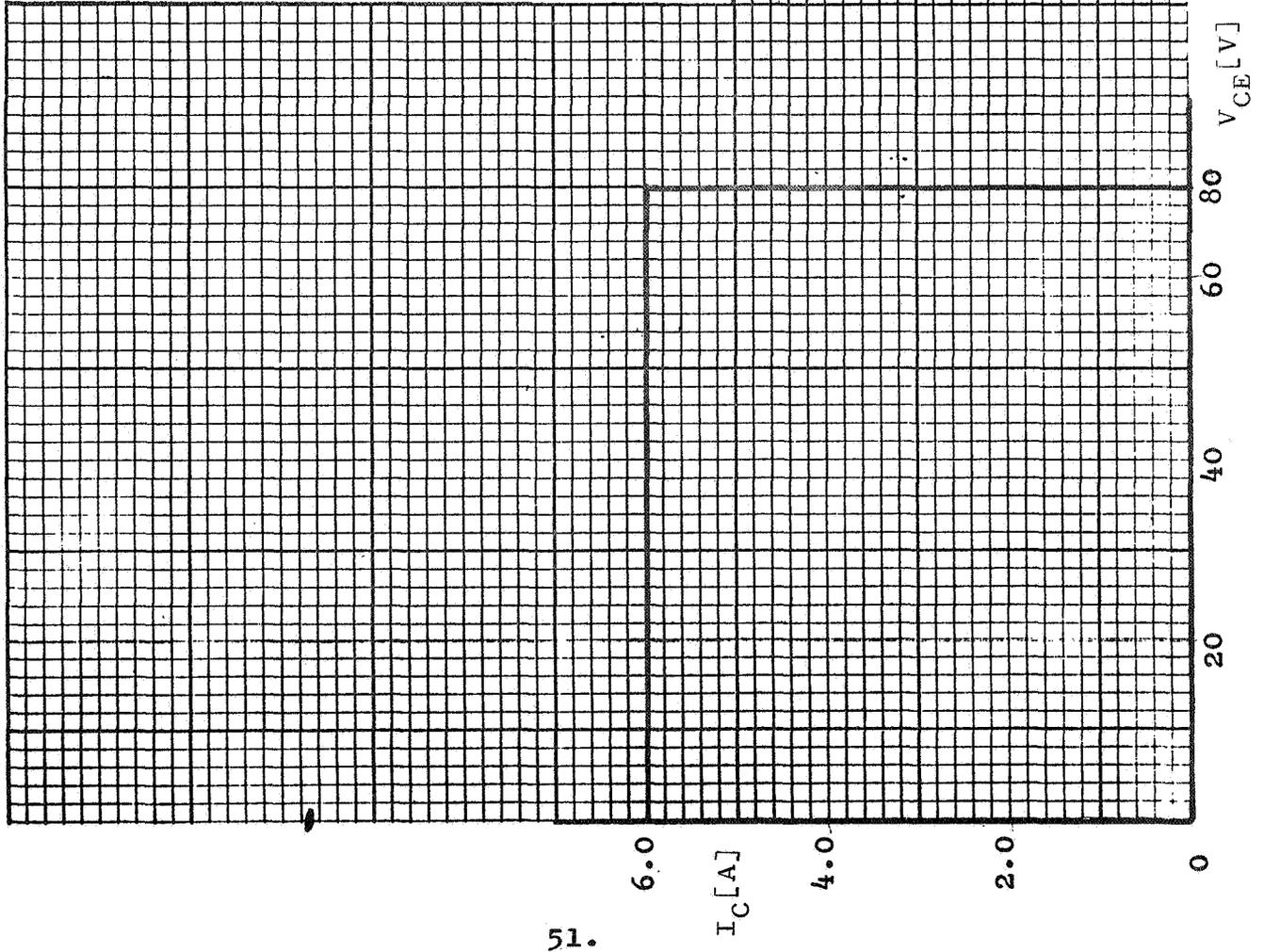
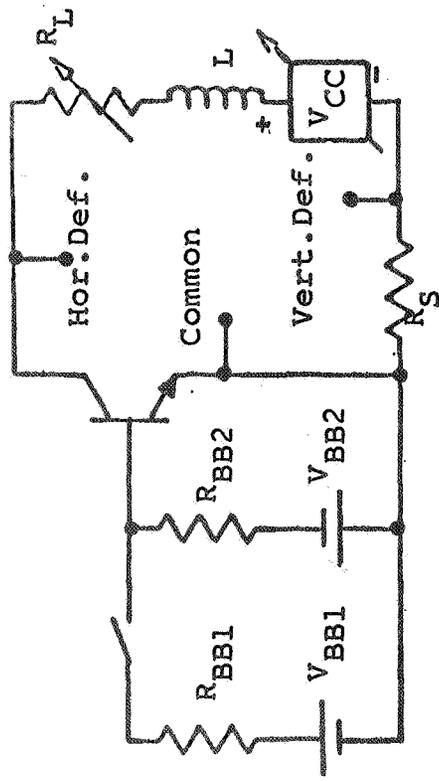


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

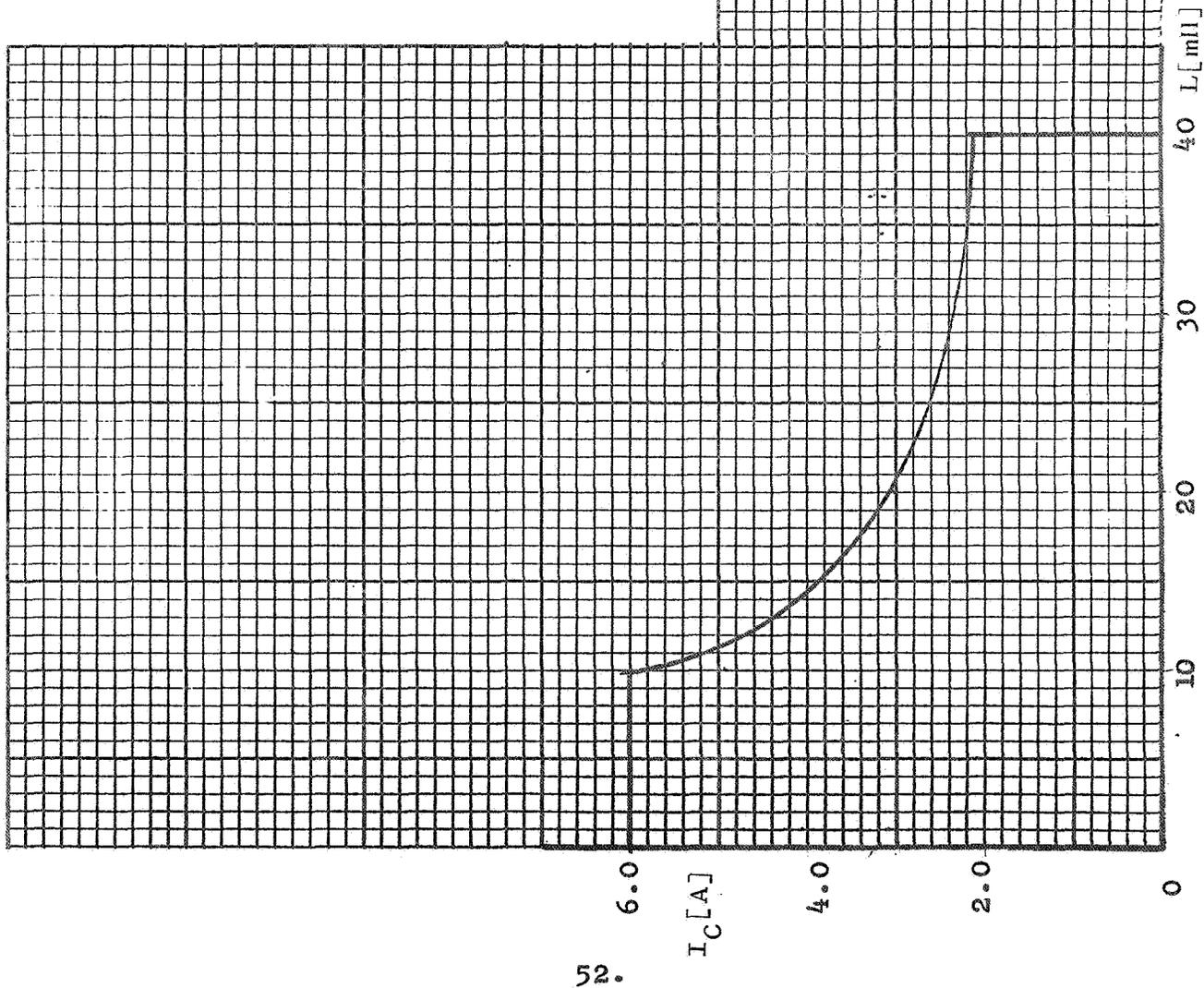


Figure 5

SHORTED CLASS B SOAR

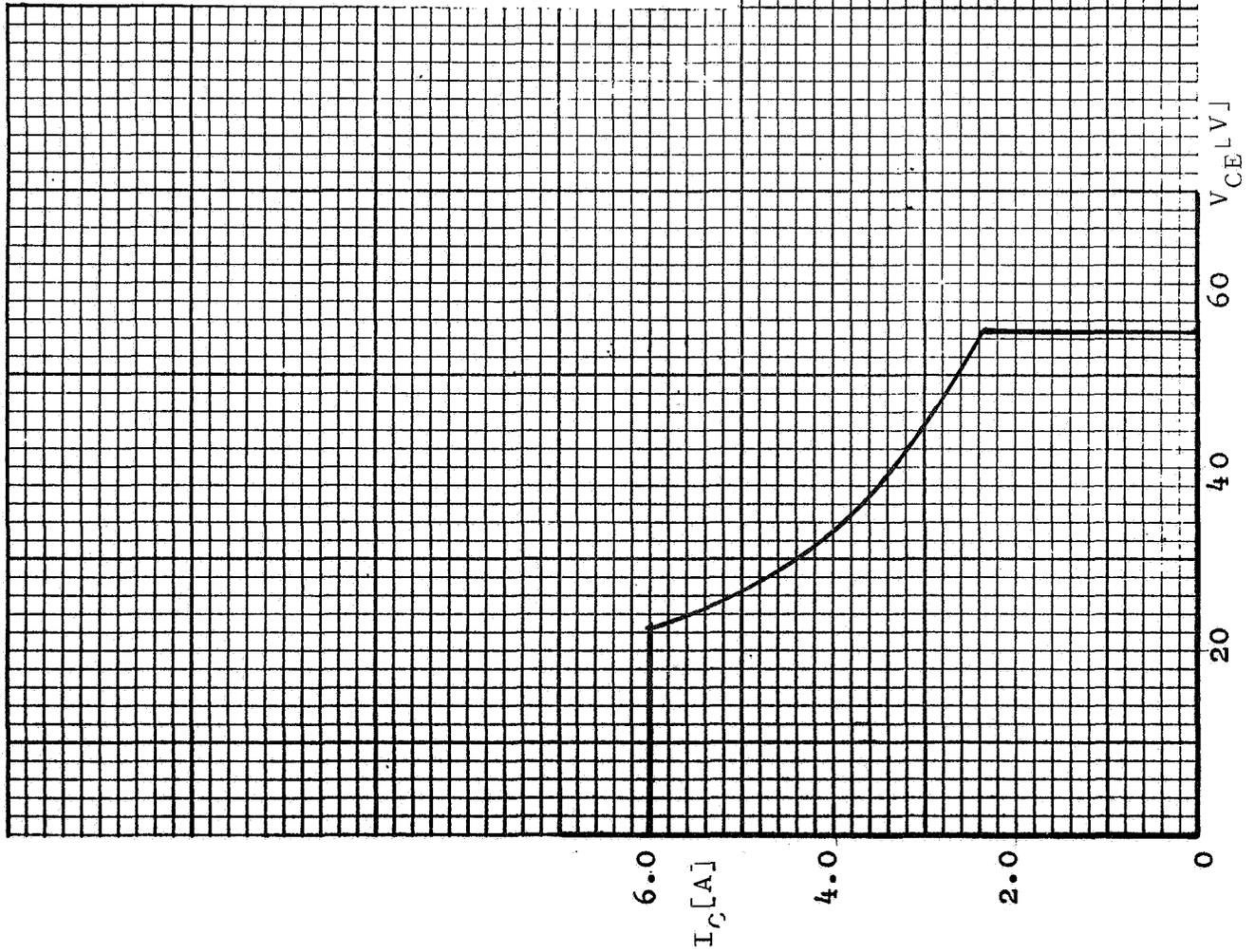
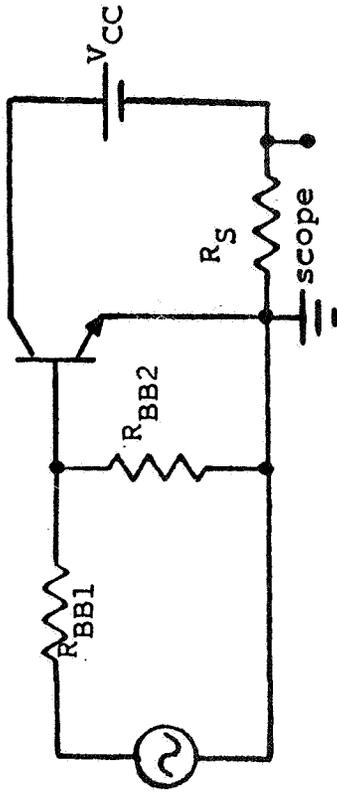


Figure 6

SILICON POWER TRANSISTOR

< Type 2N2102 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturers D & J --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline - TO-5	
2.2.0	Terminal Designation	
	1 - Base	
	2 - Emitter	
	3 - Collector	
	Case - Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(min)} = -65^{\circ}C$	<u>JS-6-T1.1</u> [JEDEC Suggested Standard: "Test Procedure for Verification of Maximum Ratings" JEDEC Publication No. 65]
	$T_{STG(max)} = +200^{\circ}C$	
3.1.2	$T_{J(max)} = 200^{\circ}C$	<u>JS-6-T2</u> $T_C = 100^{\circ}C, P_T = 2.86W, I_C = 55mA$
3.1.3	$T(Lead) = 300^{\circ}C$	Distance from case $1/16" \pm 1/32"$ Time = 10 sec (max)
3.2.0	Voltage	
3.2.1	$V_{(BR)CBO} = 120V$	<u>JS-6-T3</u>
3.2.2	$V_{(BR)EBO} = 7V$	<u>JS-6-T4</u>

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.3 $V_{(BR)CEO} = 65V$	<u>JS-6-T5.1 CR Disconnected</u> $I_C = 0.1A, R_{BB1} = 25\Omega, V_{BB1} = 5V,$ $R_{BB2} = \infty\Omega, d = 50\%, f = 60Hz,$ $L^* = 5.0mH, R_L = 0, R_S = 1.0\Omega$ Adjust $V_{CC}$ for specified $I_C$ *Chicago Standard Transformer Corp. C-2689
3.3.0 Current	
3.3.1 $I_C = 1.0A$	<u>JS-6-T6</u> $I_B = 0.3A, T_C = 25^\circ C$
3.3.2 $I_B = 0.3A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3 $I_E = 1.3A$	<u>JS-6-T10</u> $I_B = 0.3A, T_C = 25^\circ C$
3.4.0 Power	
3.4.1 $P_T = 2.86W$	<u>JS-6-T12</u> <u>Test Point: See 3.1.2</u>
3.4.2 $P_{TM} = I_C V_{CC} = 80W$	<u>JS-6-T13</u> $T_C = 25^\circ C, V_{CC} = 80, V_{BB} = 5V,$ $R_{BB} = 25, I_C = 1.0A, \text{Pulse Width}=100\mu s$ Duty Cycle $\leq 2\%, t_r \leq 5\mu s$ $t_f \leq 5\mu s$
3.5.0 Maximum Operating Conditions	

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> <u>Test Points:</u> See 3.1.2
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14</u> <u>Test Points:</u> $T_C = 100^{\circ}\text{C}$ , $V_{BB} = 5\text{V}$ , $R_{BB} = 20\Omega$ , $t_r \leq 5\mu\text{s}$ , $t_p \leq 5\mu\text{s}$ , $I_C = 1.0\text{A}$ , Duty Cycle $\leq 2\%$ , $R_S = 1.0\Omega$ 1. $t_p = 1\text{ms}$ : $V_{CC} = 35\text{V}$ 2. $t_p = 500\mu\text{s}$ : $V_{CC} = 45\text{V}$ 3. $t_p = 100\mu\text{s}$ : $V_{CC} = 80\text{V}$
3.6.0 SOAR Switching between Saturation and cutoff	
3.6.1 Resistive Load	<u>JS-6-T5.1</u> with $L = 0$ and CR disconnected <u>Test Points:</u> $R_{BB1} = 20\Omega$ , $R_{BB2} = 100\Omega$ , $V_{BB1} = 8.0\text{V}$ , $V_{BB2} = 5\text{V}$ , $T_C = 100^{\circ}\text{C}$ , $t_f \leq 5\mu\text{s}$ , $t_r \leq 5\mu\text{s}$ , $R_S = 1.0\Omega$ , $R_L = 78\Omega$ , $V_{CC} = 80\text{V}$ , $d = 10\%$
3.6.2 Clamped Inductive Load	<u>JS-6-T5.1</u> <u>Test Point:</u> $I_C \leq 1.0\text{A}$ , $V_{CE} = 80\text{V}$ , $R_{BB1} = 20\Omega$ , $R_{BB2} = 100\Omega$ , $V_{BB1} = 8\text{V}$ , $V_{BB2} = 5\text{V}$ , $R_L = 8\Omega$ , $L^* = 1.0\text{mH}$ , *J.W.Miller: 7871 in series with 7825-3

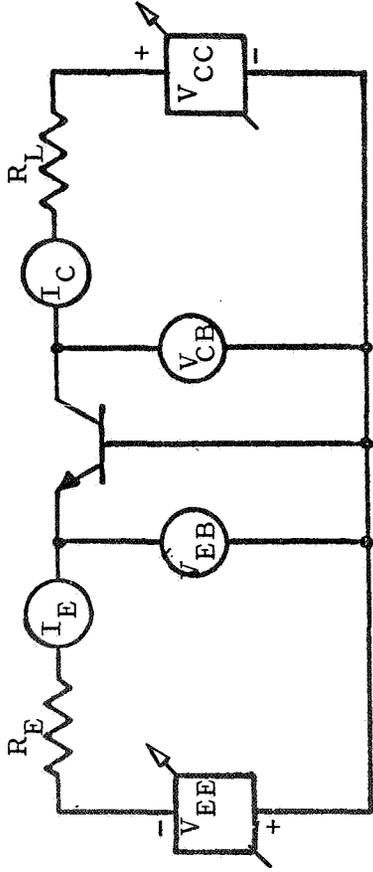
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.3 Unclamped Inductive Load	<p><u>JS-6-T5.1</u> and CR disconnected</p> <p><u>Test Points:</u></p> <p>1. <math>V_{BB1} = 8.0V</math>    <math>L^* = 1.0mH</math>  <math>R_{BB1} = 20\Omega</math>    <math>R_L = 66.66\Omega</math>  <math>V_{BB2} = 5.0V</math>    <math>V_{CC} = 10V</math>  <math>R_{BB2} = 100\Omega</math>    <math>f = 60Hz</math>  <math>R_S = 1.0\Omega</math>    <math>d = 10\%</math></p> <p>*J.W. Miller: 7871 in series with 7825-3</p> <p>2. <math>V_{BB1} = 8.0V</math>    <math>L^* = 50\mu H</math>  <math>R_{BB1} = 20\Omega</math>    <math>R_L = 7\Omega</math>  <math>V_{BB2} = 5V</math>    <math>V_{CC} = 10V</math>  <math>R_{BB2} = 100\Omega</math>    <math>f = 60Hz</math>  <math>R_S = 1.0\Omega</math>    <math>d = 10\%</math></p> <p>*J.W. Miller: 7825-8</p>
3.7.0 Shorted Class B SOAR	<p>(See Figure 6)</p> <p><u>Test Points:</u></p> <p><math>I_C</math> peak = 0.22A, <math>V_{CC} = 32.5V</math>,  <math>R_S = 1.0\Omega</math>, <math>R_{BB1} = 20\Omega</math>, <math>R_{BB2} = 100\Omega</math>  <math>f = 20Hz</math>, <math>T_C = 100^\circ C</math></p>
4.0.0 <u>Electrical Characteristics</u>	<p><math>T_C = 25^\circ C</math> (unless otherwise noted)</p>
	<p>Maximum limits unless otherwise noted</p> <p>Technique:</p> <p>DC - Continuous Operation</p> <p>C.T. - Curve Tracer</p> <p>P - 300<math>\mu s</math> Pulse, 2% Duty Cycle</p>

ItemTest Methods and Test Conditions

4.1.0	Static	
4.1.1	$I_{CBO} = 2.0nA$	$V_{CB} = 60V$ , Technique MIL-STD-3036-10
4.1.2	$I_{CBO} = 2.0\mu A$	$V_{CB} = 60V$ , $T_C = 150^\circ C$ , Technique MIL-STD-3036-D
4.1.3	$I_{EBO} = 2.0nA$	$V_{BE} = -5V$ , Technique MIL-STD-3061-D
4.1.4	$V_{(BR)CEO} = 65V$ min	<u>JS-6-T5.1</u> (See 3.2.3)
4.1.5	$V_{(BR)CER} = 80V$ min	<u>JS-6-T5.1</u> (See 3.2.3 except $R_{BB2} = 10\Omega$ , $V_{BB2} = 0$ )
4.1.6	$V_{(BR)CBO} = 120V$ min	$I_C = 1mA$ Technique C.T.
4.1.7	$V_{(BR)EBO} = 7V$ min	$I_E = 1mA$ Technique C.T.
4.1.8	$h_{FE} = 10$ min	$I_C = 1A$ , $V_{CE} = 10V$ , Technique - P
4.1.9	$h_{FE} = 25$ min	$I_C = 0.5A$ , $V_{CE} = 10V$ Technique P
4.1.10	$h_{FE} = 40$ min 120 max	$I_C = 150mA$ , $V_{CE} = 10V$ Technique P
4.1.11	$h_{FE} = 10$ min	$I_C = 10mA$ , $V_{CE} = 10V$ Technique C.T.
4.1.12	$h_{FE} = 20$ min	$I_C = 0.1mA$ , $V_{CE} = 10V$ Technique C.T.
4.1.13	$h_{FE} = 35$ max	$I_C = 10mA$ , $V_{CE} = 10V$ , $T_C = 55^\circ C$ Technique C.T.
4.1.14	$V_{CE(S)} = 2.0V$ max	$I_C = 1.0A$ , $I_B = 0.2A$ Technique C.T.
4.1.15	$V_{CE(S)} = 0.5V$ max	$I_C = 150mA$ , $I_B = 15mA$ Technique C.T.
4.1.16	$V_{BE(S)} = 2.5V$ max	$I_C = 1.0A$ , $I_B = 0.2A$ Technique C.T.
4.1.17	$V_{BE(S)} = 1.1V$ max	$I_C = 150mA$ , $I_B = 15mA$ Technique C.T.
4.1.18	$I_{CEO} = 1.0\mu A$ max	$V_{CEO} = 55V$ Technique D.C.
4.1.19	$V_{BEF} = 1.5V$ max	$V_{CB} = 120V$ Technique C.T.
4.2.0	Dynamic	
4.2.1	$t_d + t_r + t_f = 30ns$	Circuit specified with registered spec.

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.2.2	$h_{fe} = 30 \text{ min, } 100 \text{ max}$	$I_C = 1.0\text{mA, } V_{CE} = 5\text{V, } f = 1.0\text{KHz}$
4.2.3	$h_{fe} = 35 \text{ min, } 150 \text{ max}$	$I_C = 5.0\text{mA, } V_{CE} = 10\text{V, } f = 1.0\text{KHz}$
4.2.4	$h_{fe} = 3 \text{ min, } 10 \text{ max}$	$I_C = 50\text{mA, } V_{CE} = 10\text{V, } f = 20\text{MHz}$
4.2.5	NF = 6db	$I_C = 0.3\text{mA, } V_{CE} = 10\text{V, } f = 1\text{KHz}$ R = 1K $\Omega$ circuit bandwidth 1Hz
4.2.6	$C_{obo} = 15\text{pf}$	$V_{CB} = 10\text{V}$
4.2.7	$C_{ibo} = 80\text{pF}$	$V_{BE} = 0.5\text{V}$
4.2.8	$h_{ob} = 0.1 \mu\text{mhos min}$	$I_C = 1.0\text{mA, } V_{CE} = 5\text{V, } f = 1\text{KHz}$
4.2.9	$h_{ob} = 0.1 \mu\text{mhos min}$ $1.0 \mu\text{mhos max}$	$I_C = 5.0\text{mA, } V_{CE} = 10\text{V, } f = 1\text{KHz}$
4.2.10	$h_{ib} = 24\Omega \text{ min, } 34\Omega \text{ max}$	$I_C = 1.0\text{mA, } V_{CE} = 5\text{V, } f = 1\text{KHz}$
4.2.11	$h_{ib} = 4\Omega \text{ min, } 8\Omega \text{ max}$	$I_C = 5.0\text{mA, } V_{CE} = 10\text{V, } f = 1\text{KHz}$
4.2.12	$h_{rb} = 3 \times 10^{-4}$	$I_C = 1.0\text{mA, } V_{CE} = 5.0\text{V, } f = 1\text{KHz}$
4.2.13	$h_{rb} = 3 \times 10^{-4}$	$I_C = 5.0\text{mA, } V_{CE} = 10\text{V, } f = 1\text{KHz}$
5.0.0	Thermal Characteristics	
5.1.0	$\tau_J = 75\text{ms min}$	
5.2.0	$\theta_{JC} = 35^\circ\text{C/W max}$	
5.2.1	$\theta_{JA} = 175^\circ\text{C/W max}$	

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

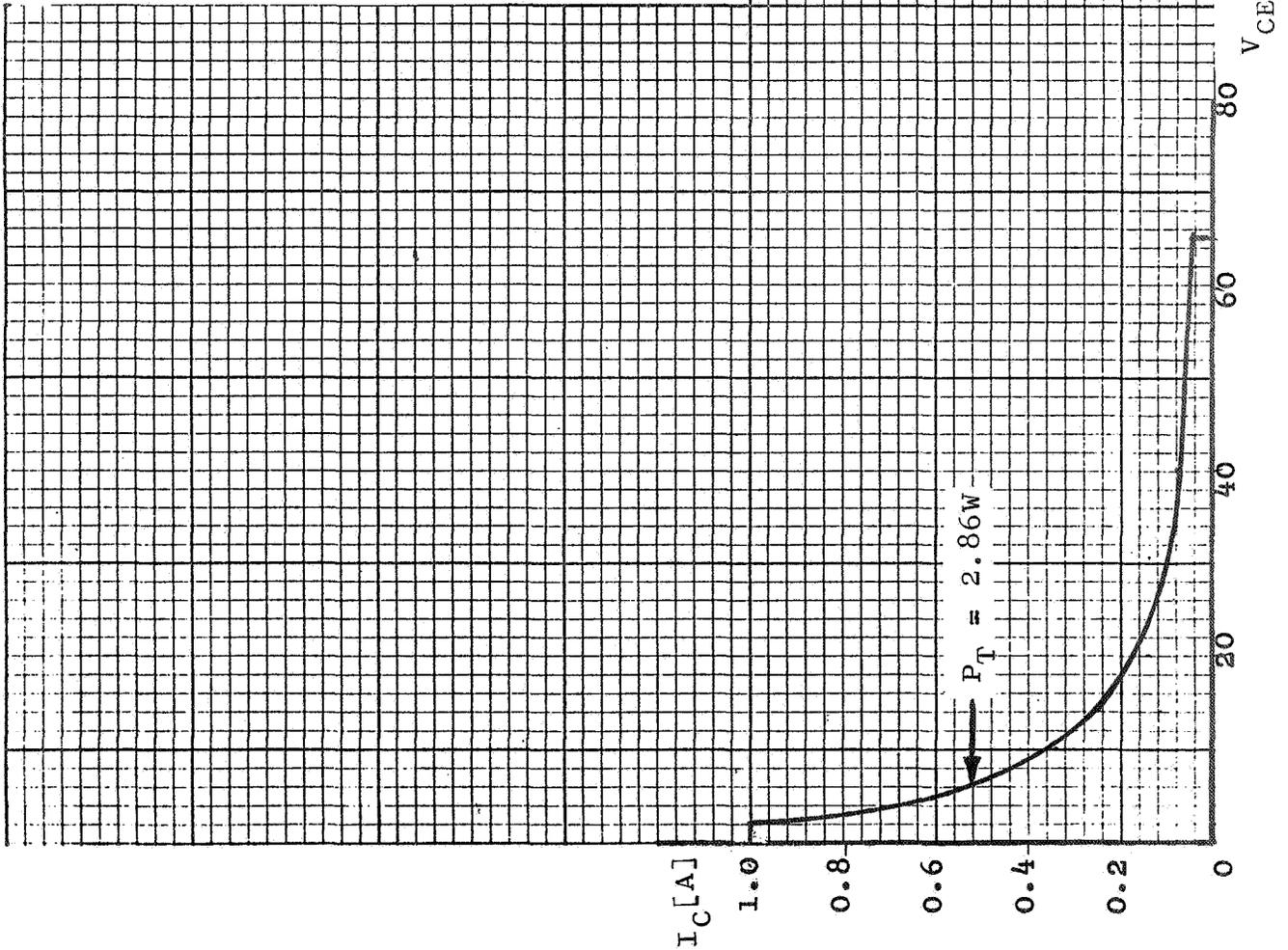
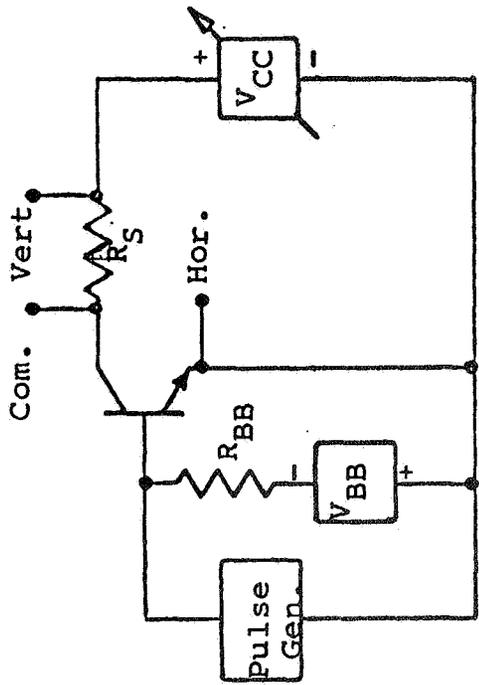


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

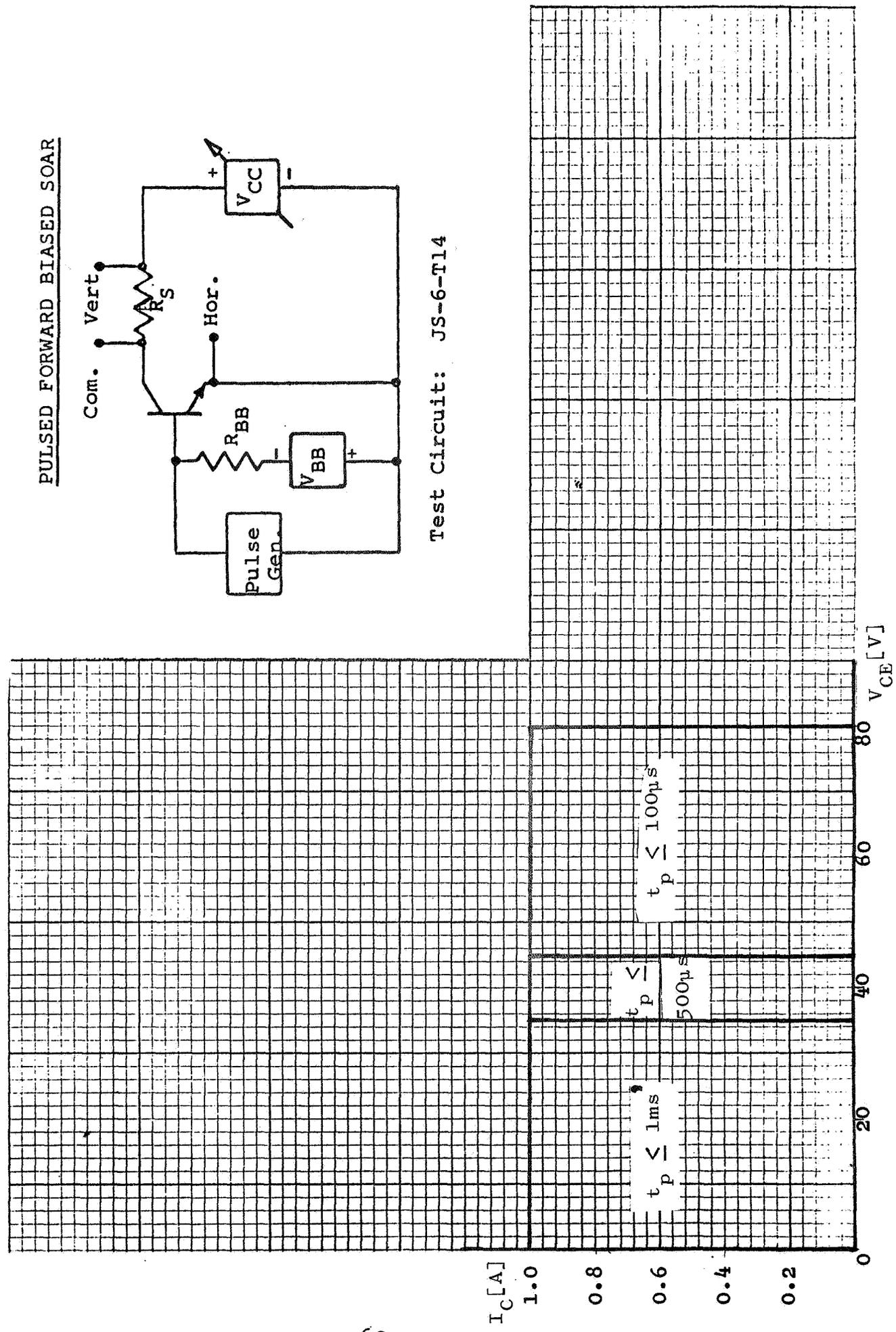
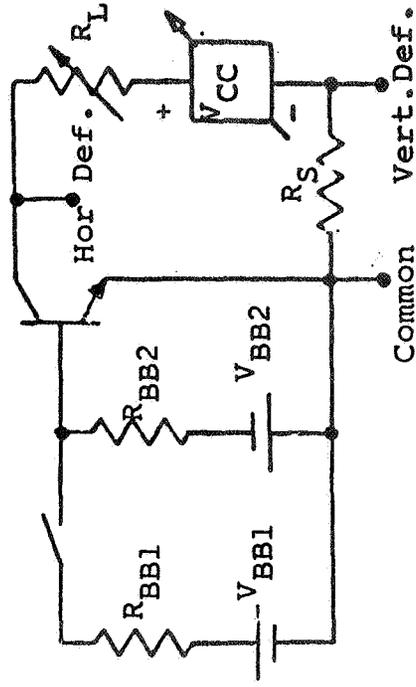


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

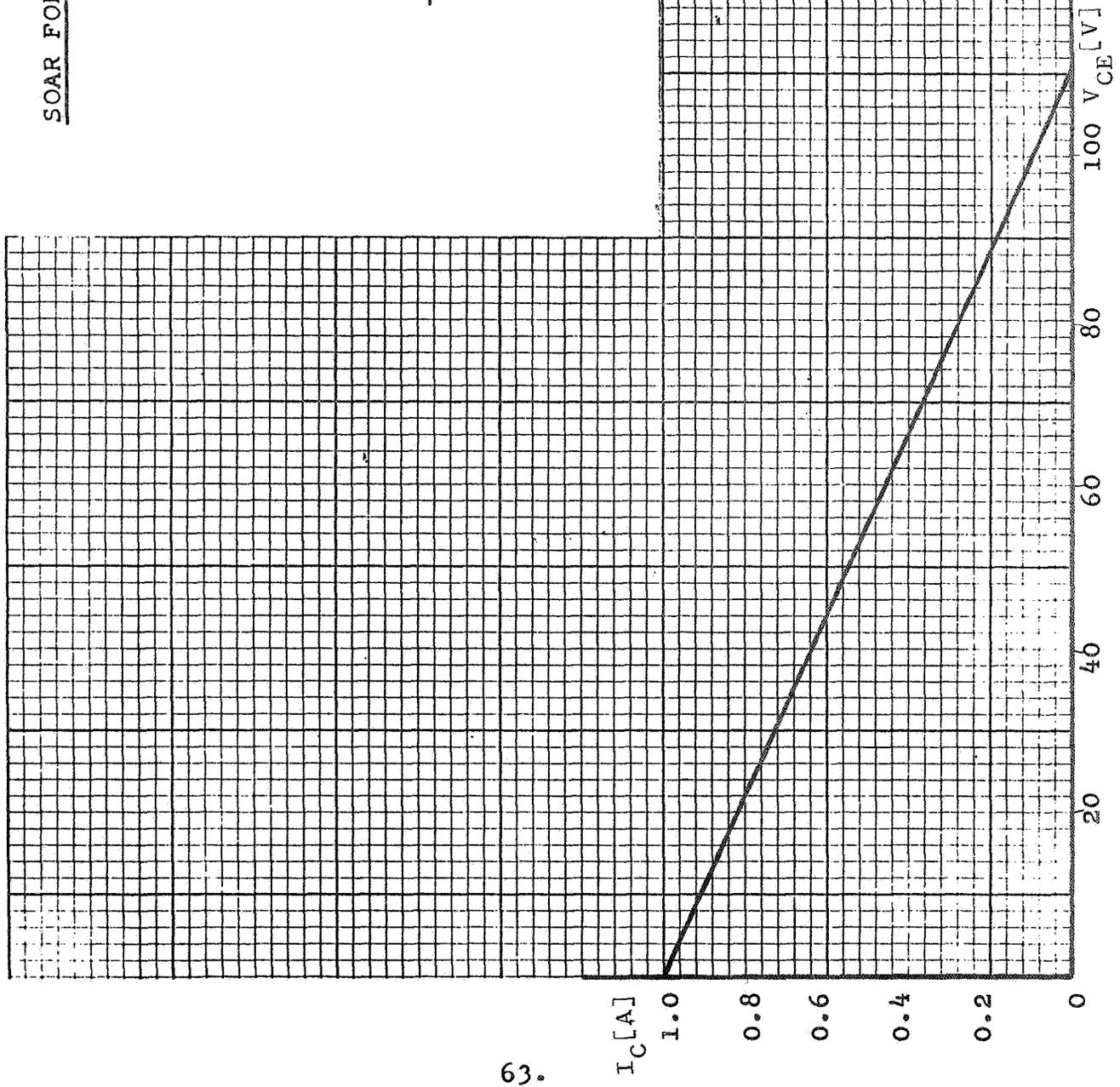
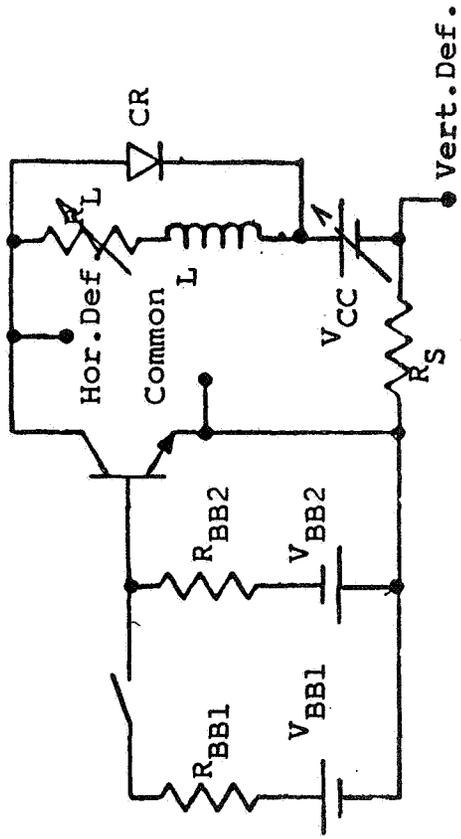


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

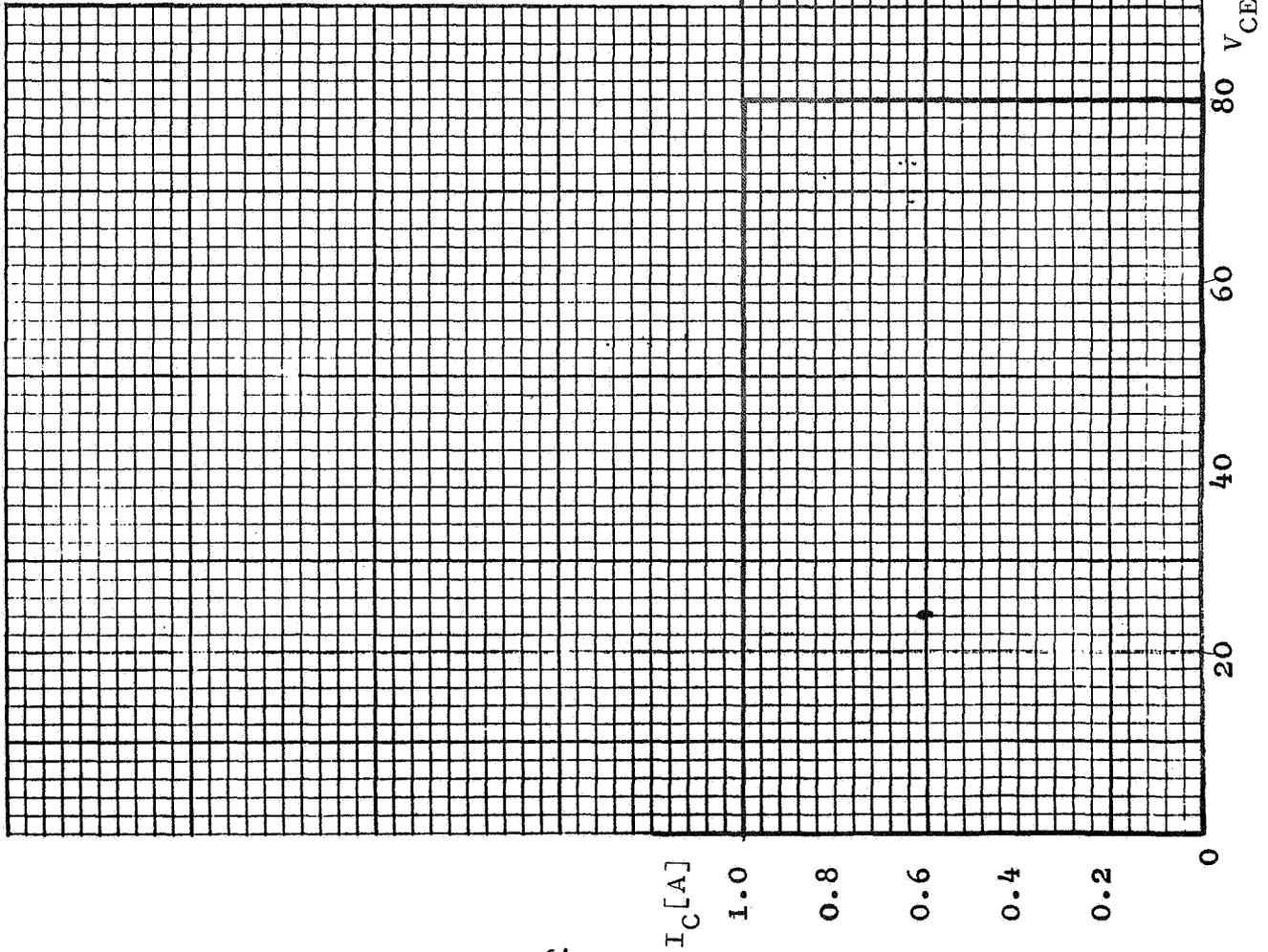
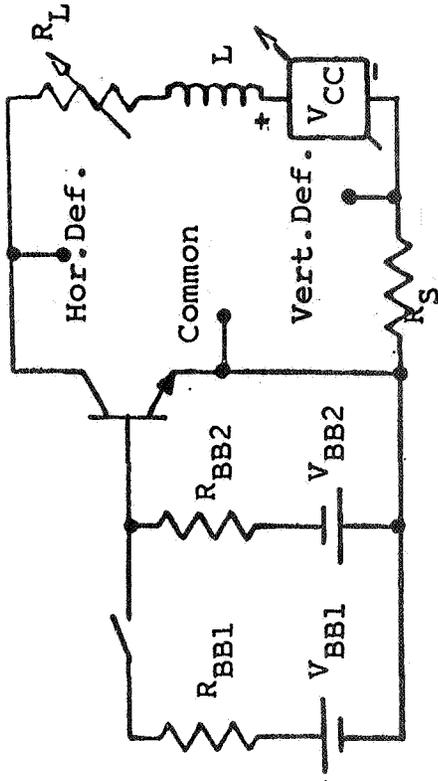


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

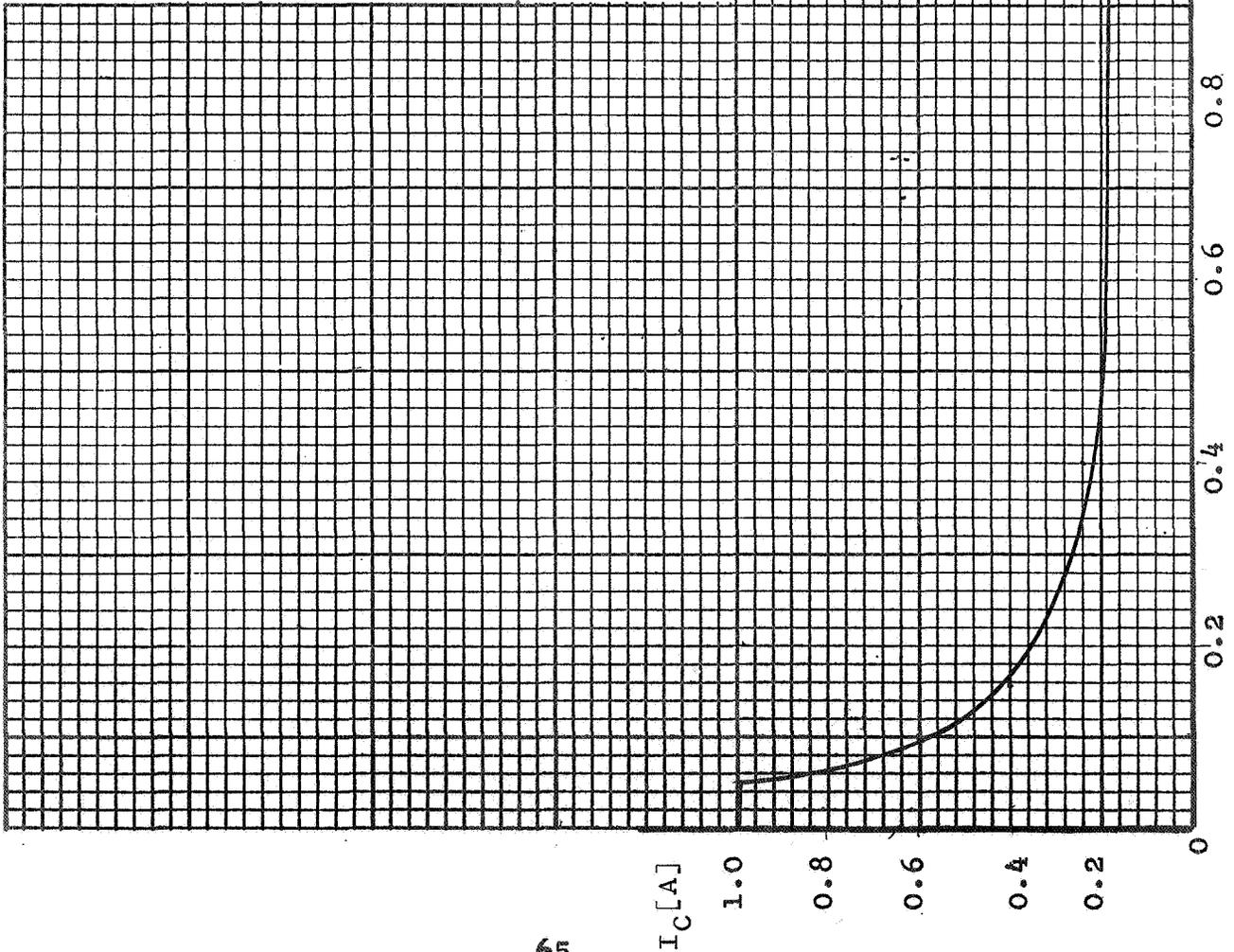


Figure 5

SHORTED CLASS B SOAR

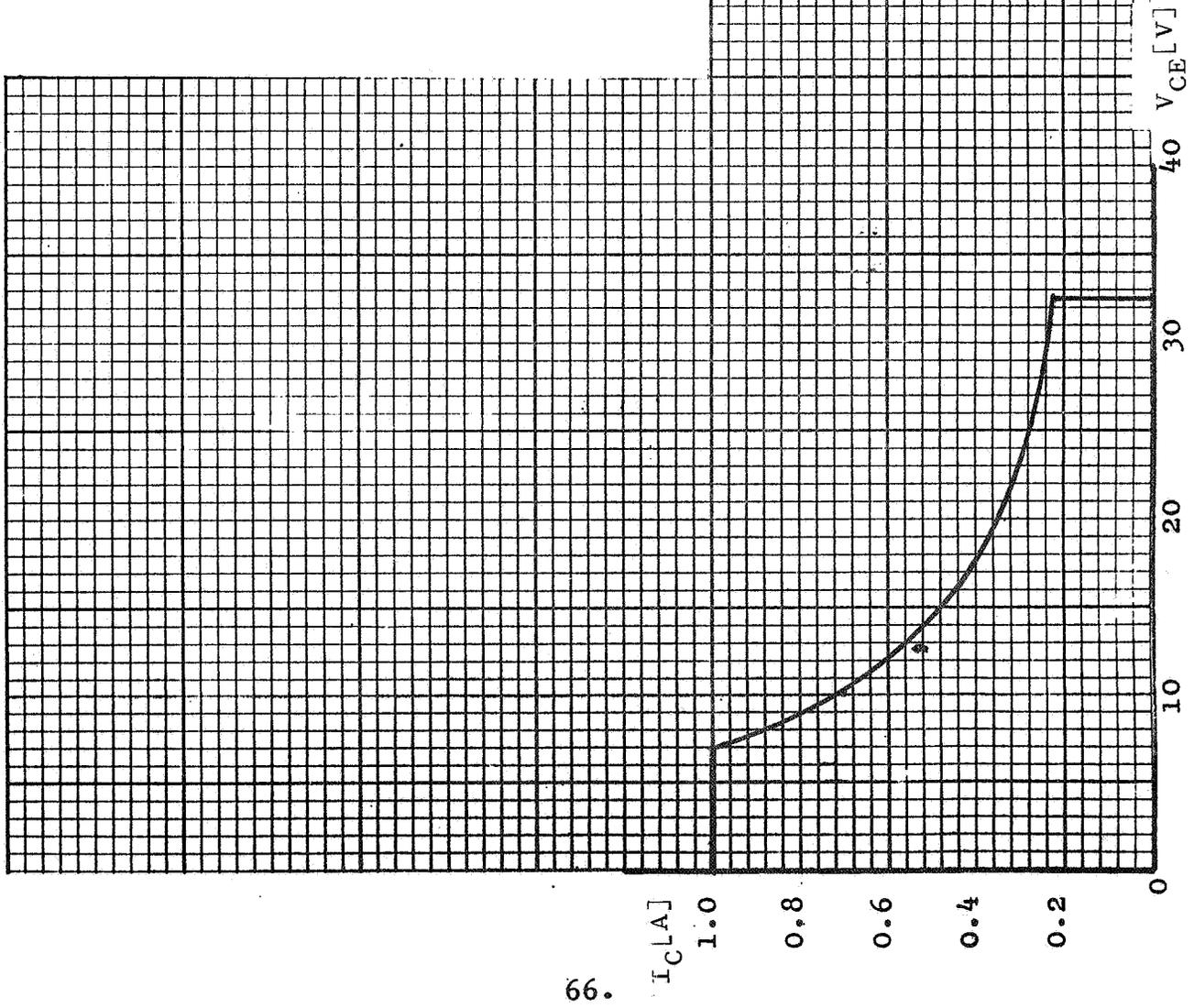
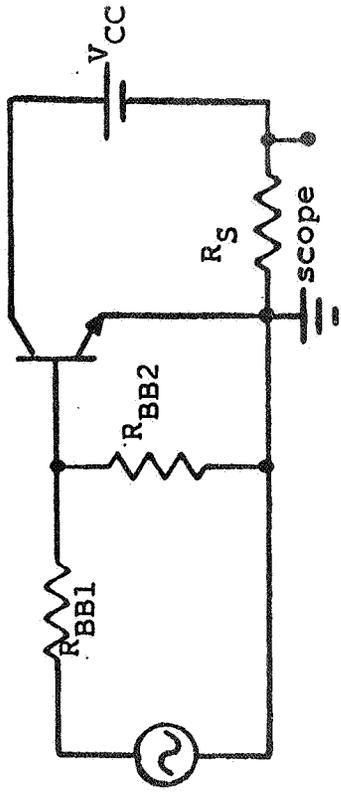


Figure 6

SILICON POWER TRANSISTOR

< S2N2034A >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer H --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline - T05	
2.2.0	Terminal Designation	
	1. -- Emitter	
	2. -- Base	
	3. -- Collector	
	case -- Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = +200^{\circ}C$	<u>JS-6-T1.2</u> [JEDEC Publication No.65 "Test Procedures for Verification of Maximum Ratings."]
	$T_{STG(min)} = -65^{\circ}C$	
3.1.2	$T_{J(max)} = 200^{\circ}C$	<u>JS-6-T2</u> $T_C = 100^{\circ}C$ $V_{CB} = 60V, I_C = 83mA$
3.1.3	$T(Lead) = 230^{\circ}C$	Distance from case - 1/16 in. Time = 3.0s
3.2.0	Voltage	$T_C = 25^{\circ}C$
3.2.1	$V_{CB0} = 80V$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1

<u>Item</u>		<u>Test Method and Test Conditions</u>
3.2.2	$V_{EBO} = 10V$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1
3.2.3	$V_{CEX} = 60V$	<u>JS-6-T5.1</u> $I_C (V_{CE} = V_{CEX}) = 3A$ $V_{CC} = 60V, R_L = 19.6\Omega$ $L = 1.0mH^*, CR = 1N1202$ $V_{BB1} = 6V, R_{BB1} = 5\Omega$ $V_{BB2} = 1.5V, R_{BB2} = 5\Omega$ Pulse width = 1.0ms, Duty Cycle = 2% $R_S = 0.1\Omega, t_r \leq 50\mu s$ $t_f \leq 50 \mu s$ *Miller # 7871 in series with 7825-3
3.3.0	Current	
3.3.1	$I_C = 3A$	<u>JS-6-T6</u> $I_B = 0.6A, T_C = \leq 25^\circ C$
3.3.2	$I_B = 1A$	<u>JS-6-T8</u> $T_C = \leq 25^\circ C$
3.4.0	Power	
3.4.1	$P_{,T} = 5W$	<u>JS-6-T12</u> $T_C = \leq 100^\circ C$ $V_{CB} = 60V, I_C = 83mA$
	Derating Factor = $0.05 W/^\circ C$	
3.4.2	$P_{TM} = I_C V_{CC} = 180W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 60V, V_{BB} = 1.5V,$ $R_{BB} = 5\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.4.2 (Cont'd)	Pulse width = 1ms, Duty Cycle = $\leq 1\%$ , $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> [See Figure 1] <u>Test Point:</u> [See 3.4.1]
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14</u> [See Figure 2] <u>Test Points:</u> $T_C \leq 100^\circ C$ , $V_{BB} = 1.5V$ , $R_{BB} = 5\Omega$ $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ , $I_C = 3A$ Duty Cycle $\leq 1\%$ , $R_S = 0.1\Omega$ 1. For $t_p = 7.5ms$ ; $V_{CC} = 20V$ 2. For $t_p = 5.0ms$ ; $V_{CC} = 30V$ 3. For $t_p = 2.5ms$ ; $V_{CC} = 50V$ 4. For $t_p = 1ms$ ; $V_{CC} = 60V$
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<u>JS-6-T5-5.1</u> with L=0 and CR disconnected [See Figure 3] <u>Test Points:</u> $I_C = 3A$ , $V_{CC} = 90V$ , $R_{BB1} = 5\Omega$ $R_{BB2} = 5\Omega$ , $V_{BB1} = 6V$ , $V_{BB2} = 1.5V$ $T_C = 100^\circ C$ ; $t_f \leq 50\mu s$ , Collector Current

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.6.1	(Cont'd)	$t_r \leq 50\mu s$ Collector Current $R_S = .1\Omega$
3.6.2	Clamped Inductive Load	<u>JS-6-T5-5.1</u> [See Figure 4] <u>Test Points:</u> $I_C = 3A, V_{CC} = 60V, R_L = 19.6\Omega$ $L = 1mH^*, R_{BB1} = 5\Omega, R_{BB2} = 5\Omega$ $V_{BB1} = 6V, V_{BB2} = 1.5V, t_p = 1ms$ $CR = 1N1202, T_C = 25^\circ C, t_r \leq 50\mu s,$ $t_f \leq 50\mu s$ Duty Cycle = 2%, $R_S = 0.1\Omega$ *Miller # 7871 in series with 7825-3
3.6.3	Unclamped Inductive Load	<u>JS-6-T5-5.1</u> with CR disconnected [See Figure 5] <u>Test Points:</u> $R_{BB1} = 5\Omega, R_{BB2} = 5\Omega, R_S = .1\Omega$ $V_{BB1} = 6V, V_{BB2} = 1.5V, f = 20Hz$ $T_C = 25^\circ C, d = 10\%$ 1. $I_C = 3A, V_{CC} = 50V, R_L = 16.23\Omega$ $L = 15mH^*$ 2. $I_C = 0.9A, V_{CC} = 35V, R_L = 38.5\Omega$ $L = 60mH^{**}$ *Series Stancor C-2688 & C-2689 **Series 2 Stancor C-2686 & C-2688
3.7.0	Shorted Class B SOAR	[See Figure 6] <u>Test Point:</u> $I_{C(peak)} = 0.25A, V_{CC} = 60V, R_S = .1\Omega$ $R_{BB1} = 1\Omega, R_{BB2} = 3\Omega, f = 20Hz$ $T_C \leq 100^\circ C$

ItemTest Methods and Test Conditions

4.0.0

Electrical  
Characteristic

Maximum limits  
unless otherwise  
noted.

 $T_C = 25^{\circ}\text{C}$  [unless otherwise noted]

Technique:

DC - Continuous  
Operation

C.T. - Curve Tracer

P - 300 $\mu\text{s}$  Pulse  
2% Duty Cycle

4.1.0

Static

4.1.1

 $I_{CEX} = 750\mu\text{A}$ 
 $V_{CE} = 80\text{V}$ ,  $V_{BE} = -1.5\text{V}$ ,  $T_C = 150^{\circ}\text{C}$ 

Technique - C.T.

4.1.2

 $I_{CEX} = 150\mu\text{A}$ 
 $V_{CE} = 80\text{V}$ ,  $V_{BE} = -1.5\text{V}$ 

Technique - C.T.

4.1.3

 $I_{CBO} = 150\mu\text{A}$  $V_{CB} = 80\text{V}$ 

Technique - C.T.

4.1.4

 $I_{EBO} = 50\mu\text{A}$  $V_{EB} = 10\text{V}$ 

Technique - C.T.

4.1.5

 $V_{[BR]CEO} = 60\text{V min}$  $I_C = 50\text{mA}$ 

Technique - C.T.

4.1.6

 $I_{CEO} = 100\mu\text{A}$  $V_{CE} = 45\text{V}$ 

Technique - C.T.

4.1.7

 $h_{FE} = 20 \text{ min}$  $V_{CE} = 4\text{V}$ ,  $I_C = 1\text{A}$  $h_{FE} = 60 \text{ max}$ 

Technique - C.T.

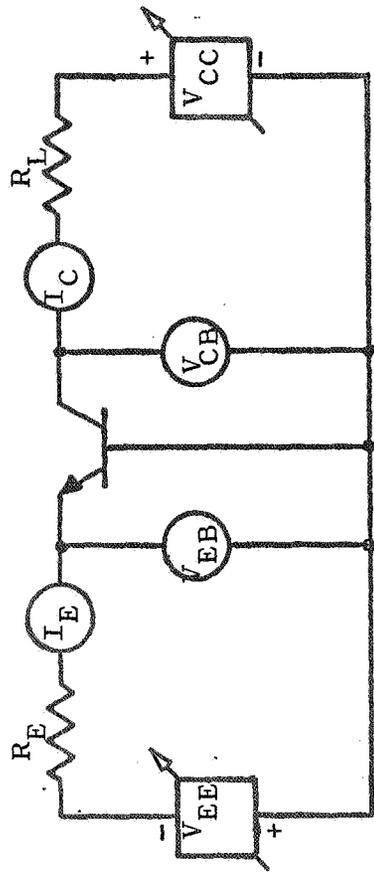
4.1.8

 $h_{FE} = 20 \text{ min}$ 
 $V_{CE} = 4\text{V}$ ,  $I_C = 1\text{A}$ ,  $T_C = -55^{\circ}\text{C}$ 

Technique - C.T.

<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.1.9	$V_{CE[sat]} = 0.3V$	$I_C = 1A, I_B = 0.1A$ Technique - C.T.
4.1.10	$V_{BE} = 1.2V$	$V_{CE} = 4; I_C = 1A$ Technique - C.T.
4.1.11	$V_{CE[sat]} = 1V$	$I_C = 3A, I_B = 0.3A$
4.1.12	$V_{BE[sat]} = 1.5V$	$I_C = 3A, I_B = 0.3A$ Technique - C.T.
4.2.4	$t_{on} = 1.0\mu s$	$V_{CC} = 12V, I_C = 1.0A, I_{B1} = 100mA$
4.2.5	$t_{off} = 1.5\mu s$	$V_{CC} = 12V, I_C = 1.0A, I_{B1} = 100mA,$ $I_{B2} = -50mA$
4.2.7	$\left  h_{fe} \right _{min} = 1$ $\left  h_{fe} \right _{max} = 6$	$V_{CE} = 4V, I_C = 0.1A$ $f = 1.0MHz$
5.0.0	<u>Thermal Characteristics</u>	
5.1.0	$\tau_J = 80ms \text{ min}$	$I_C = 1A, V_{CE} = 5V, T_C = 25^\circ C$ MIL-STD-750 Method 3146.1
5.2.0	$\theta_{J-C} = 20^\circ C/W$	$I_C = 1A, V_{CE} = 5V$ MIL-STD-750A Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

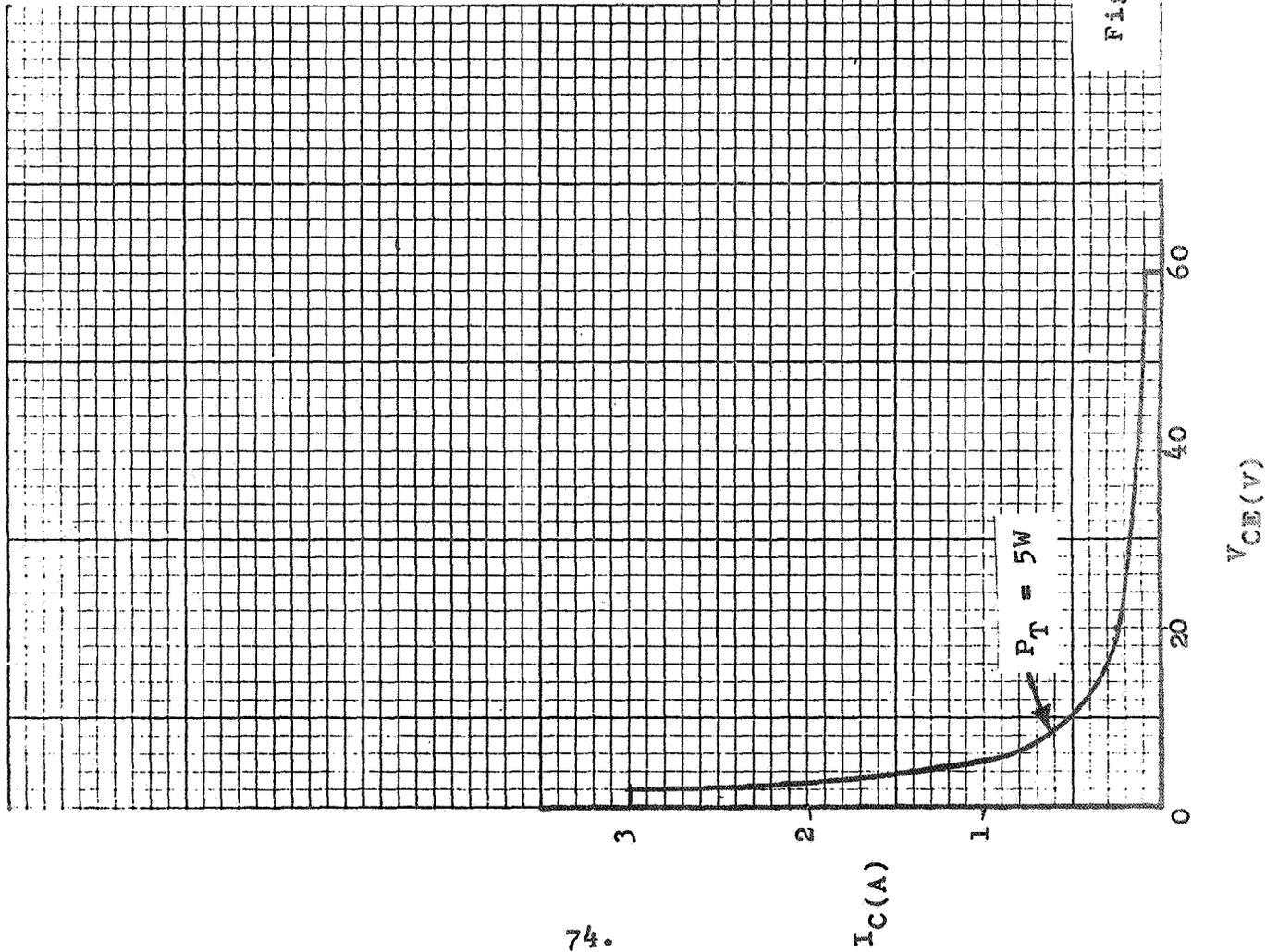
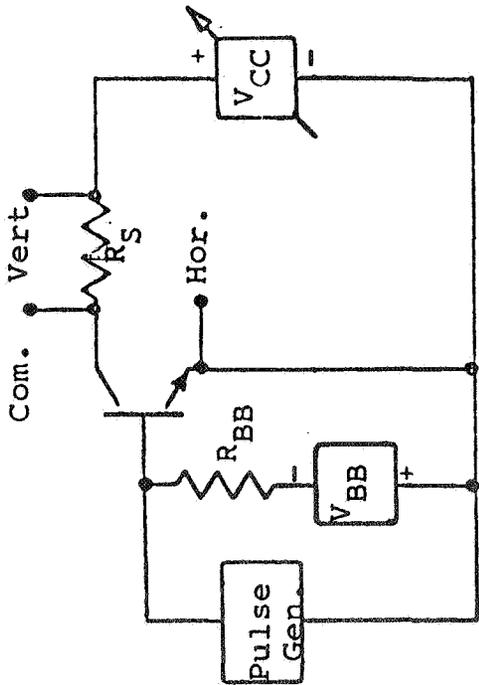


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

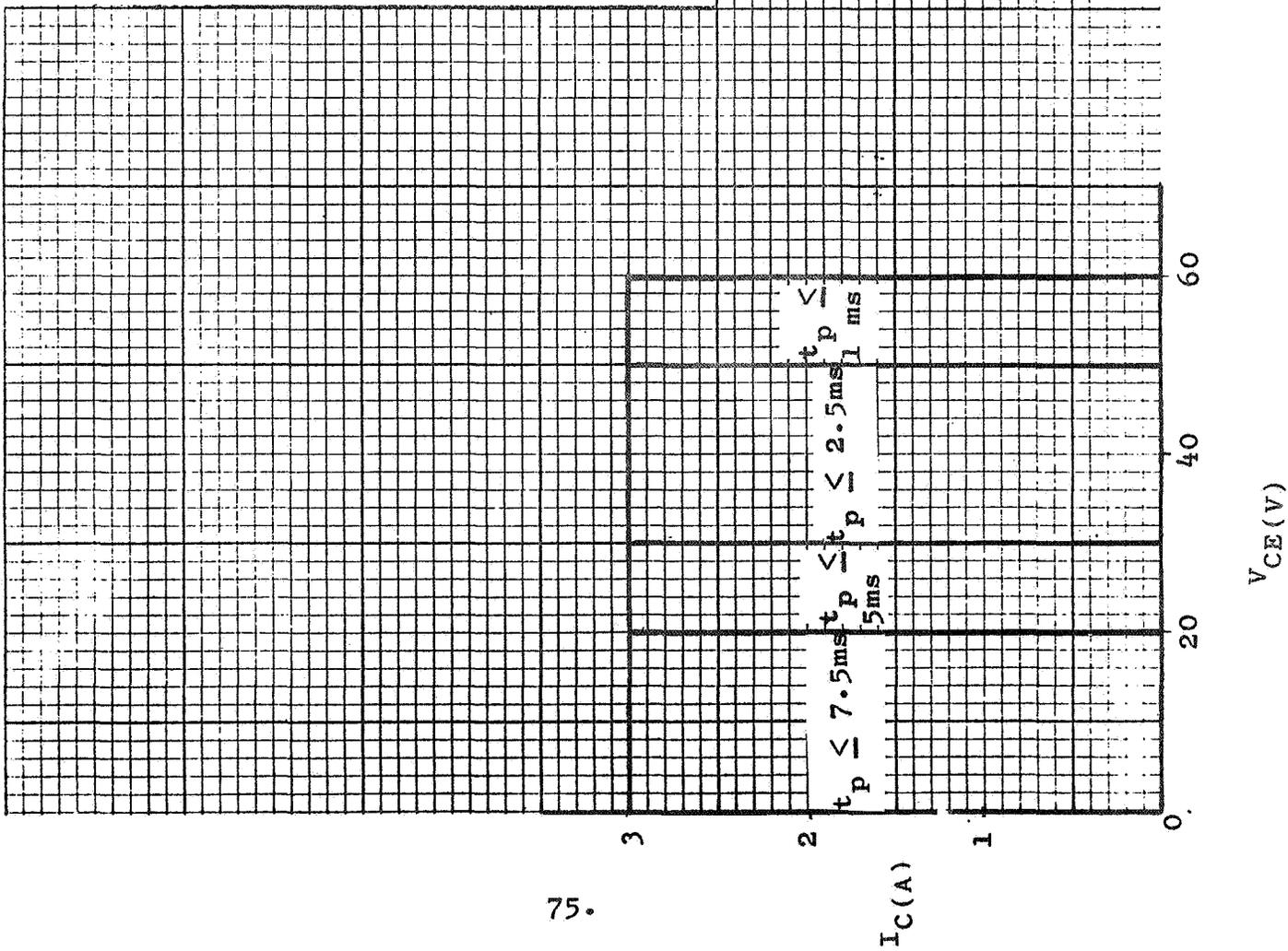
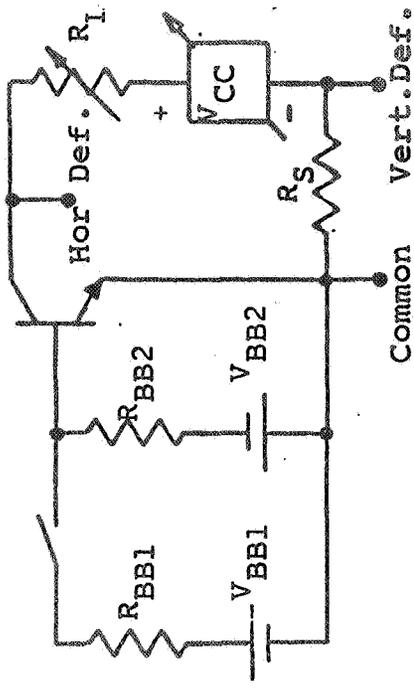


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

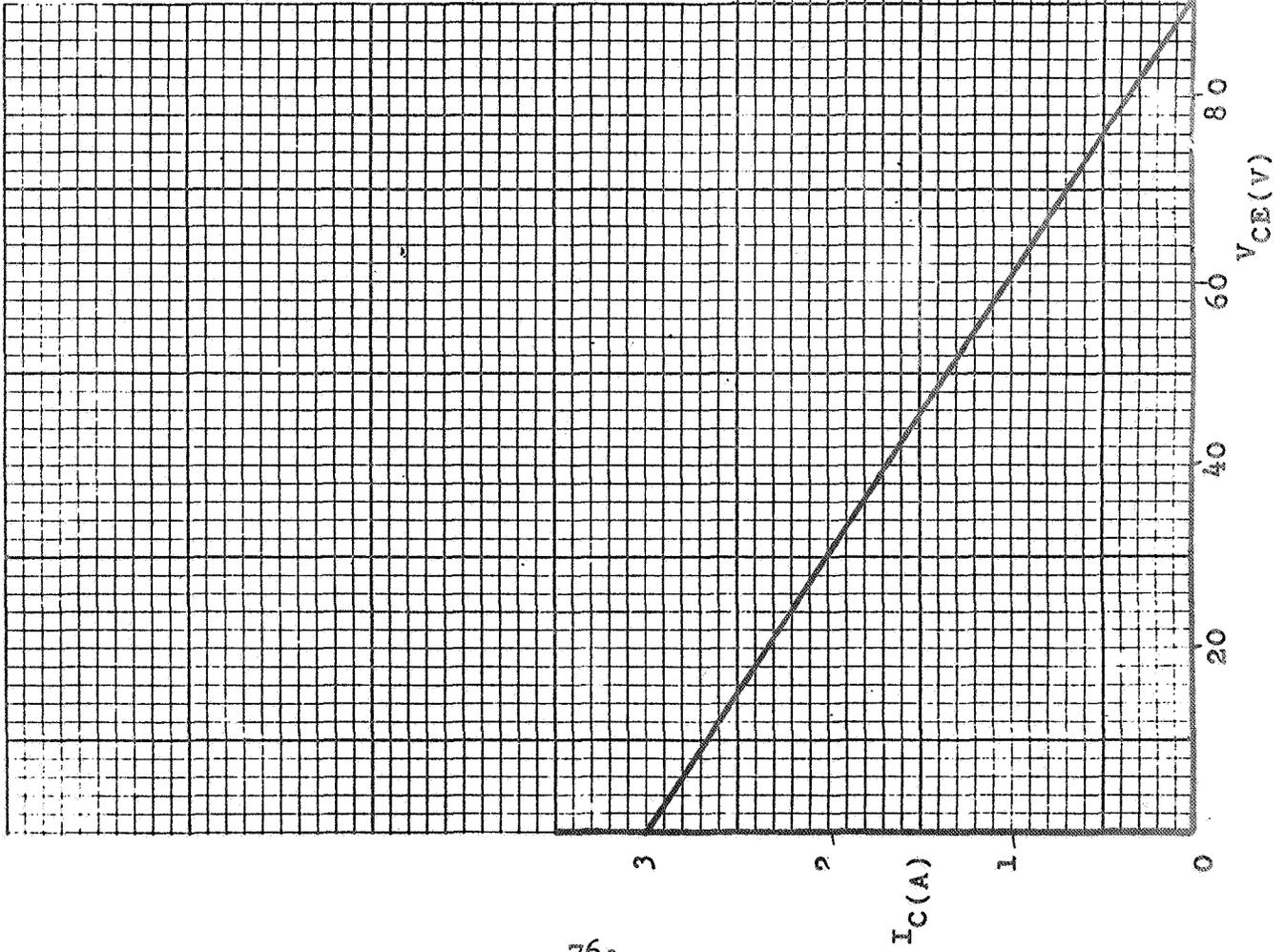
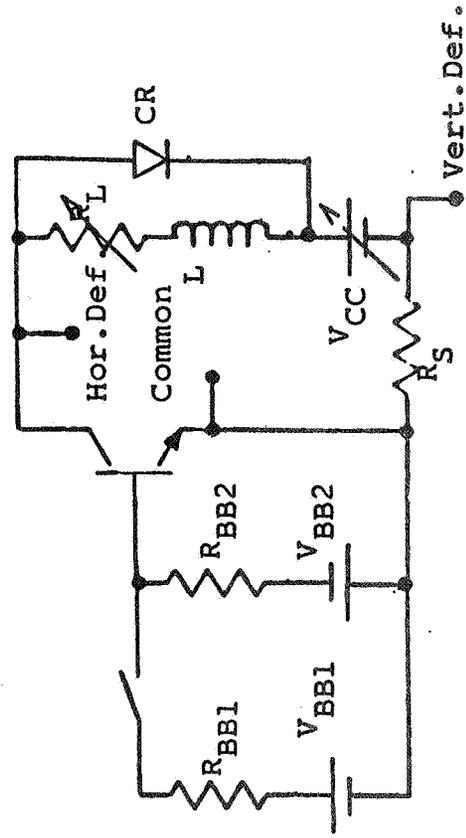


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

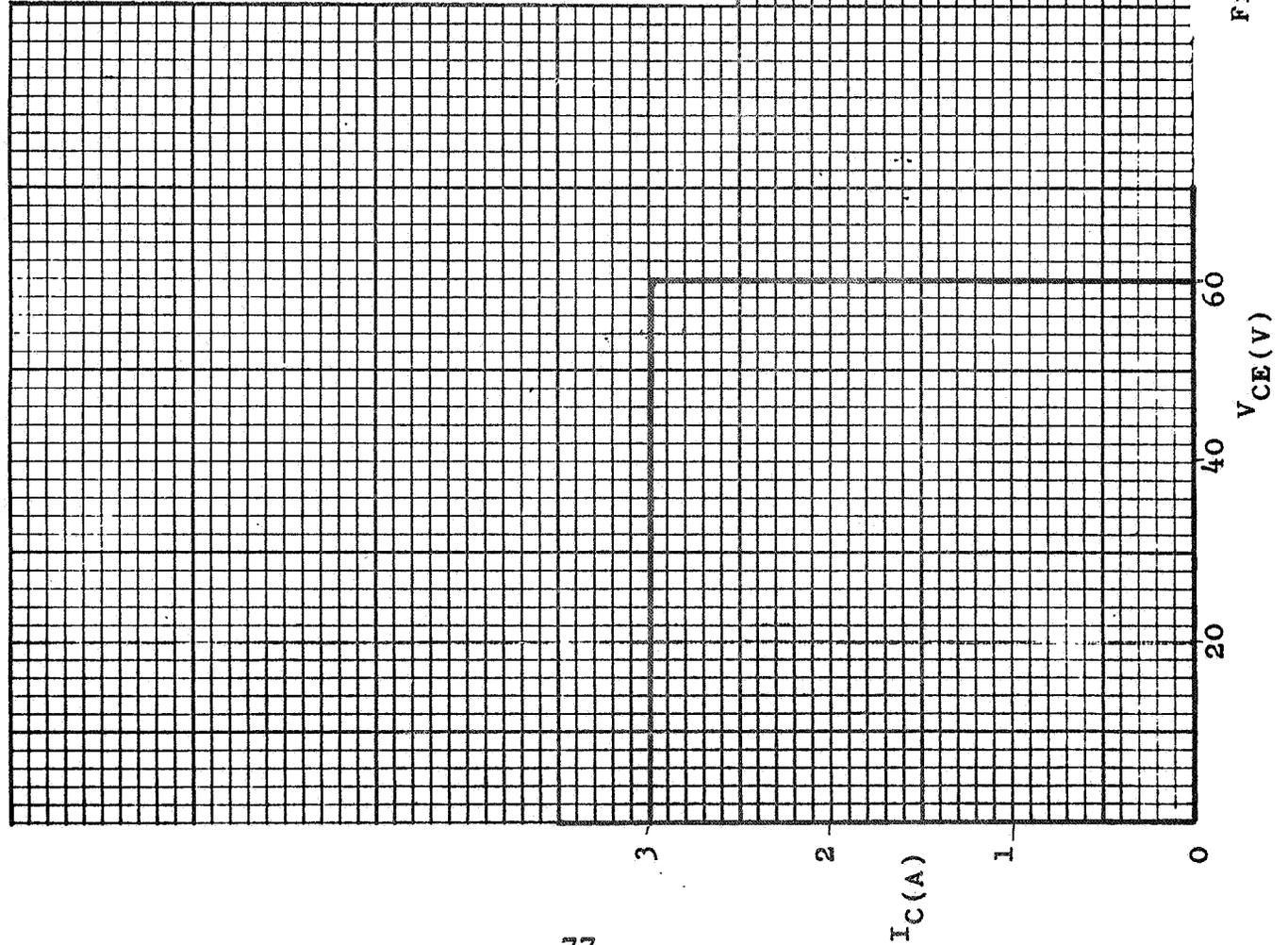
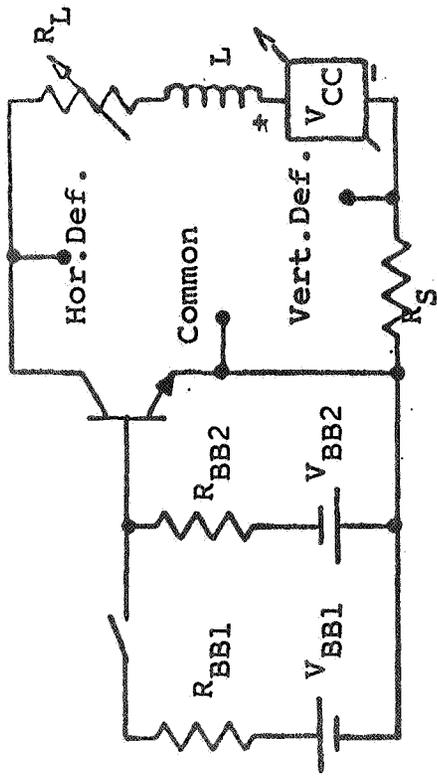


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

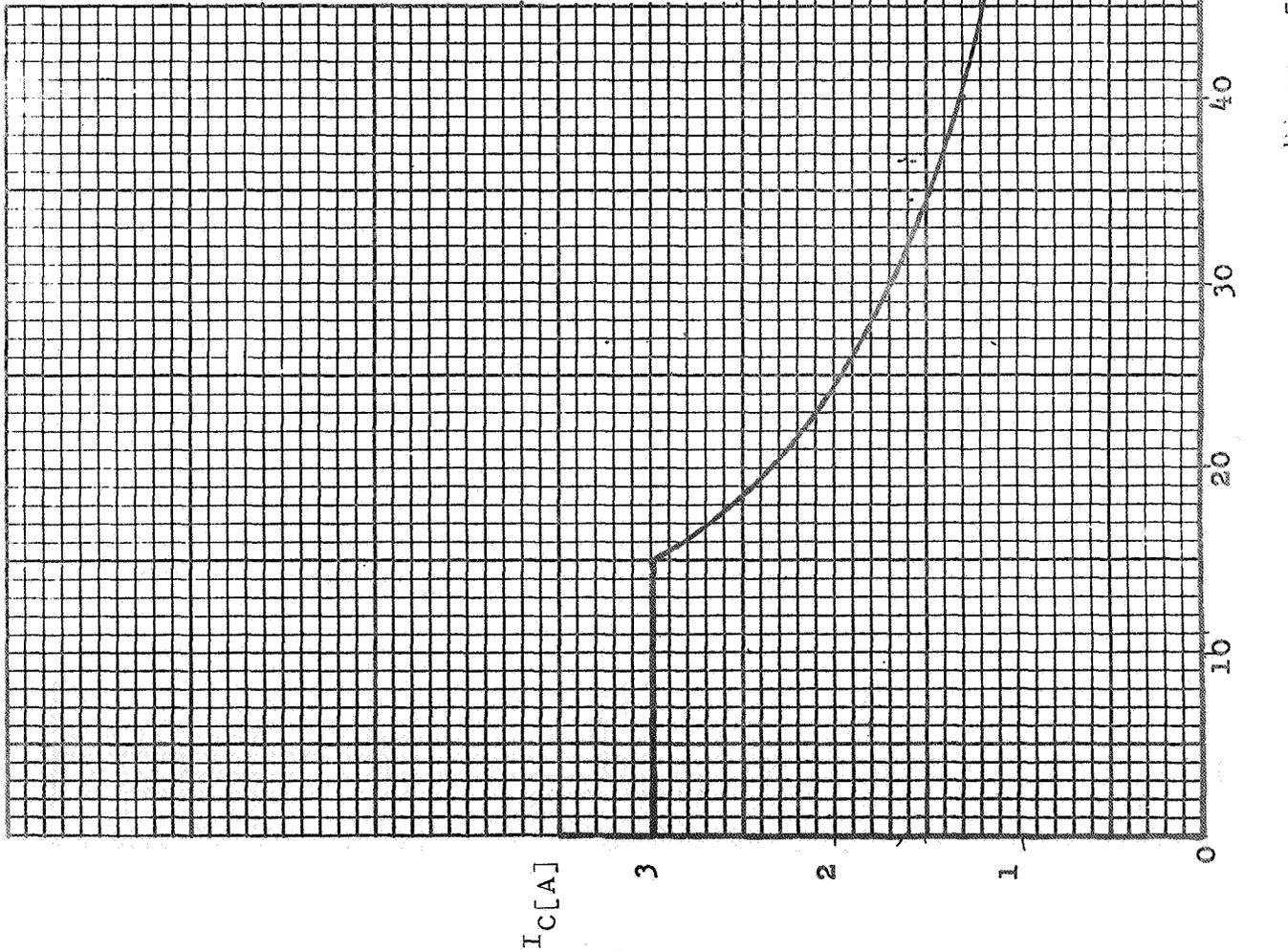


Figure 5

SHORTED CLASS B SOAR

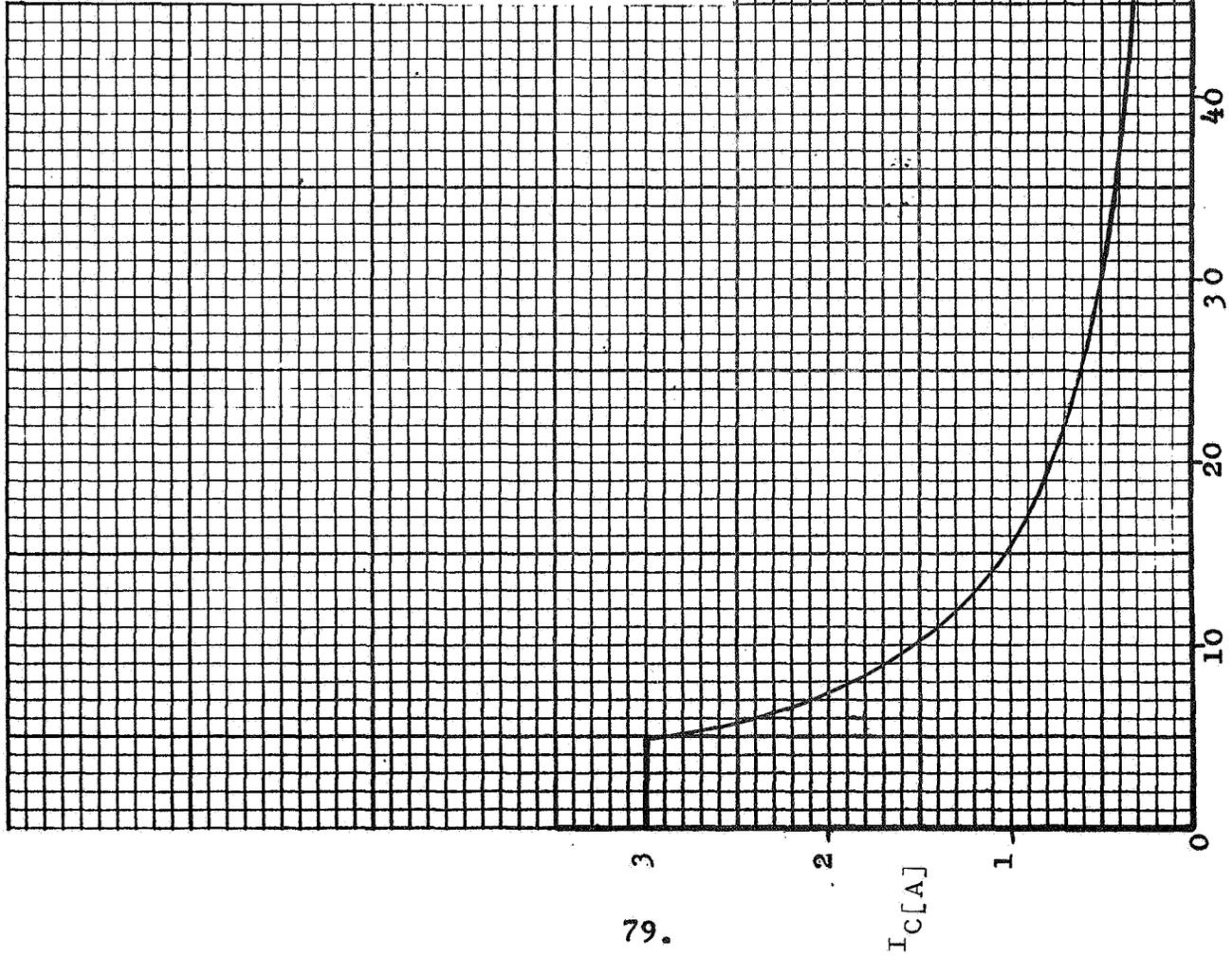
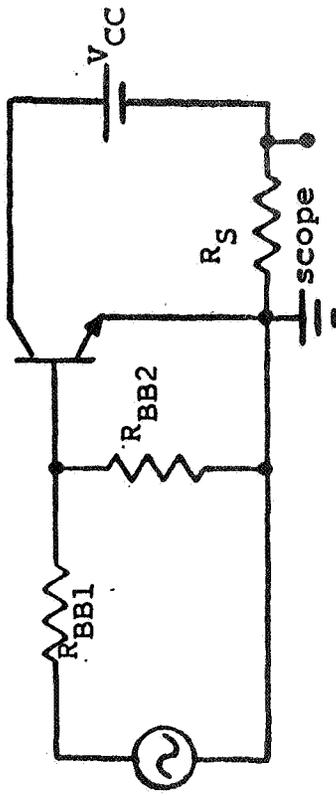


Figure 6

$V_{CE}$  [V]

$I_C$  [A]

Silicon Power Transistor

< Type 2N2126 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer C --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

GEORGE C. MARSHALL SPACE FLIGHT CENTER

HUNTSVILLE, ALABAMA

Contract No. NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	Terminal Designation	
	1 - Base	
	2 - Emitter	
	3 - Collector	
	case - Collector	
2.2.1	Maximum Stud Torque - 100 in.lbs.	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{stg}(\max) = +175^{\circ}\text{C}$	<u>JS-6-T1.1</u>
	$T_{stg}(\min) = -65^{\circ}\text{C}$	<u>JS-6-T1.2</u>
3.1.2	$T_j = 175^{\circ}\text{C}$	<u>JS-6-T2</u>
		$T_C = 100^{\circ}\text{C}, V_{CB} = 100\text{V}, I_C = 1.67\text{A}$
3.1.3	$T(\text{Lead}) = 230^{\circ}\text{C}$	Distance from case - 1/4 in., Time - 10s
3.2.0	Voltage	
3.2.1	$V_{CB0} = 200\text{V}$	<u>JS-5-T3</u> or MIL-STD-750A Method 3001.1 (See page 18)
3.2.2	$V_{EB0} = 15\text{V}$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1 (See page 19)
3.2.3	$V_{CEX} = 180\text{V}$	<u>JS-6-T5-2.1</u>
		$I_C (V_{CE} = V_{CEX}) = 30\text{A}, V_{CC} = 180\text{V},$ $R_L = 6\Omega, L = 1\text{mH}^*, CR = 1\text{N1204},$ $V_{BB1} = 14\text{V}, R_{BB1} = 1\Omega, V_{BB2} = 8\text{V},$ $R_{BB2} = 3\Omega,$ Duty Cycle = 1%, $t_p = 1\text{ms}, R_s = 0.1\Omega$
		*Miller No. 7870

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.3.0	Current	
3.3.1	$I_C = 30A$	<u>JS-6-T6</u> $I_b = 6A, T_C = 25^{\circ}C$
3.3.2	$I_B = 10A$	<u>JS-6-T8</u> $T_C = 25^{\circ}C$
3.3.3	$I_E = 36A$	<u>JS-6-T10</u> $I_b = 6A, T_C = 25^{\circ}C$
3.4.0	Power	
3.4.1	$P_T = 167W$	<u>JS-6-T12</u> $T_C = 100^{\circ}C, V_{CB} = 175V, I_C = .93A$ Derating Factor - $2.22W/^{\circ}C$
3.4.2	$P_{TM} = I_C V_{CC} = 465W$	<u>JS-6-T13</u> $T_C = 100^{\circ}C, V_{CC} = 155V, V_{BB} = 8V,$ $R_{BB} = 3\Omega, I_C = 30A, \text{Pulse Width} = 100\mu s,$ Duty Cycle = 1%, $t_r \leq 50\mu s,$ $t_f = 50\mu s$
3.5.0	Maximum Operating Conditions	
3.5.1	Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> <u>Test Point:</u> (See 3.4.1)
3.5.2	Pulsed Forward Biased SOAR	<u>JS-6-T14</u> <u>Test Points:</u> $T_C = 100^{\circ}C, V_{BB} = 8V, R_{BB} = 3\Omega$ $t_r \leq 50\mu s, t_f \leq 50\mu s, I_C = 30A,$ Duty Cycle $\leq 1\%, R_S = 0.1\Omega$ 1. For $t_p = 10ms; V_{CC} = 50V$ 2. For $t_p = 1ms: V_{CC} = 90$ 3. For $t_p = 500\mu s: V_{CC} = 120V$ 4. For $t_p = 100\mu s: V_{CC} = 155V$

ItemTest Methods and Test Conditions

3.6.0 SOAR  
Switching between  
Saturation and  
Cutoff

3.6.1 Resistive Load

JS-6-T5-2.1 with L = 0 and CR  
Disconnected

Test Points:

$R_{BB1} = 1\Omega$ ,  $R_{BB2} = 3\Omega$ ,  $V_{BB1} = 14V$ ,

$V_{BB2} = 8V$ ,  $T_C = 100^\circ C$ ,  $t_f \leq 50\mu s$

Coll. Current,  $t_r \leq 50\mu s$  Coll.

Current,  $R_S = 0.1\Omega$ ,  $I_C = 30A$ ,

$V_{CC} = 200V$

3.6.2 Clamped Inductive  
Load

JS-6-T5-2.1

Test Points: (See 3.2.3)

3.6.3 Unclamped Inductive  
Load

JS-6-T5-2.1 and CR disconnected

Test Points:

1.  $V_{BB1} = 14V$       L = 0.2mH\*

$R_{BB1} = 1\Omega$        $R_L = 0.4\Omega$

$V_{BB2} = 8V$        $V_{CC} = 16.5V$

$R_{BB2} = 3\Omega$       f = 60Hz

$R_S = 0.1\Omega$       d = 10%

2.  $V_{BB1} = 7V$       L = 1mH\*\*

$R_{BB1} = 1\Omega$        $R_L = 2.1\Omega$

$V_{BB2} = 8V$        $V_{CC} = 10.5V$

$R_{BB2} = 3\Omega$       f = 60Hz

$R_S = 0.1\Omega$       d = 10%

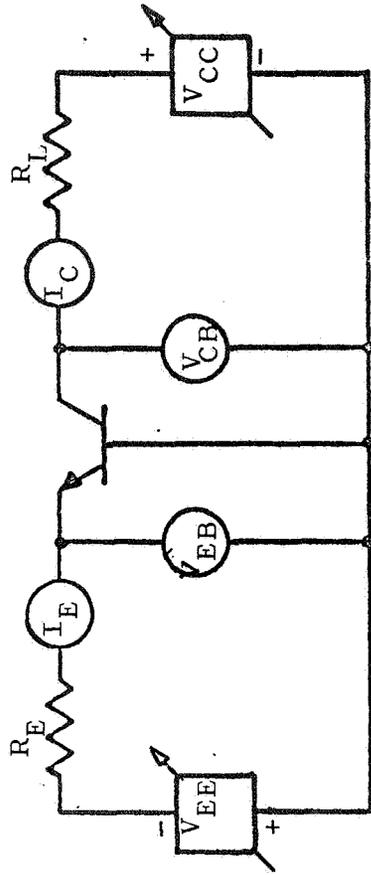
\*Miller No. 7828

\*\*Miller No. 7830 in series with 7871

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.7.0 Shorted Class B SOAR	[See Figure 6] <u>Test Points:</u> $I_{Cpeak} = 5.4A, V_{CC} = 92.5V, R_S = 0.1\Omega$ $R_{BB1} = 1\Omega, R_{BB2} = 3\Omega, f = 20Hz,$ $T_C = 100^\circ C$
4.0.0 <u>Electrical Characterisitics</u>  Maximum limits unless otherwise noted  Technique:  DC - Continuous Operation  C.T. - Curve Tracer  P - 300 $\mu$ s Pulse, 2% Duty Cycle	$T_C = 25^\circ C$ [unless otherwise noted]
4.1.0 Static	
4.1.1 $I_{CEX} = 30mA$	$V_{CEX} = 200V, V_{BE} = -1.5V,$ Technique - C.T., $T_C = 175^\circ C$
4.1.2 $I_{CEO} = 100mA$	$V_{CEO} = 175V,$ Technique - C.T.
4.1.3 $I_{EBO} = 25mA$	$V_{EBO} = 15V, T_C = 175^\circ C$ Technique - C.T.
4.1.4 $V_{CEO} = 185V$ min	<u>JS-6-T5-2.1</u> and CR disconnected $I_C = 5A, R_{BB1} = 3\Omega, V_{BB1} = 3V,$ $R_{BB2} = \infty\Omega, d = 50\%, f = 60Hz,$ $L = 5mH, R_L = 0.1\Omega, R_S = 0.1\Omega$ Adjust $V_{CC}$ for specified $I_C$
4.1.5 $h_{FE} = 10$ min	$V_{CE} = 4V, I_C = 20A$ Technique-C.T.
4.1.6 $V_{CE(sat)} = 1.5V$	$I_C = 20A, I_B = 4A,$ Technique - C.T.
4.1.7 $V_{BE(sat)} = 2.5V$	$I_C = 20A, I_B = 4A,$ Technique - C.T.

<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.2.0	Dynamic	
4.2.1	$t_{on} = 20\mu s$	$V_{CC} = 12V, I_C = 20A, I_{B1} = 5A$
4.2.2	$t_{off} = 25\mu s$	$V_{CC} = 12V, I_C = 20A, I_{B2} = 5A$
4.2.3	$f_{hfe} = 8KHz \text{ min}$ $32KHz \text{ max}$	$I_C = 5A, V_{CE} = 12V$
5.0.0	<u>Thermal</u> <u>Characteristics</u>	
5.1.0	$T_{jmin} = 45ms$	$I_C = 2A, V_{CE} = 10V, T_C = 25^{\circ}C$ MIL-STD-750, Method 3146.1
5.2.0	$\theta_{JC} = 0.45^{\circ}C/W$	$I_C = 2A, V_{CB} = 10V$ MIL-STD-750A, Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

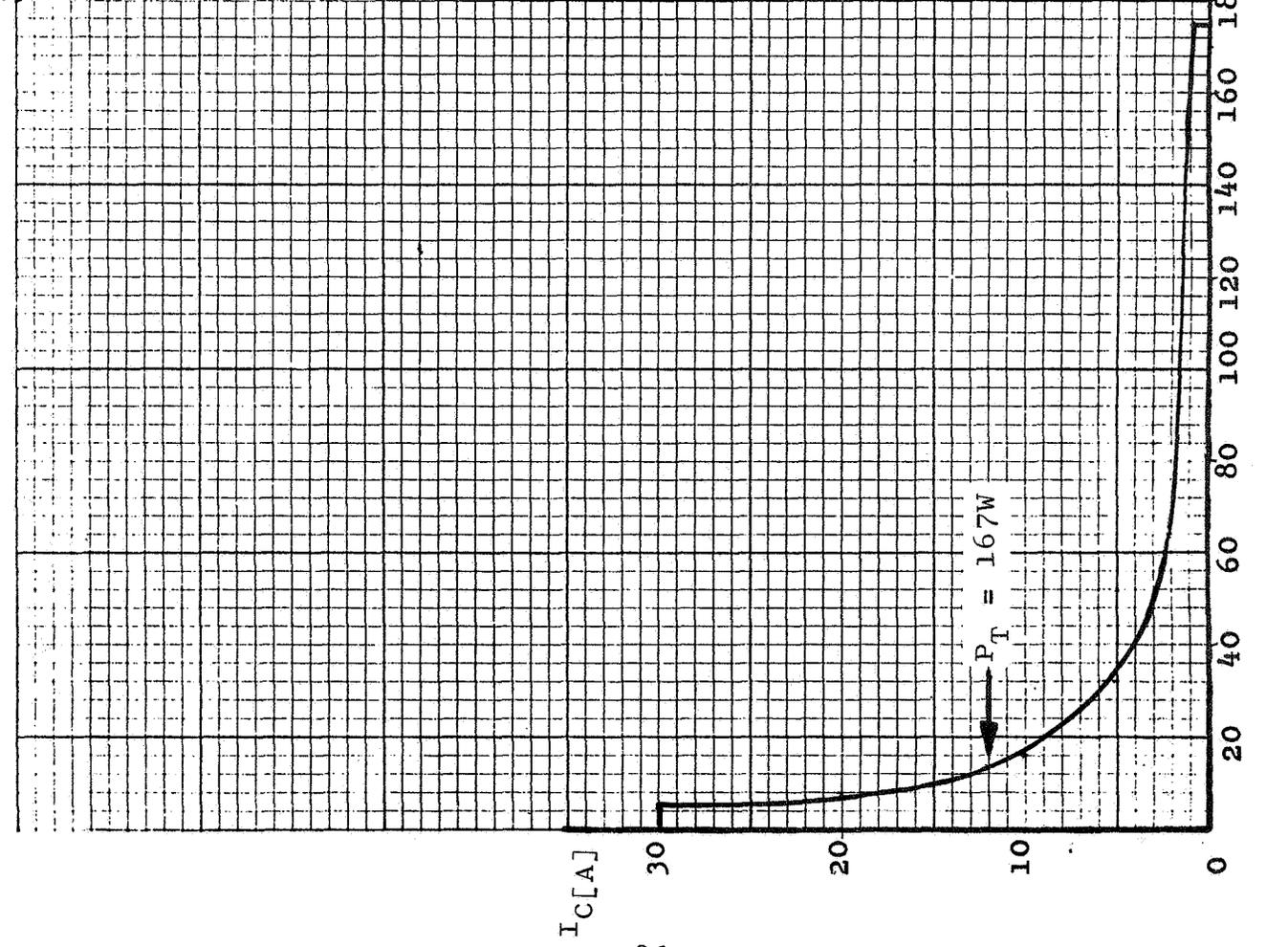
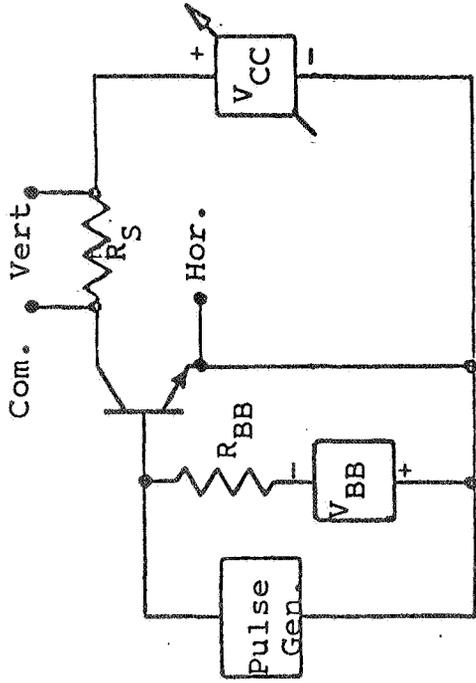


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

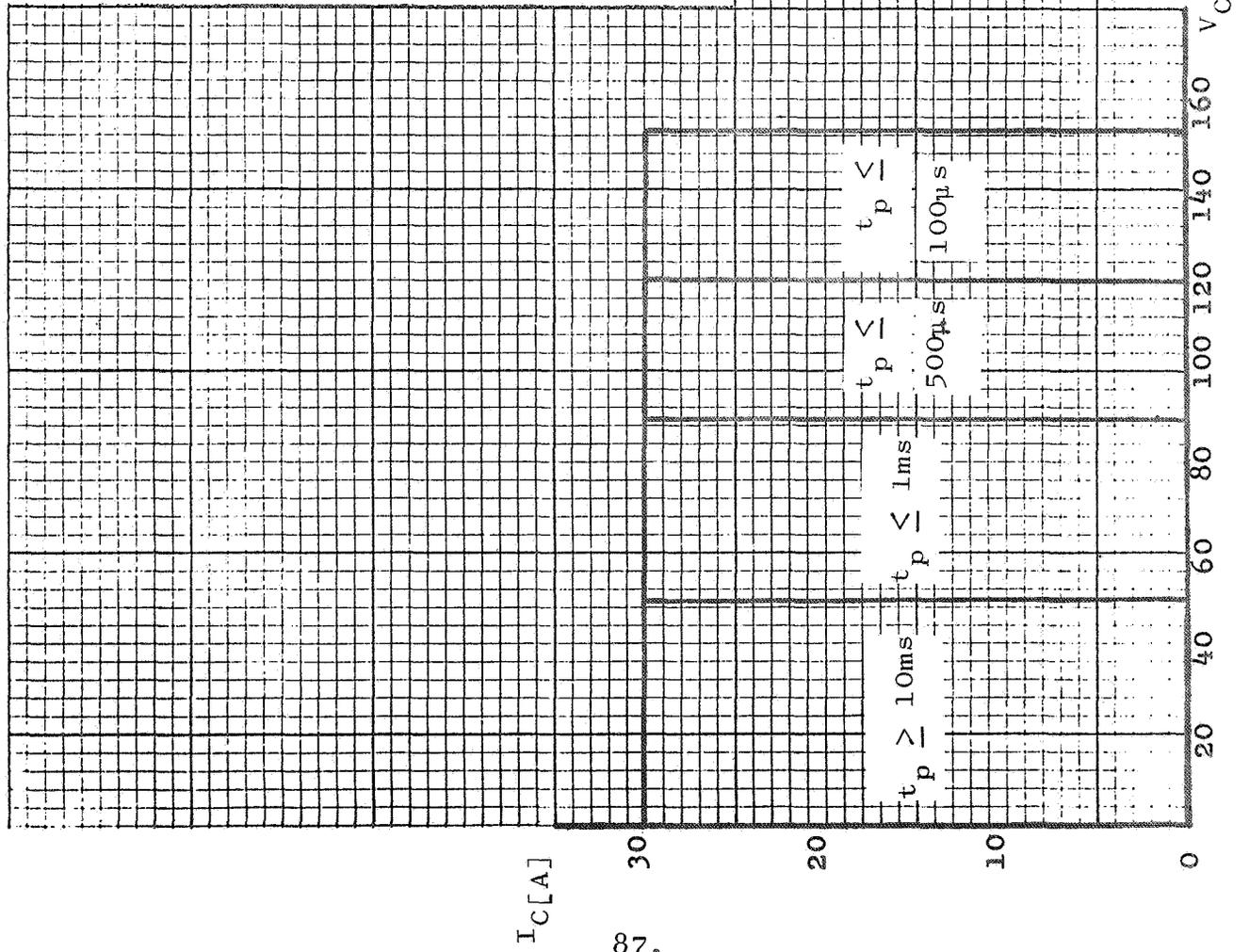
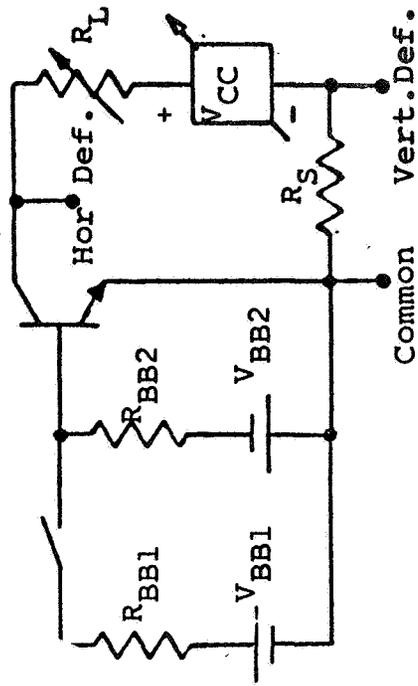


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

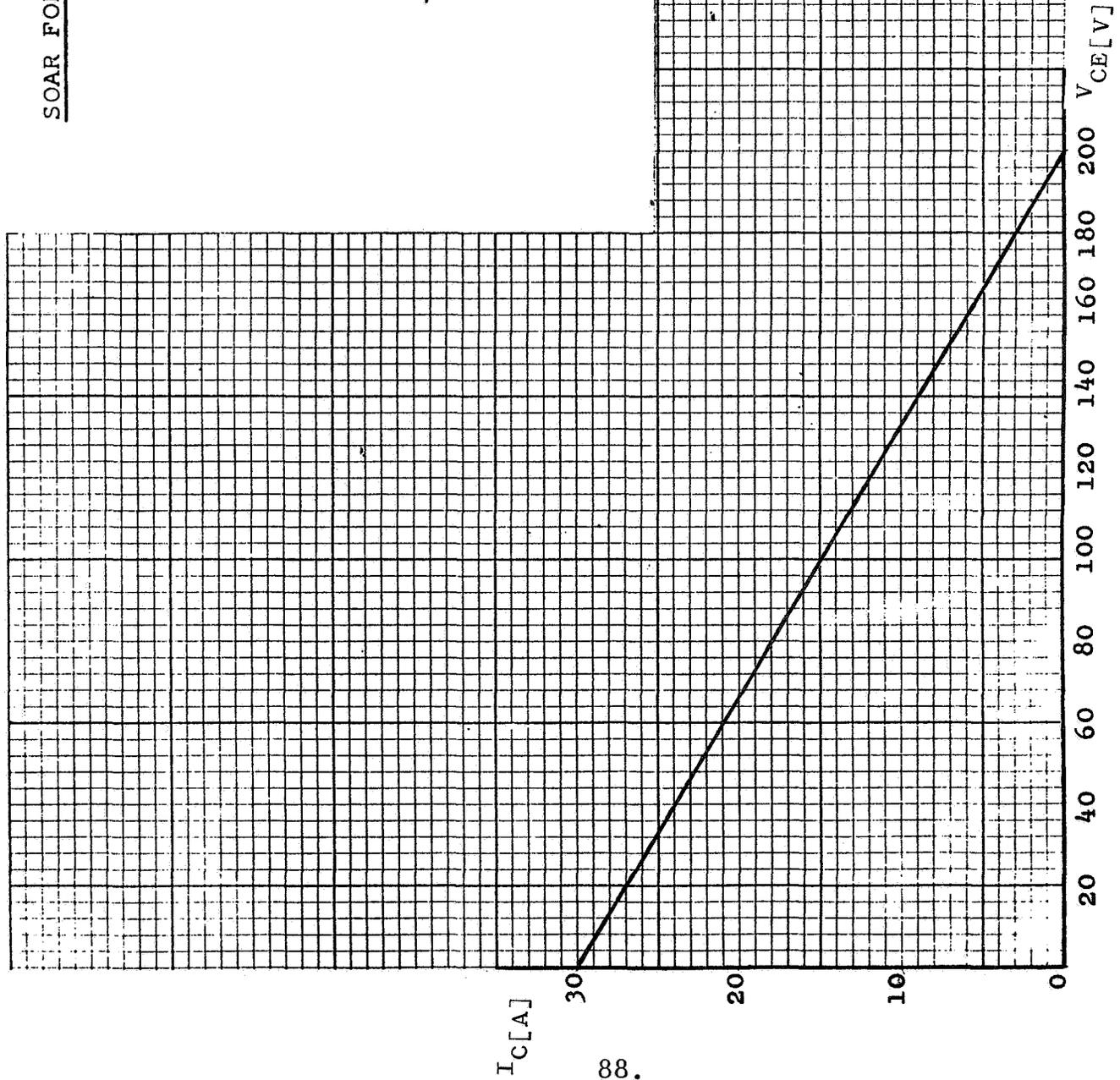
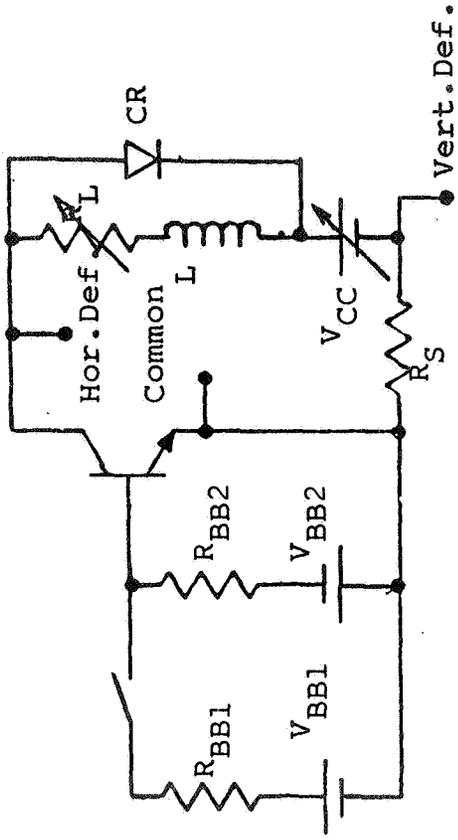


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

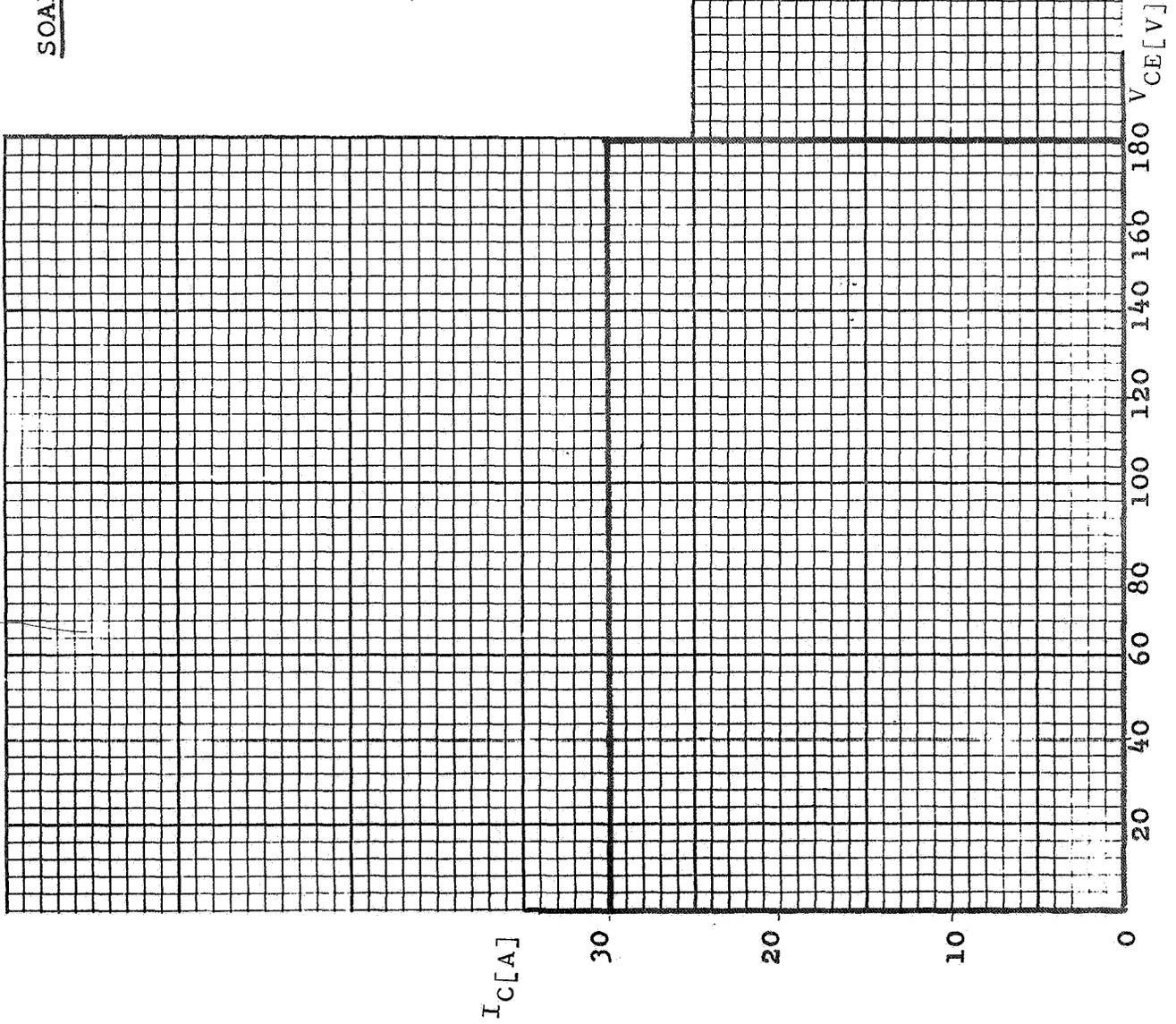
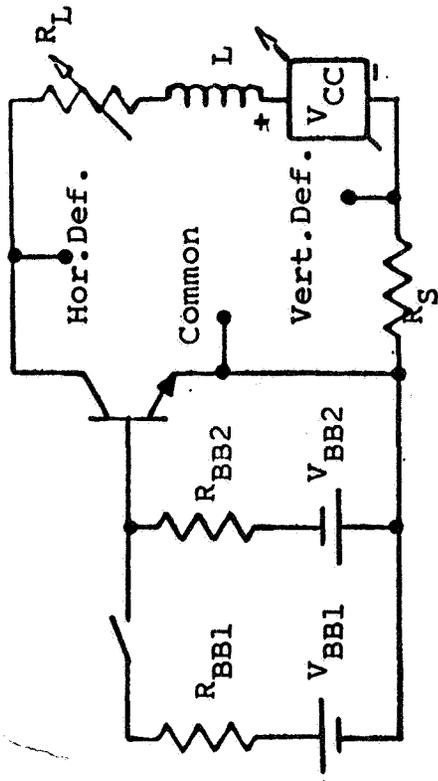


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

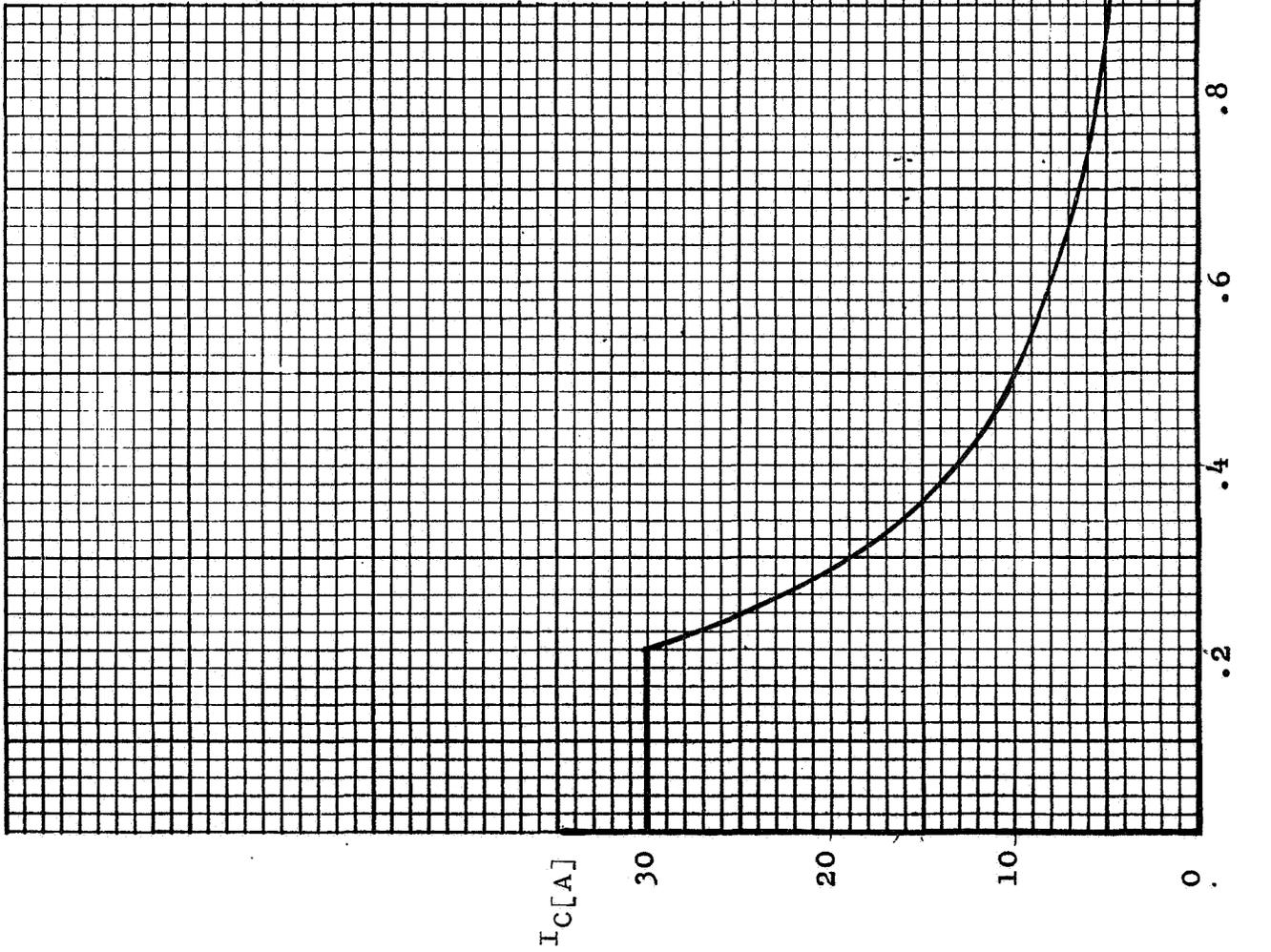


Figure 5

SHORTED CLASS B SOAR

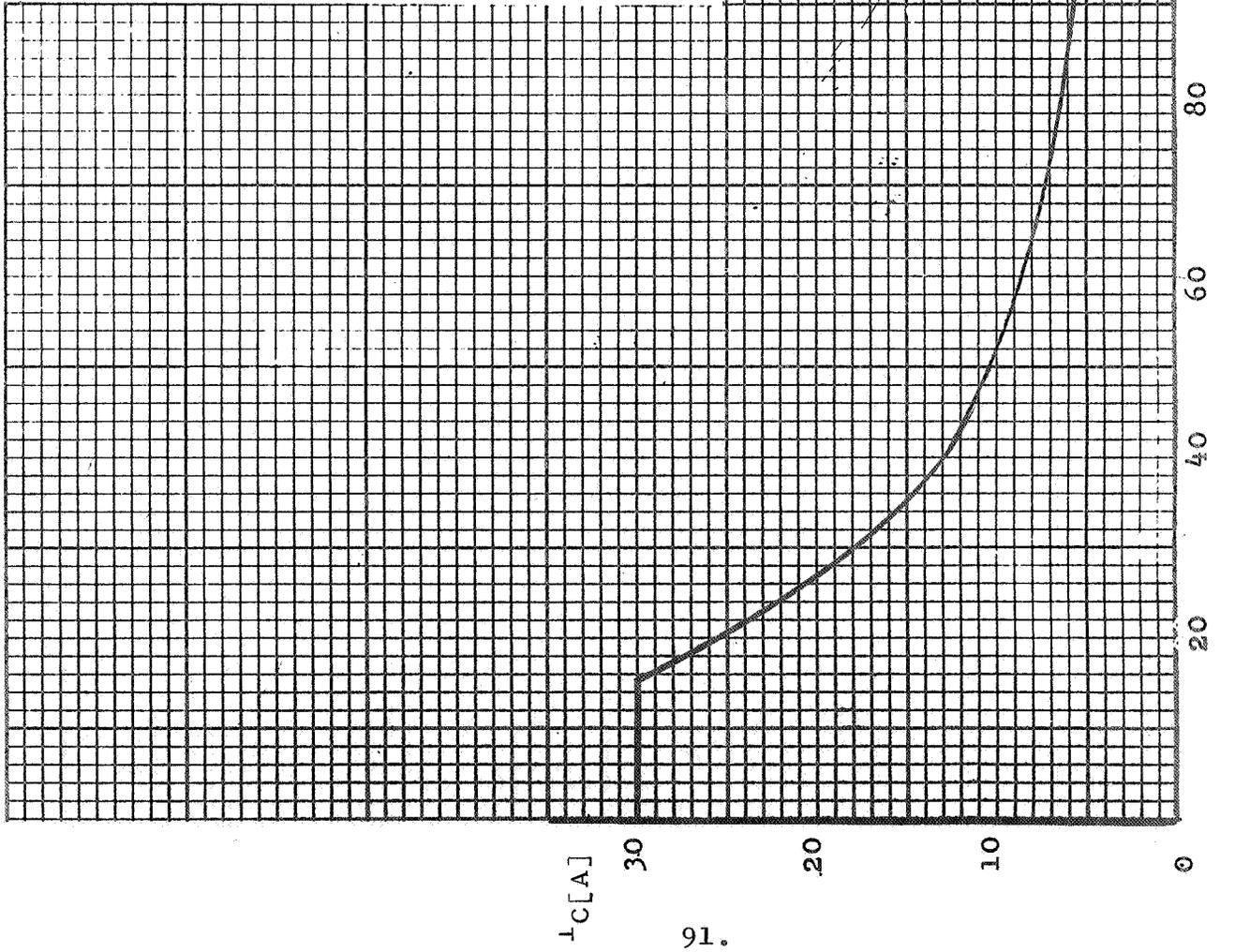
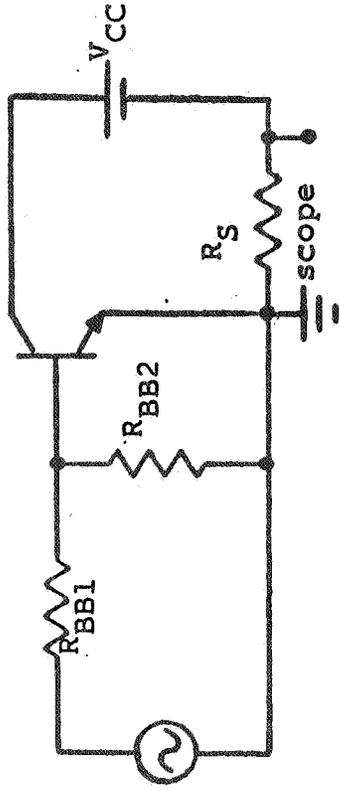


Figure 6

SILICON POWER TRANSISTOR

< Type 2N657A >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer E --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Method and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline - TO-5	
2.2.0	Terminal Designation	
	1 - Emitter	
	2 - Base	
	3 - Collector	
	case - Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = 200^{\circ}C$	<u>JS-6-T1.2</u> [JEDEC publication No. 65 "Test Procedures for Verification of Maximum Ratings of Power Transistors"]
	$T_{STG(min)} = 200^{\circ}C$	
3.1.2	$T_J(max) = 200^{\circ}C$	<u>JS-6-T2</u> $T_C = 100^{\circ}C, V_{CB} = 100V, I_C = 28.6mA$
3.1.3	$T(Lead) = 260^{\circ}C$	Distance from case = 1/16 in.  Time = 10s
3.2.0	Voltage	
3.2.1	$V_{CBO} = 100V$	<u>JS-6-T3</u> or MIL-STD-750A, method 3001.1
3.2.2	$V_{EBO} = 8V$	<u>JS-6-T4</u> of MIL-STD-750A, method 3026.1
3.2.3	$V_{CEX} = 100V$	<u>JS-6-T5</u> $I_C (V_{CE} = V_{CEX}) = 0.5A, V_{CC} = 100V,$ $R_L = 190\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.3 $V_{CEX}$ [cont'd]	$L = 10mH; 0.11\Omega$ (Stancor C-2688), $CR = 1N1204, V_{BB1} = 10.1V, R_{BB1} = 33\Omega$ $V_{BB2} = 6.5V, R_{BB2} = 100\Omega, t_p = 1ms,$ $R_S = 1\Omega, \text{Duty Cycle} = \leq 1\%$
3.3.0 Current	
3.3.1 $I_C = 500mA$	<u>JS-6-T6</u> $I_B = 50mA, T_C = 25^\circ C$
3.2.2 $I_B = 250mA$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3 $I_E = 550mA$	<u>JS-6-T10</u> $I_B = 50mA, T_C = 25^\circ C$
3.4.0 Power	
3.4.1 $P_T = 2.86W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 100V, I_C = 0.5A$ $V_{BB} = 6.5V, R_{BB} = 100\Omega, \text{Pulse Width } 0.5ms$ $\text{Duty Cycle } \leq 1\%, t_r \leq 50\mu s, t_f \leq 50\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> [See Figure 1] $T_C = 100^\circ C$ <u>Test Points:</u> [See 3.1.2]

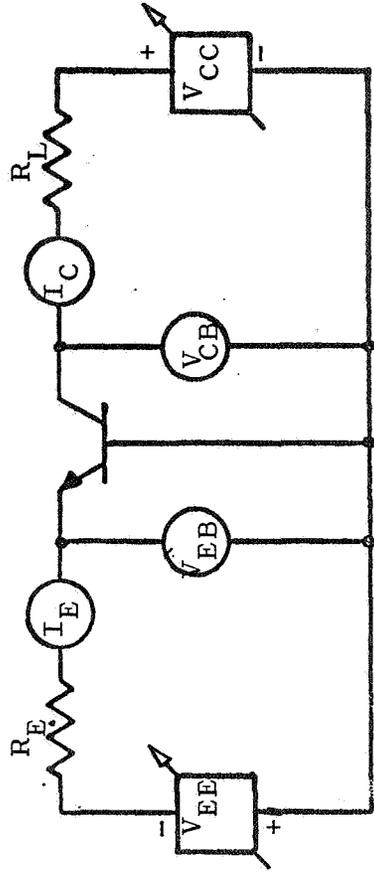
<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.5.2	Pulsed Forward Biased SOAR	<p><u>JS-6-T14</u> [See Figure 2]</p> <p><math>T_C = 100^\circ\text{C}</math>, <math>I_C = 0.5\text{A}</math>, <math>R_S = 0.1\Omega</math></p> <p><math>V_{BB} = 6.5\text{V}</math>, <math>R_{BB} = 100\Omega</math>, <math>t_r \leq 50\mu\text{s}</math>,  <math>t_f \leq 50\mu\text{s}</math>, Duty Cycle <math>\leq 1\%</math></p> <p><u>Test Points:</u></p> <ol style="list-style-type: none"> <li>1. For <math>t_p \leq 5\text{ms}</math>, <math>V_{CC} = 35\text{V}</math></li> <li>2. For <math>t_p \leq 2\text{ms}</math>, <math>V_{CC} = 50\text{V}</math></li> <li>3. For <math>t_p \leq 1\text{ms}</math>, <math>V_{CC} = 65\text{V}</math></li> <li>4. For <math>t_p \leq 0.5\text{ms}</math>, <math>V_{CC} = 100\text{V}</math></li> </ol>
3.6.0	SOAR Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<p><u>JS-6-T2.1</u> with L - 0 and CR disconnected  [See Figure 3]</p> <p><math>T_C = 100^\circ\text{C}</math></p> <p><u>Test Points:</u></p> <p><math>t_r \leq 50\mu\text{s}</math>, <math>t_f \leq 50\mu\text{s}</math>, <math>I_C = 0.5\text{A}</math>,  <math>V_{CC} = 100\text{V}</math>, <math>R_S = 0.1\Omega</math>, <math>R_{BB1} = 33\Omega</math>  <math>R_{BB2} = 100\Omega</math>, <math>V_{BB1} = 10.1\text{V}</math>, <math>V_{BB2} = 6.5\text{V}</math></p>
3.6.2	Clamped Inductive Load	<p><u>JS-6-T5-2.1</u> [See Figure 4]</p> <p><math>T_C = 25^\circ\text{C}</math></p> <p><u>Test Points:</u> [See 3.2.3]</p>
3.6.3	Unclamped Inductive Load	<p><u>JS-6-T5-2.1</u> and CR disconnected  [See Figure 5]</p> <p><math>T_C = 25^\circ\text{C}</math></p>

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.3 Unclamped Inductive Load [cont'd]	$f = 1\text{Hz}$ , Duty Cycle $\leq 5\%$ , $R_S = 0.1\Omega$ $R_{BB1} = 33\Omega$ , $R_{BB2} = 100\Omega$ , $V_{BB1} = 10.1\text{V}$ , $V_{BB2} = 6.5\text{V}$ 1. $L = 50\text{mH}$ ; $0.424\Omega$ [series 2-Stancor C-2686], $I_C = 0.5\text{A}$ , $V_{CC} = 9\text{V}$ , $R_L = 9\Omega$ 2. $I_C = 0.15\text{A}$ , $V_{CC} = 8\text{V}$ , $R_L = 34\Omega$ $L = 600\text{mH}$ ; $6\Omega$ [series 2-TRIAD C-47U]
3.7.0 Shorted Class B SOAR	[See Figure 6] <u>Test Points:</u> $I_{C\text{peak}} = 50\text{mA}$ , $V_{CC} = 80\text{V}$ , $R_S = 1\Omega$ $R_{BB1} = 10\Omega$ , $R_{BB2} = 5\Omega$ , $f \geq 20\text{Hz}$ , $T_C = 100^\circ\text{C}$
4.0.0 <u>Electrical Characteristics</u>	$T_C = 25^\circ\text{C}$ [unless otherwise noted]
Maximum Limits unless otherwise noted	
Technique:	
DC - Continuous Operation	
C.T. - Curve Tracer	
P - $300\mu\text{s}$ Pulse, 2% Duty Cycle	

ItemTest Methods and Test Conditions

4.1.0	Static	
4.1.1	$I_{CEO} = 100\mu A$	$V_{CEO} = 100V$ , Technique - C.T.
4.1.2	$I_{CBO} = 10\mu A$	$V_{CBO} = 30V$ , Technique - C.T.
4.1.3	$I_{CBO} = 250\mu A$	$V_{CBO} = 30V$ , $T_C = 150^\circ C$ Technique - C.T.
4.1.4	$V_{(BR)CEO} = 100V$	$I_C = 10mA$ , Technique - C.T.
4.1.5	$V_{CBO} = 100V$	$I_C = 100\mu A$ , Technique - C.T.
4.1.6	$V_{EBO} = 8V$	$I_E = 250\mu A$ , Technique - C.T.
4.1.7	$h_{FE} = 30$ min 90 max	$V_{CE} = 10V$ , $I_C = 200mA$ Technique = C.T.
4.1.8	$h_{FE} = 20$ min	$V_{CE} = 10V$ , $I_C = 0.5A$ , Technique - P
4.1.9	$V_{CE(sat)} = 2V$	$I_C = 200mA$ , $I_B = 40mA$ , Technique - C.T.
4.1.10	$V_{CE(sat)} = 4V$	$I_C = 0.5A$ , $I_B = 0.1A$ , Technique - C.T.
4.1.11	$V_{BE(sat)} = 3.5V$	$I_C = 0.5A$ , $I_B = 0.1A$ , Technique - C.T.
4.1.12	$h_{1E} = 200ohms$	$V_{CE} = 10V$ , $I_B = 8mA$ , Technique - P
4.2.0	Dynamic	
4.2.1	$f_{hfe} = 50KHz$ (min) 200KHz(max)	$I_C = 50mA$ , $V_{CE} = 10V$
5.0.0	Thermal Characteristics	
5.1.0	$\tau_{J(min)} = 250ms$	$I_C = 0.2A$ , $V_{CE} = 5V$ , $T_C = 25^\circ C$ ; MIL-STD-750 Method 3146.1
5.2.0	$\theta_{J-C(max)} = 35^\circ C/W$	$I_C = 0.2A$ , $V_{CE} = 5V$ , $T_C = 25^\circ C$ ; MIL-STD-750 Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

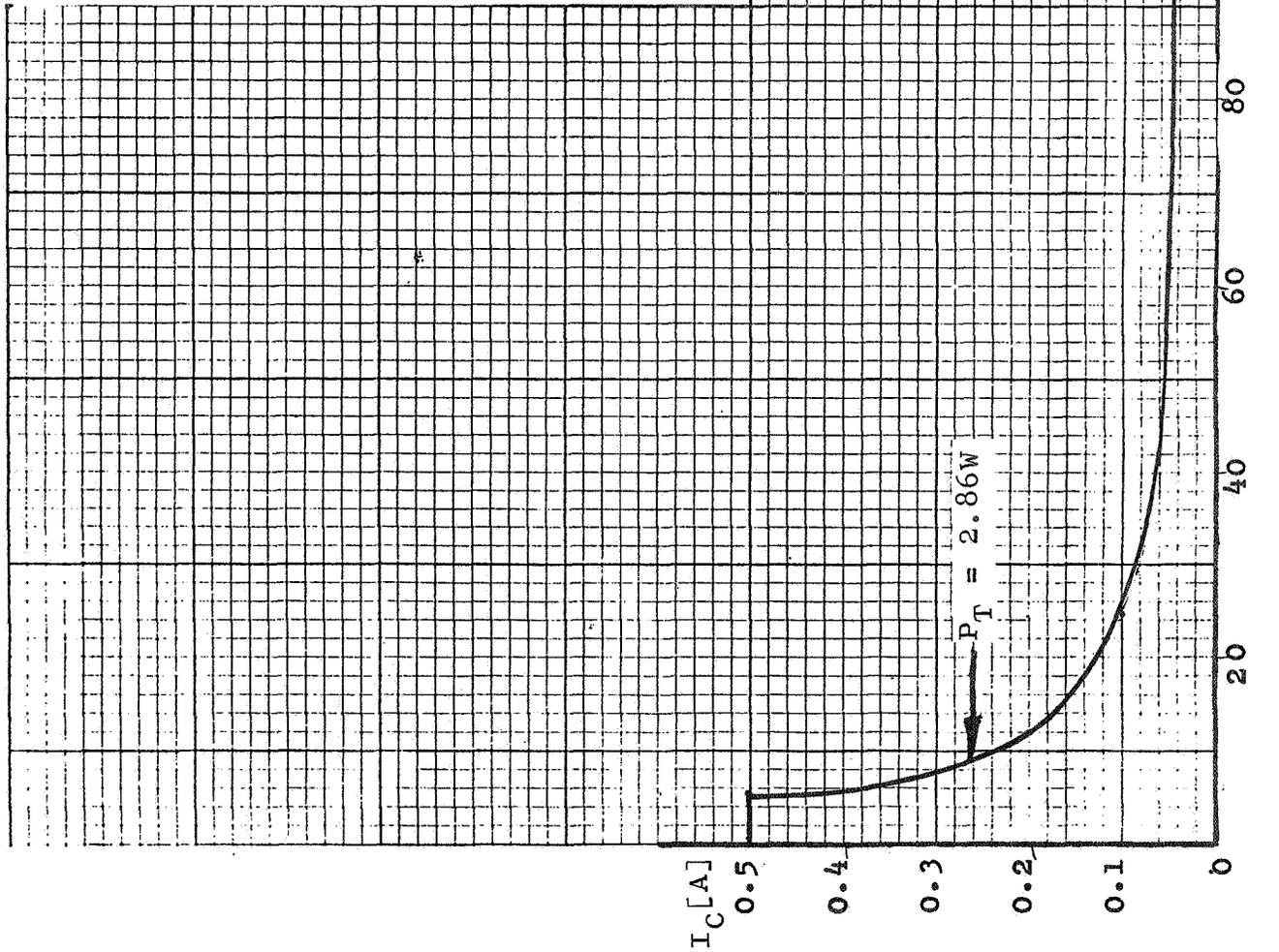
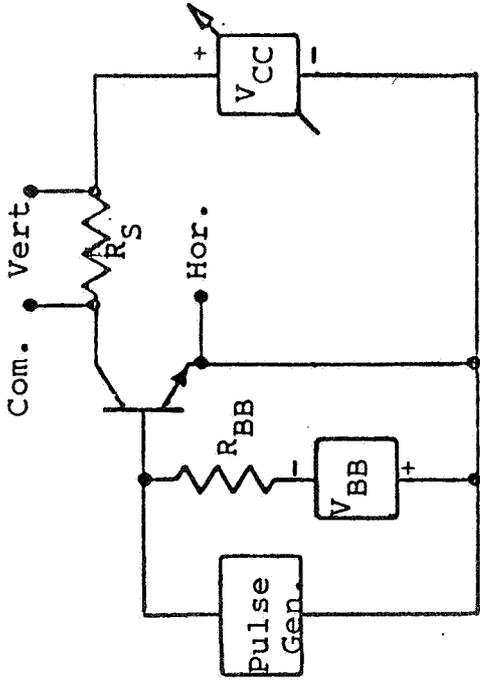


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

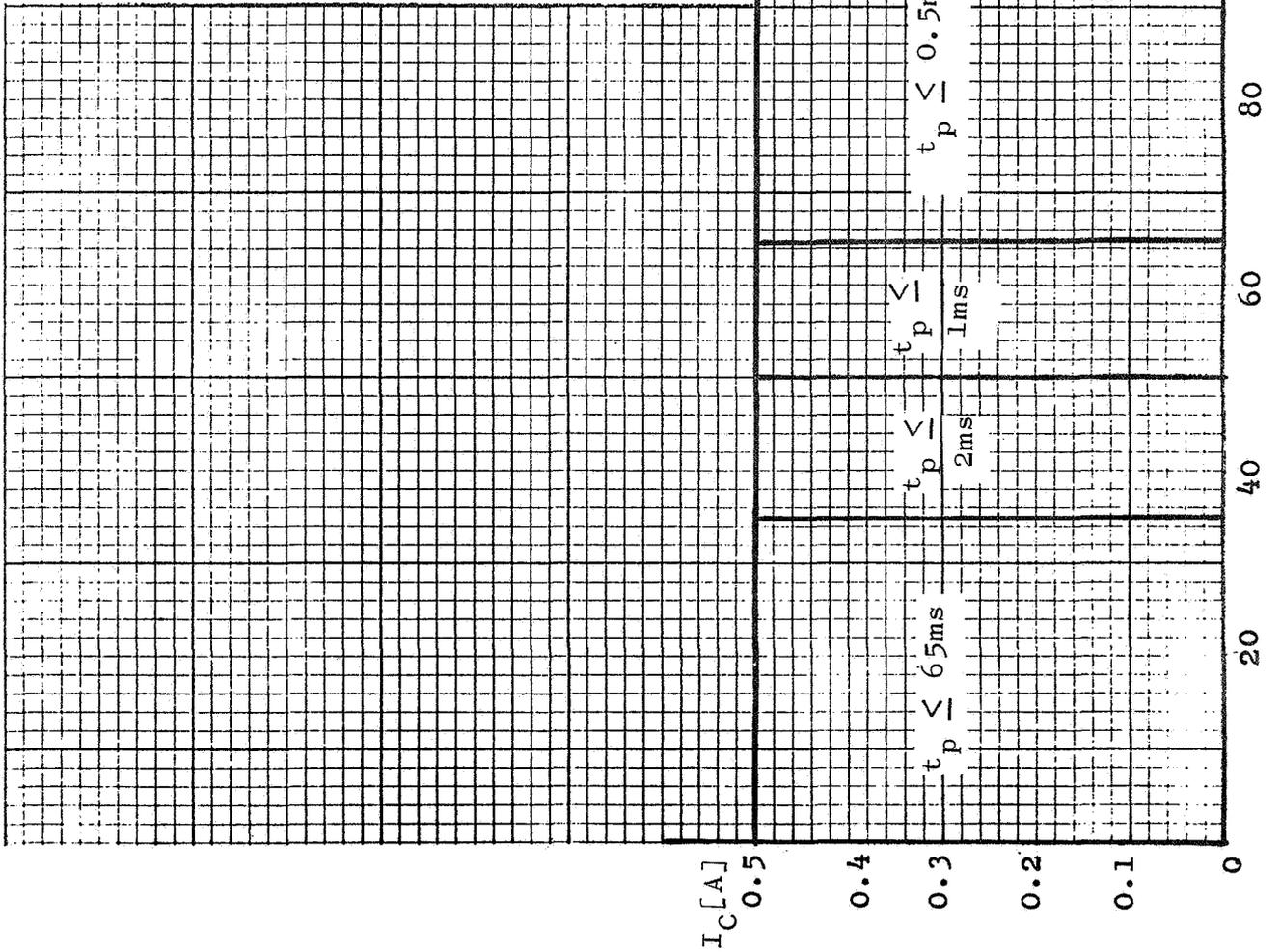
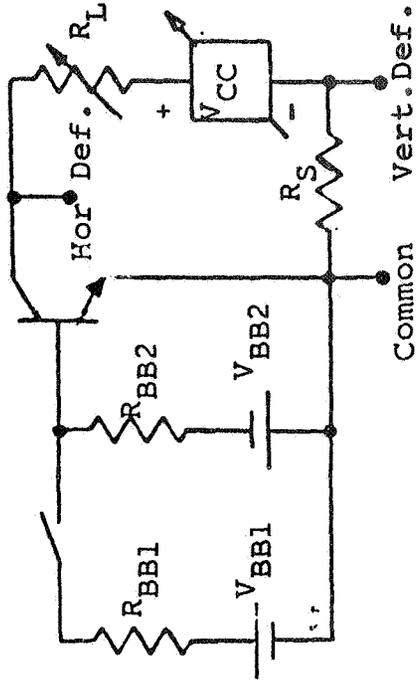


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

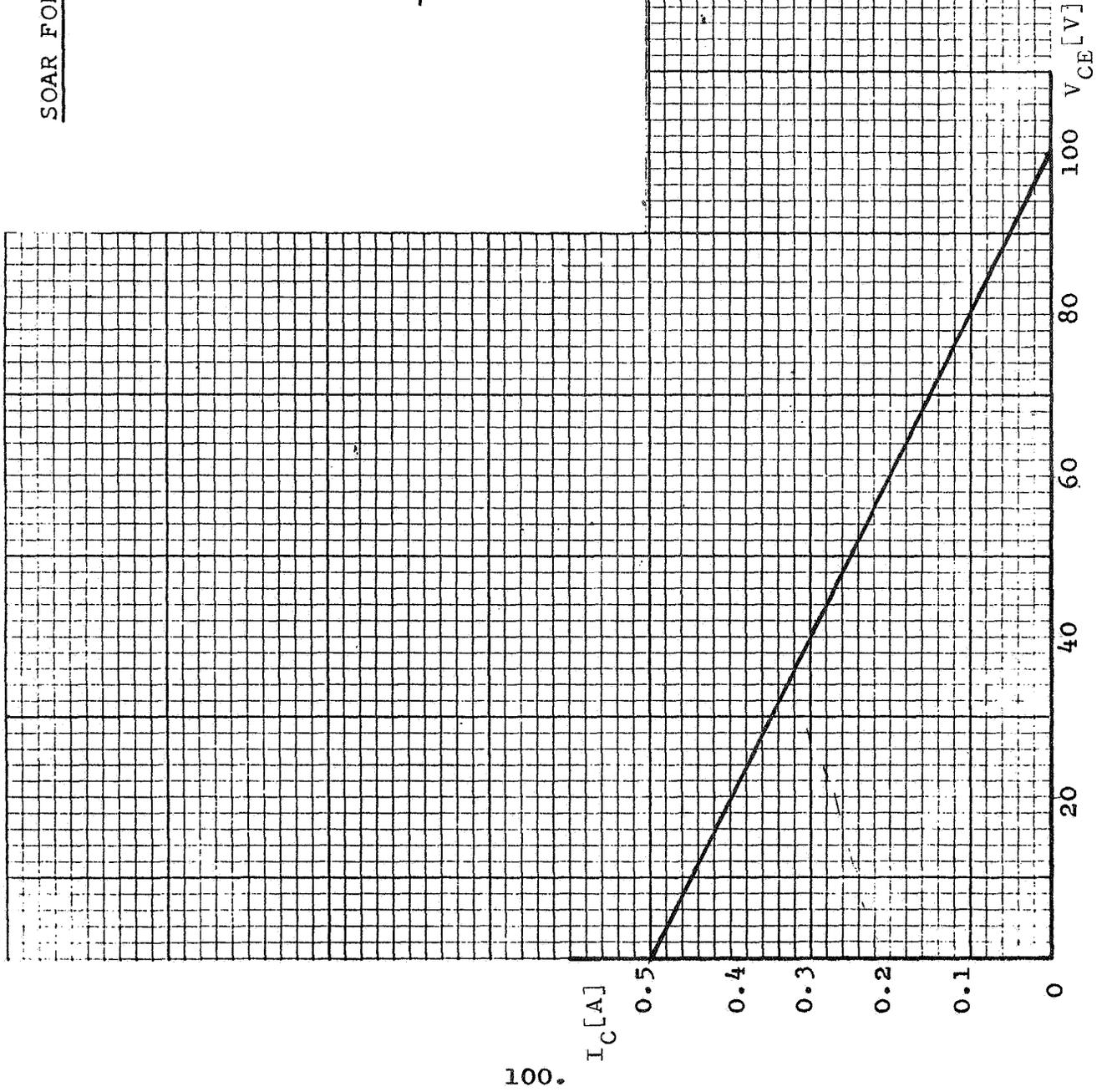
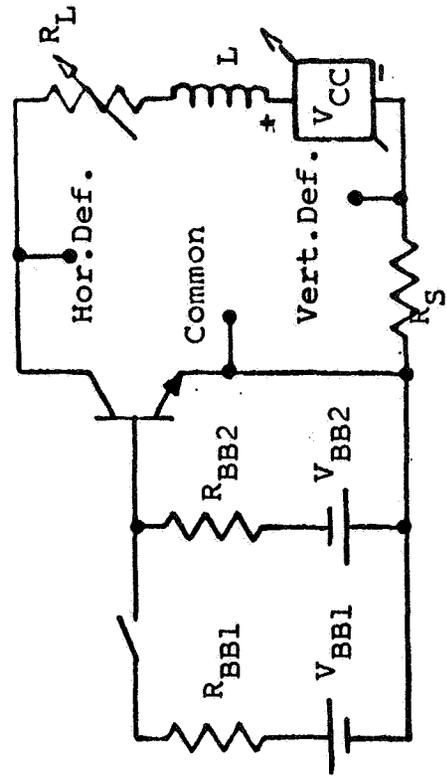


Figure 3



SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

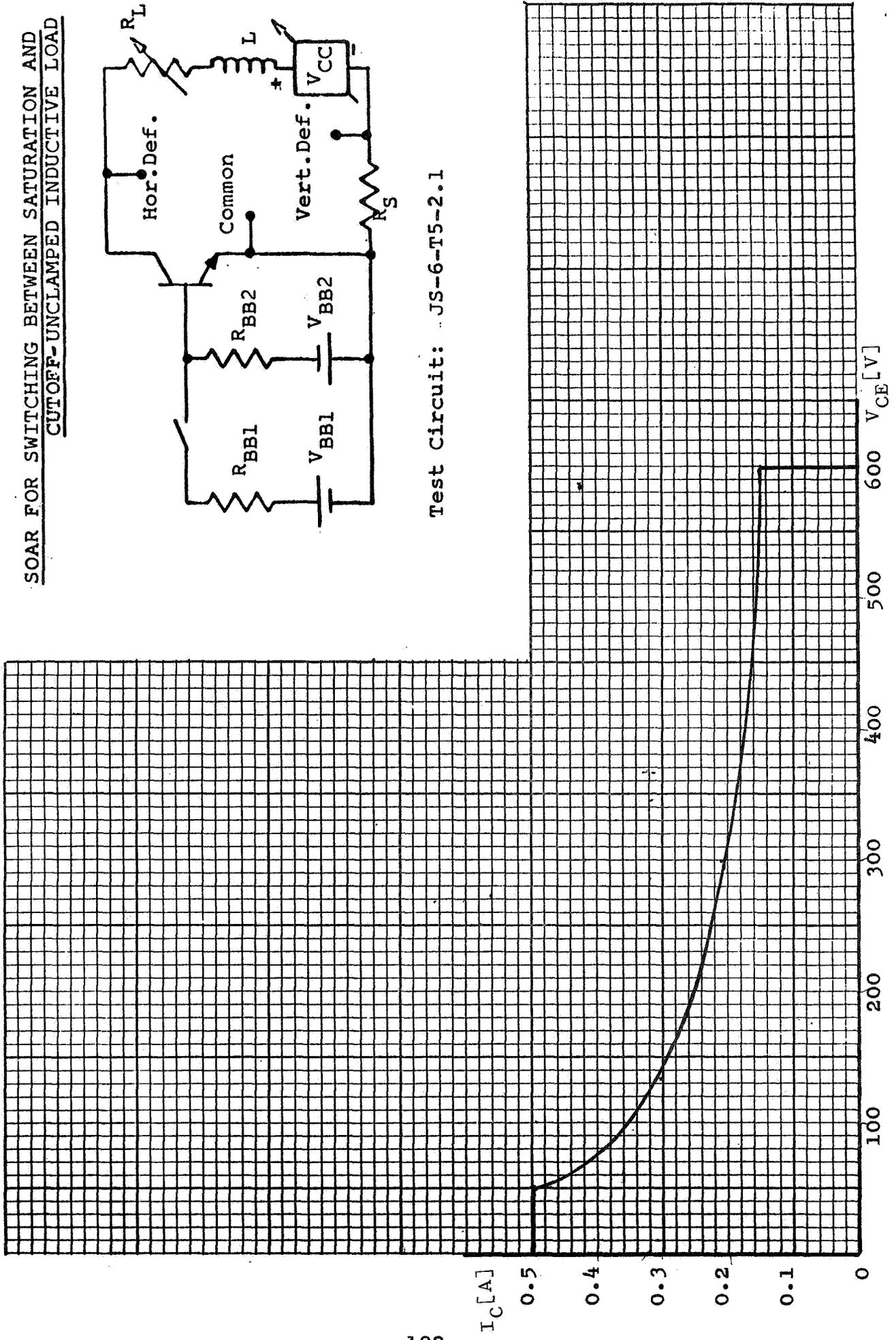


Figure 5

SHORTED CLASS B SOAR

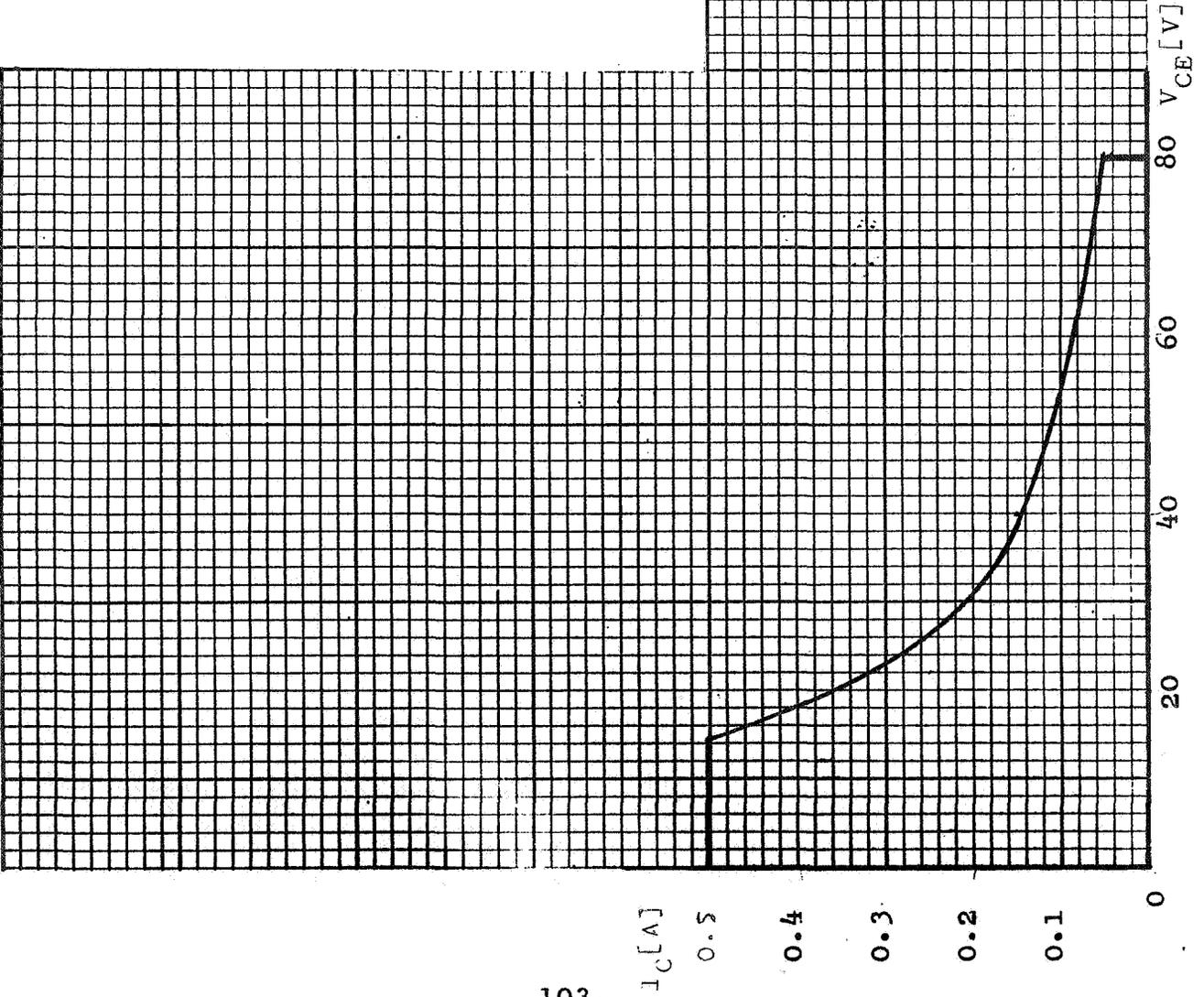
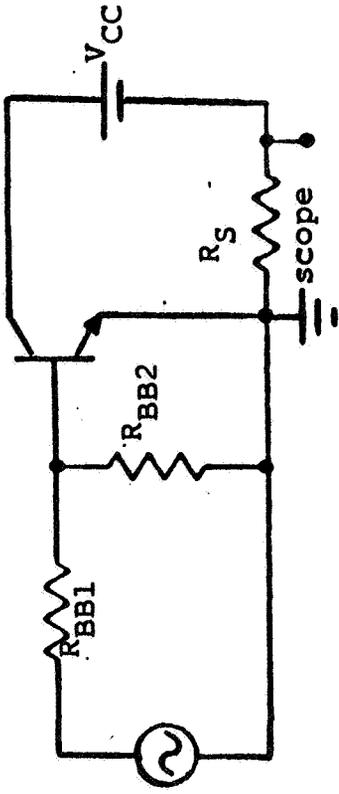


Figure 6

SILICON POWER TRANSISTOR

< Type 2N697 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufactuers E & G --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline - TO-5	
2.2.0	Terminal Designation	
	1 --	Emitter
	2 --	Base
	3 --	Collector
	case --	Collector
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(min)} = -65^{\circ}C$	<u>JS-6-T1.1</u> [JEDEC Publication No. 65
	$T_{STG(max)} = 300^{\circ}C$	<u>JS-6-T1.2</u> "Test Procedures for
		Verification of Maximum
		Ratings of Power Transistors"]
3.1.2	$T_J = 175^{\circ}C$	<u>JS-6-T2</u>
		$T_C = 100^{\circ}C, V_{CB} = 40V, I_C = 0.025A$
3.1.3	$T(Lead) = 260^{\circ}C$	Distance from case = 1/16 in
		Time 10s
3.2.0	Voltage	
3.2.1	$V_{CBO} = 60V$	<u>JS-6-T3</u> or MIL-STD-750A, Method 3001.1
3.2.2	$V_{EBO} = 5V$	<u>JS-6-T4</u> or MIL-STD-750A, Method 3026.1
3.2.3	$V_{CEX} = 40V$	<u>JS-6-T5</u>
		$I_C(V_{CC} = V_{CEX}) = 0.5A, V_{CC} = 40V,$
		$R_L = 72\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.3	$V_{CEX}$ [cont'd] $L = 10\text{mH} / 0.11\Omega$ , [Stancor C-2699] $CR = 1N1204$ , $V_{BB1} = 8.5\text{V}$ , $R_{BB1} = 30\Omega$ $V_{BB2} = 4\text{V}$ , $R_{BB2} = 65\Omega$ , Duty Cycle = $\leq 1\%$
3.3.0	Current
3.3.1	$I_C = 0.5\text{A}$ <u>JS-6-T6</u> $I_B = 0.05\text{A}$ , $T_C = 25^\circ\text{C}$
3.3.2	$I_B = 0.1\text{A}$ <u>JS-6-T8</u> $T_C = 25^\circ\text{C}$
3.3.3	$I_E = 0.55\text{A}$ <u>JS-6-T10</u> $I_B = 0.05\text{A}$ , $T_C = 25^\circ\text{C}$
3.4.0	Power
3.4.1	$P_T = 1\text{W}$ <u>JS-6-T12</u> $T_C = 100^\circ\text{C}$ , $V_{CB} = 40\text{V}$ , $I_C = 0.025\text{A}$ Derating Factor = $13.3\text{mW}/^\circ\text{C}$
3.4.2	$P_{TM} = 20\text{W}$ <u>JS-6-T13</u> $T_C = 100^\circ\text{C}$ , $V_{CC} = 40\text{V}$ , $I_C = 0.5\text{A}$ , $V_{BB} = 4\text{V}$ , $R_{BB} = 65\Omega$ , Pulse Width = $0.1\text{m}$ Duty Cycle $\leq 1\%$ , $t_r \leq 50\mu\text{s}$ , $t_f \leq 50\mu\text{s}$
3.5.0	Maximum Operating Conditions
3.5.1	Forward Biased Continuous DC SQAR <u>JS-6-T12</u> [See Figure 1]

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.1 Forward Biased Continuous DC SOAR [cont'd]	$T_C = 100^\circ\text{C}$ <u>Test Point:</u> [See 3.4.1]
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14</u> [See Figure 2] <u>Test Point:</u> $T_C = 100^\circ\text{C}$ , $I_C = 0.5\text{A}$ , $R_S = 1\Omega$ $V_{BB} = 4\text{V}$ , $R_{BB} = 65\Omega$ , $t_r \leq 50\mu\text{s}$ , $t_f \leq 50\mu\text{s}$ , Duty Cycle $\leq 1\%$ 1. For $t_p = 10\text{ms}$ ; $V_{CC} = 10\text{V}$ 2. For $t_p = 1\text{ms}$ ; $V_{CC} = 18\text{V}$ 3. For $t_p = 0.5\text{ms}$ ; $V_{CC} = 30\text{V}$ 4. For $t_p = 0.1\text{ms}$ ; $V_{CC} = 40\text{V}$
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<u>JS-6-T5-2.1</u> with L - 0 and CR disconnected [See Figure 3] $T_C = 100^\circ\text{C}$ <u>Test Point:</u> $V_{CC} = 60\text{V}$ , $I_C = 0.5\text{A}$ , $t_r \leq 50\mu\text{s}$ , $t_f \leq 50\mu\text{s}$ , $R_{BB1} = 30\Omega$ , $R_{BB2} = 65\Omega$ , $V_{BB1} = 8.5\text{V}$ , $V_{BB2} = 4\text{V}$
3.6.2 Clamped Inductive Load	<u>JS-6-T5-2.1</u> [See Figure 4] $T_C = 25^\circ\text{C}$ <u>Test Point:</u> [See 3.2.3]

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.3 Unclamped Inductive Load	<p><u>JS-6-T5-2.1</u> and CR disconnected [See Figure 5]</p> <p><math>T_C = 25^{\circ}\text{C}</math></p> <p><u>Test Point:</u></p> <p><math>f = 60\text{Hz}</math>, Duty Cycle <math>\leq 1\%</math>  <math>R_S = 1\Omega</math>, <math>t_r \leq 50\mu\text{s}</math>, <math>t_f \leq 50\mu\text{s}</math></p> <p>1. <math>R_{BB1} = 30\Omega</math>, <math>R_{BB2} = 65\Omega</math>,  <math>V_{BB1} = 8.5\text{V}</math>, <math>V_{BB2} = 4\text{V}</math>,  <math>L = 10\text{mH} / 0.11\Omega</math>, (Stancor C-2688)</p> <p>2. <math>R_{BB1} = 120\Omega</math>, <math>R_{BB2} = 150\Omega</math>,  <math>V_{BB1} = 5\text{V}</math>, <math>V_{BB2} = 2\text{V}</math>, <math>I_C = 0.1\text{A}</math>,  <math>V_{CC} = 14\text{V}</math>, <math>R_L = 125\Omega</math>, <math>L = 100\text{mH} /</math>  <math>1.175\Omega</math>, (Series Stancor C-2688 and  TRIAD C-47u)</p>
3.7.0 Shorted Class B SOAR	<p>[See Figure 6]</p> <p><u>Test Points:</u></p> <p><math>I_C \text{ peak} = 0.05\text{A}</math>, <math>V_{CC} = 40\text{V}</math>,  <math>R_S = 10\Omega</math>, <math>R_{BB1} = 10\Omega</math>; <math>R_{BB2} = 27\Omega</math>;  <math>f = 20\text{Hz}</math>, <math>T_C = 100^{\circ}\text{C}</math></p>
4.0.0 <u>Electrical Characteristics</u>	<p><math>T_C = 25^{\circ}\text{C}</math> [unless otherwise noted]</p>
Maximum Limits unless otherwise noted	

ItemTest Methods and Test Conditions4.0.0 Electrical  
Characteristics [Cont'd]

Technique:

DC - Continuous Operation

C.T. - Curve Tracer

P - 300 $\mu$ s Pulse, 2% Duty Cycle

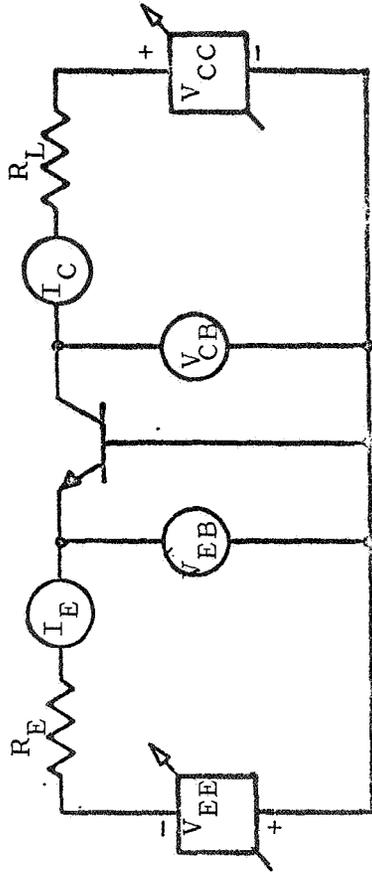
## 4.1.0 Static

- |        |                              |   |
|--------|------------------------------|---|
| 4.1.1  | $I_{CEO} = 10\mu A$          | $V_{CEO} = 40V$ Technique - C.T.                    |
| 4.1.2  | $I_{CBO} = 1\mu A$           | $V_{CBO} = 30V$ Technique - C.T.                    |
| 4.1.3  | $I_{CBO} = 100\mu A$         | $V_{CBO} = 30V, T_C = 150^\circ C$ , Technique-C.T. |
| 4.1.4  | $V_{CBO} = 60V$              | $I_C = 100\mu A$ Technique - C.T.                   |
| 4.1.5  | $V_{CER} = 40 V$             | $I_C = 100\mu A, R_B \leq 10\Omega$ Technique-C.T.  |
| 4.1.6  | $V_{EBO} = 5V$               | $I_E = 100\mu A$ Technique - C.T.                   |
| 4.1.7  | $V_{(BR)CEO} = 30V$ min      | $I_C = 0.05A$ Technique - C.T.                      |
| 4.1.8  | $h_{FE} = 40$ min<br>120 max | $V_{CE} = 10V, I_C = 0.15A$<br>Technique - P        |
| 4.1.9  | $h_{FE} = 25$ min            | $V_{CE} = 10V, I_C = 0.5A$ Technique - P            |
| 4.1.10 | $V_{CE(sat)} = 1.5V$         | $I_C = 0.15A, I_B = 0.015A$ ,<br>Technique - C.T.   |
| 4.1.11 | $V_{CE(sat)} = 4V$           | $I_C = 0.5A, I_B = 0.1A$ Technique - P              |
| 4.1.12 | $V_{BE(sat)} = 1.3V$         | $I_C = 0.15A, I_B = 0.015A$<br>Technique - C.T.     |
| 4.1.13 | $V_{BE(sat)} = 2.5V$         | $I_C = 0.5A, I_B = 0.1A$ Technique - P              |

## 4.2.0 Dynamic

<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.2.1	$f_T = 50\text{MHz min}$ $160\text{MHz max}$	$I_C = 0.05\text{A}, V_{CE} = 10\text{V}$ $f = 20\text{MHz}$
4.2.2	$C_{obo} = 35\text{pF}$	$V_{CB} = 10\text{V}, f = 1\text{MHz}$
5.0.0	Thermal Characteristics	
5.1.0	$J(\text{min}) = 70\text{ms}$	$I_C = 0.4\text{A}, V_{CE} = 5\text{V}, \text{MIL-STD-750}$ Method 3146.1
5.2.0	$\Theta_{J-C(\text{max})} = 75^\circ\text{C/W}$	$I_C = 0.4\text{A}, V_{CE} = 5\text{V}, T_C = 20^\circ\text{C}$ MIL-STD-750 Method 3136
5.3.0	$\Theta_{J-A(\text{max})} = 250^\circ\text{C/W}$	

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ C$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

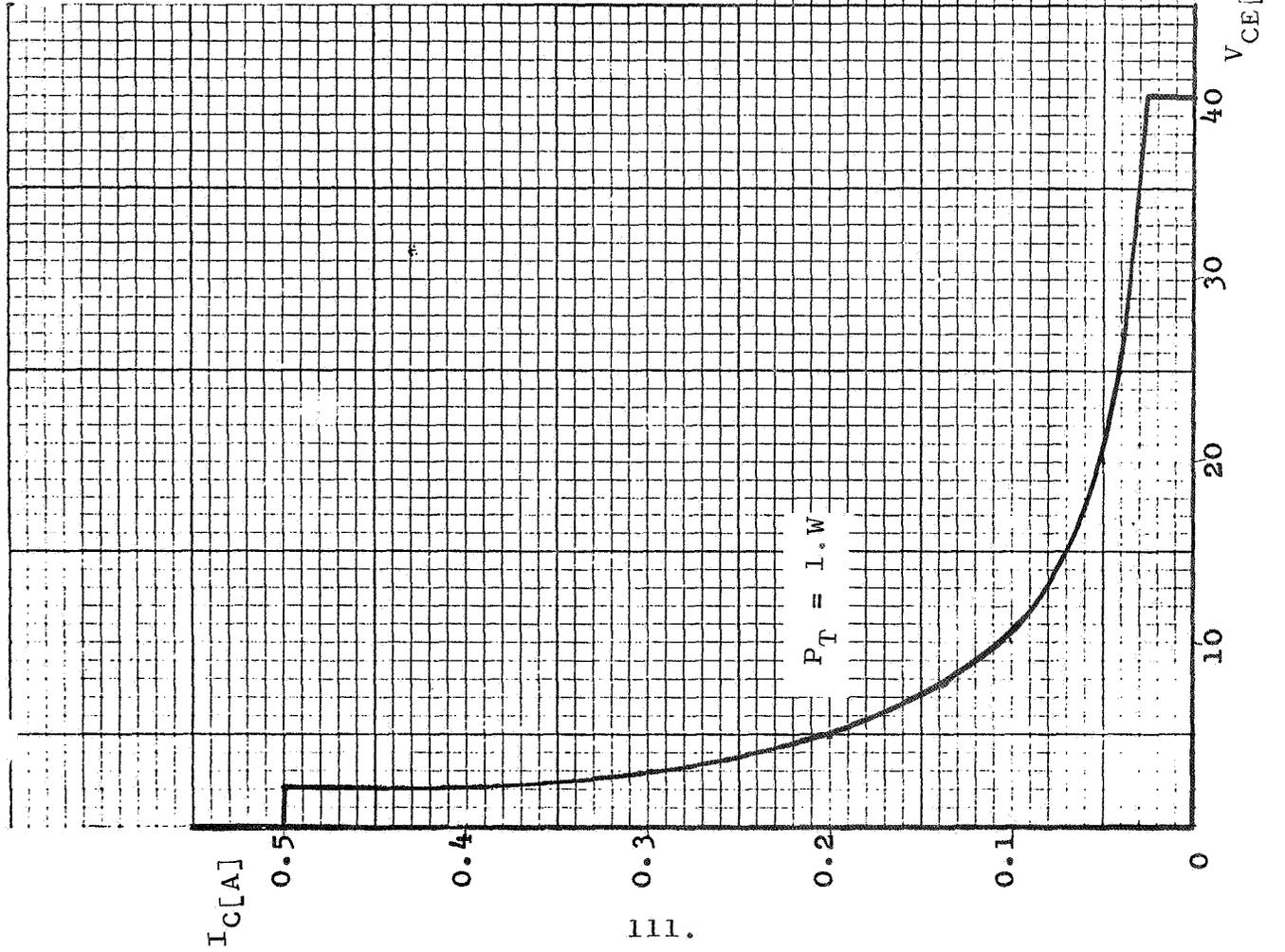
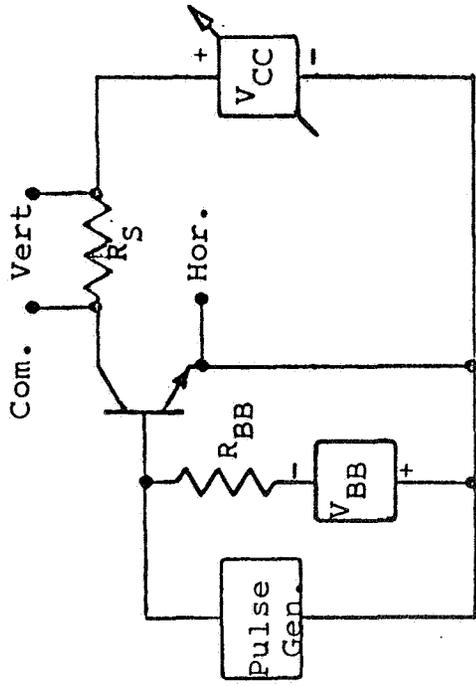


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

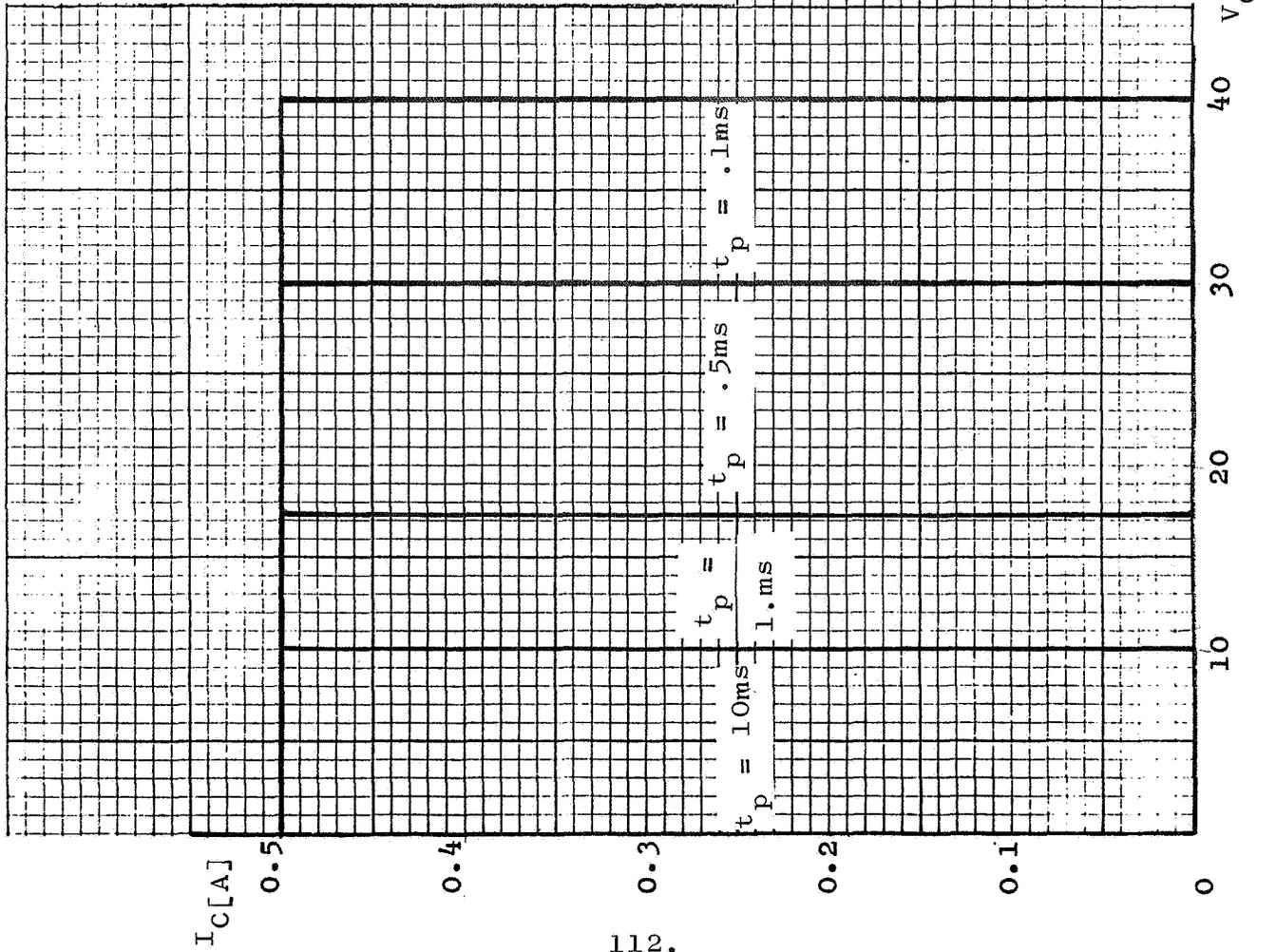
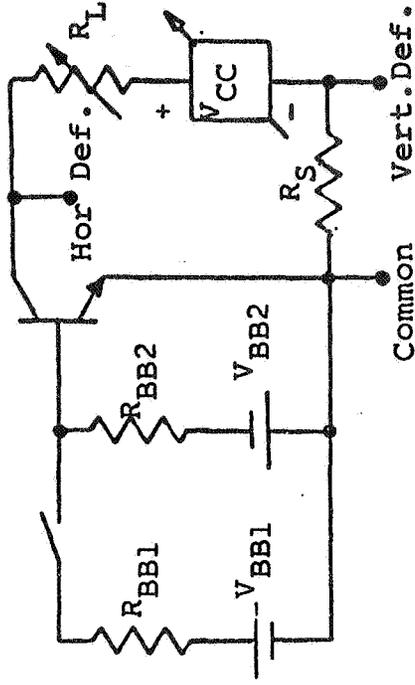
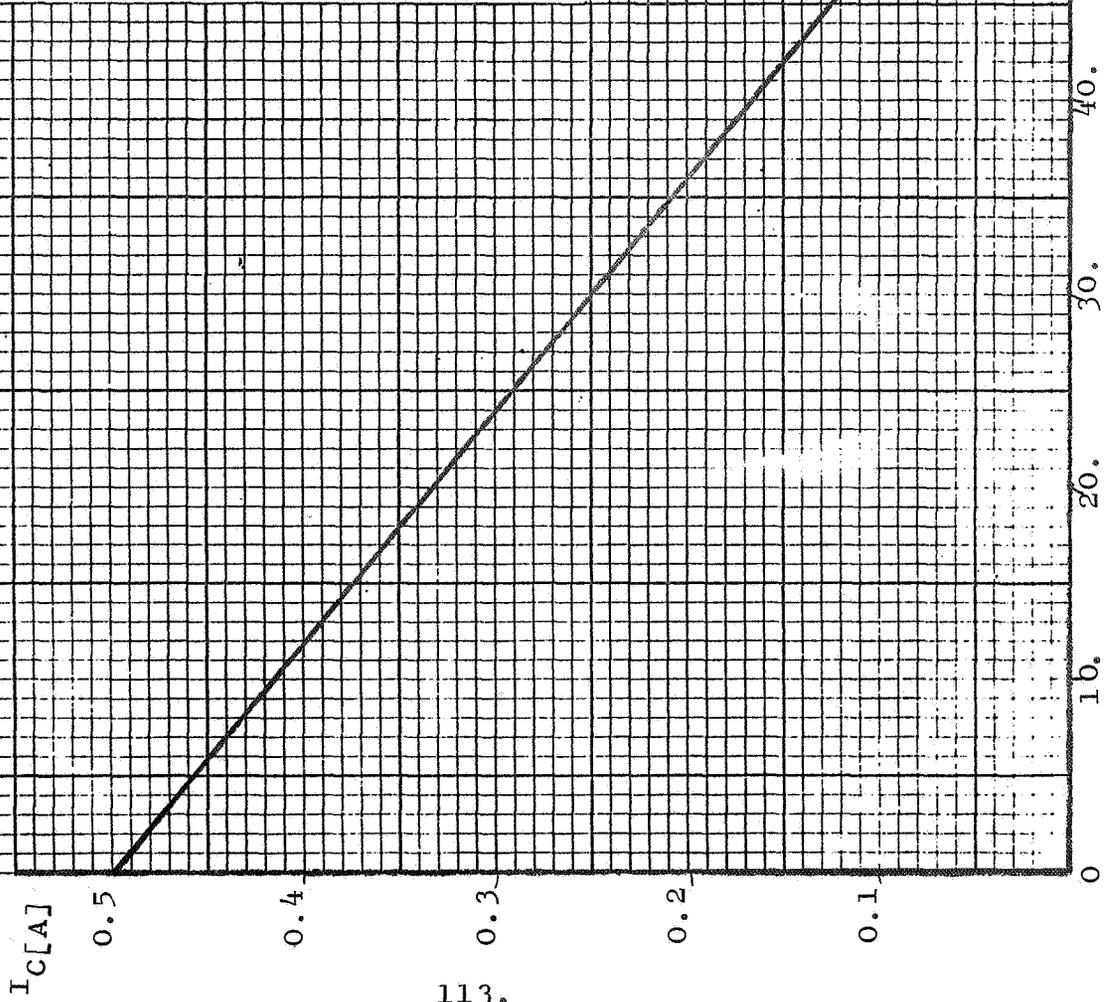


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

$V_{CE}$  [V]

Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD

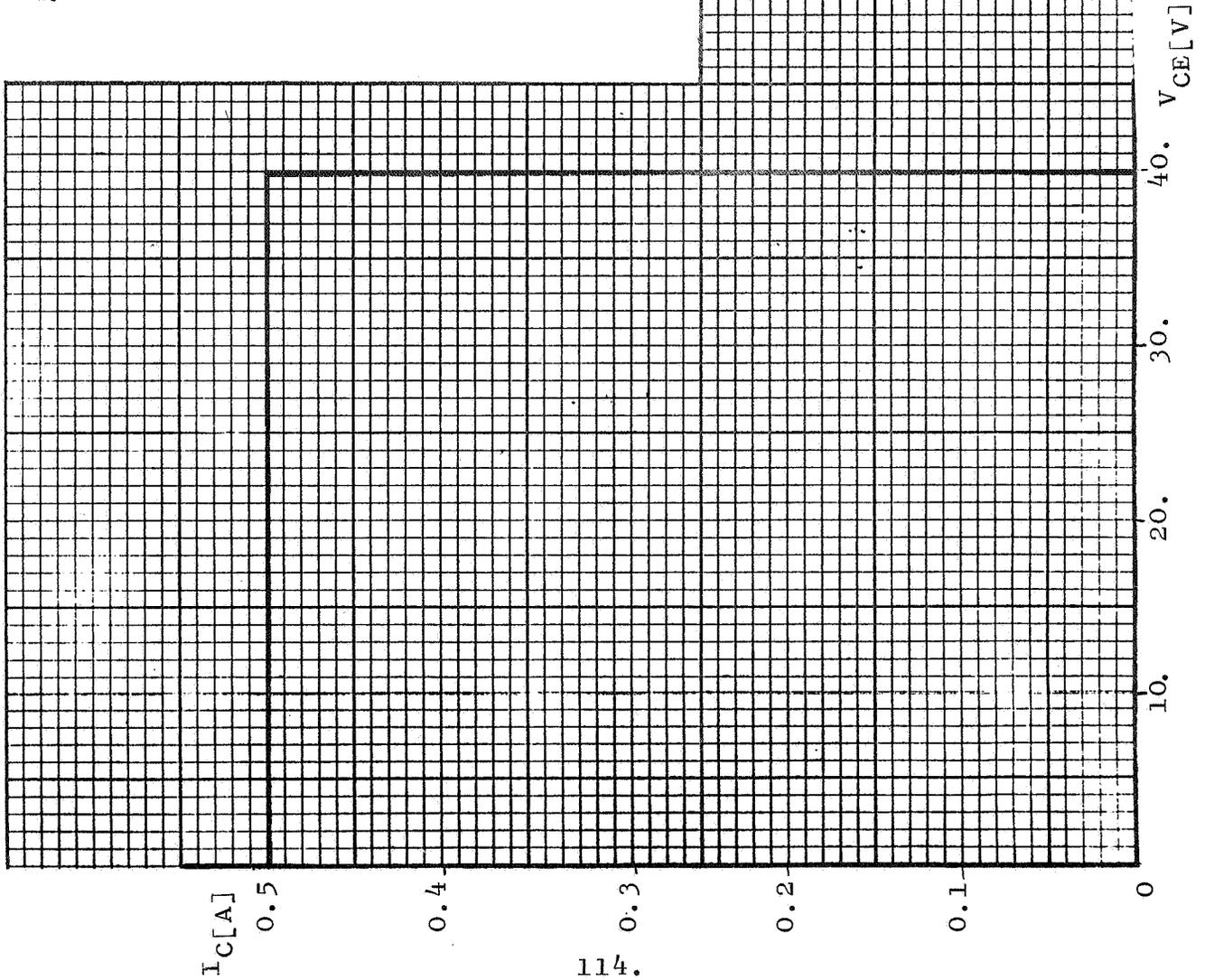
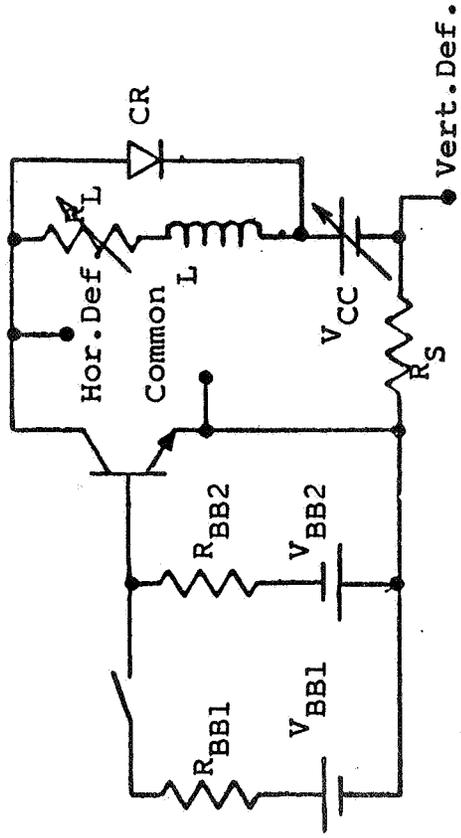
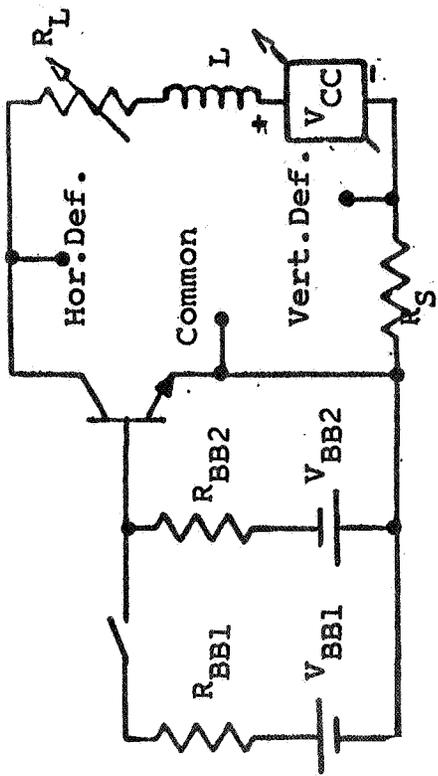


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

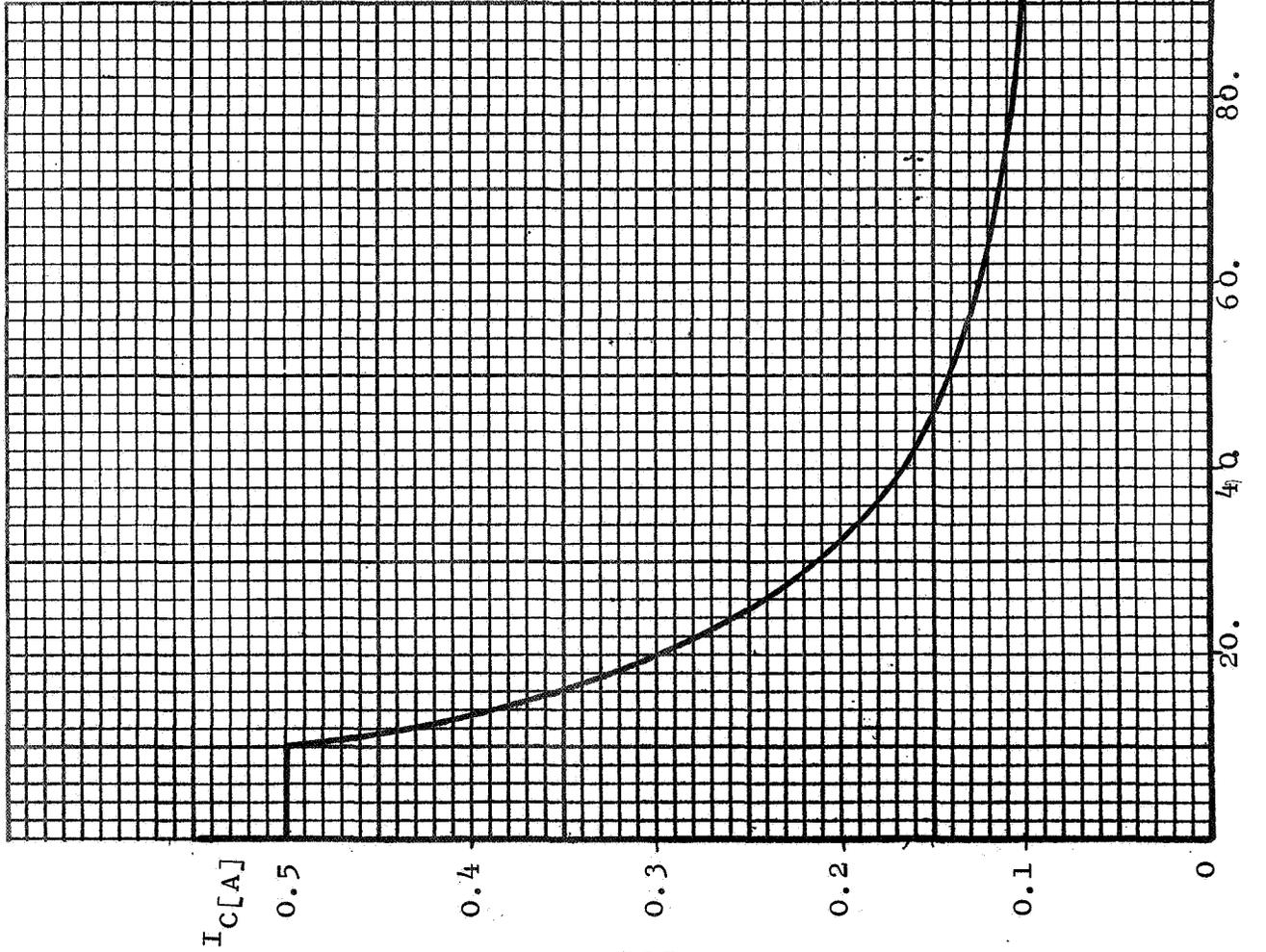


Figure 5

SHORTED CLASS B SOAR

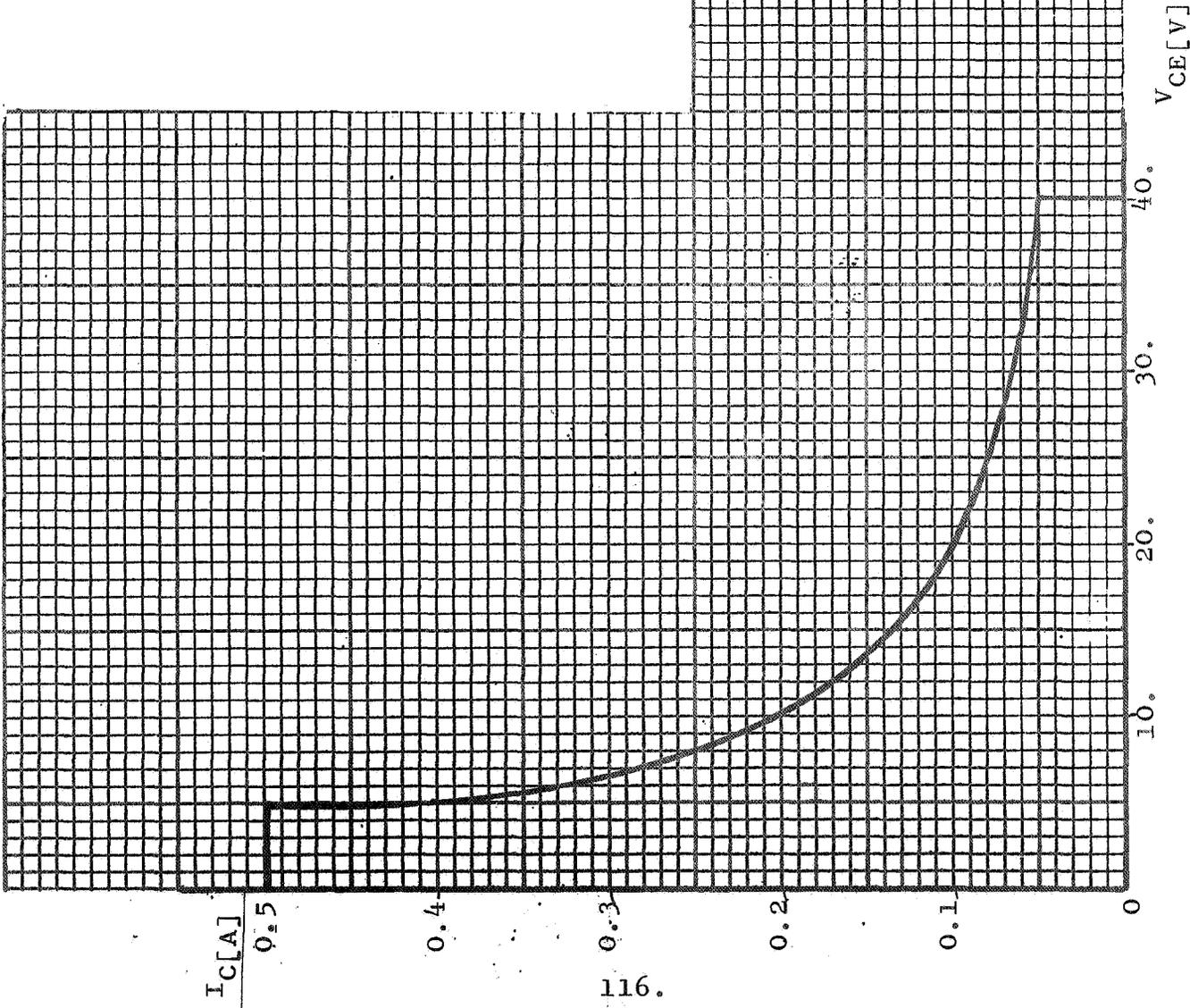
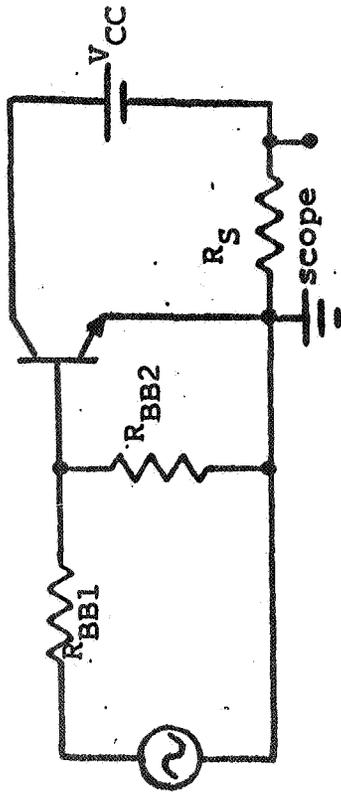


Figure 6

-- TEST REPORT --  
SILICON POWER TRANSISTOR

< 2N2880 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer H --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

Item

Test Methods and Test Conditions

1.0.0 General Description

1.1.0 Type = NPN

1.2.0 Material = Silicon

2.0.0 Mechanical Data

2.1.0 Outline = TO-111

2.2.0 Terminal Designation

1. --- Emitter

2. --- Base

3. --- Collector

Case - Collector

3.0.0 Maximum Ratings

3.1.0 Temperature

3.1.1  $T_{STG(min)} = -65^{\circ}C$

JS-6-T1.1

$T_{STG(max)} = +200^{\circ}C$

JS-6-T1.2

3.1.2  $T_J(max) = 200^{\circ}C$

JS-6-T2

$T_C = 100^{\circ}C$

$P_T = 30W, I_C = 5A$

3.1.3  $T(Lead) = +230^{\circ}C$

Distance from case = 1/16"

Time = 10 sec.

3.2.0 Voltage

$T_C = 25^{\circ}C$

3.2.1  $V_{CBO} = 100V$

JS-6-T3 or MIL-STD-750A

Method 3001.1

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.2 $V_{EBO} = 8V$	<u>JS-6-T3</u> or MIL-STD-750A Method 3026.1
3.2.3 $V_{CEX} = 100V$	<u>JS-6-T4</u> or MIL-STD-750A Method 3053 $I_C (V_{CE} = V_{CEX}) = 5A$ $V_{CC} = 100V, R_L = 19.5\Omega$ $L^* = 1.0mH, CR = 1N1204$ $V_{BB1} = 9V, R_{BB1} = 5\Omega$ $V_{BB2} = 2.5V, R_{BB2} = 5\Omega$ Pulse width = 1.0ms, Duty Cycle = 2% $R_S = 0.1\Omega, t_r \leq 50\mu s$ $t_f \leq 50\mu s$ * Miller No. 7871 in series with Miller No. 7825-3
3.3.0 Current	
3.3.1 $I_C = 5A$	<u>JS-6-T6</u> $I_B = 0.5A, T_C \leq 25^\circ C$
3.3.2 $I_B = 0.5A$	<u>JS-6-T8</u> $T_C \leq 25^\circ C$
3.4.0 Power	
3.4.1 $P_T = 30W$	<u>TS-6-T12</u> or MIL-STD-750A Method 3051 $T_C \leq 100^\circ C$ Derating Factor = $0.3 W/^\circ C$ $V_{CB} \approx 30V, I_C = 1A$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.4.2 $P_{TM} = I_C V_{CC} = 350W$	<u>JS-6-T13</u> or MIL-STD-750A Method 3052 $T_C = 100^{\circ}C$ , $V_{CC} = 70V$ $V_{BB} = 2.5V$ , $R_{BB} = 5\Omega$ Pulse width = 0.5ms Duty Cycle $\leq 1\%$ $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC SOAR	<u>JS-6-T12</u> or MIL-STD-750A Method 3051 [see figure 1] <u>Test Points:</u> 1. [see 3.4.1] 2. $V_{CB} \approx 70V$ , $I_C = 0.2A$ , $T_C = 100^{\circ}C$ , $P_T = 14W$
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T1.4</u> or MIL-STD-750A Method 3052 Test Points: [see figure 2] $T_C \leq 100^{\circ}C$ , $V_{BB} = 2.5V$ $R_{BB} = 5\Omega$ , $I_C = 5A$ $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ Duty Cycle $\leq 1\%$ , $R_S = 0.1\Omega$ 1. For $t_p = 5ms$ ; $V_{CC} = 20V$ 2. For $t_p = 2.5ms$ ; $V_{CC} = 35V$ 3. For $t_p = 1ms$ ; $V_{CC} = 50V$ 4. For $t_p = 0.5ms$ ; $V_{CC} = 70V$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<p><u>JS-6-T5.1</u> or MIL-STD-750A</p> <p>Method 3053 with L = 0 and CR disconnected [see figure 3]</p> <p><u>Test Points:</u></p> <p><math>I_C = 5A, V_{CC} = 100V, R_{BB1} = 5\Omega</math>  <math>R_{BB2} = 5\Omega, V_{BB1} = 9V, V_{BB2} = 2.5V</math>  <math>T_C = 100^\circ C; R_S = 0.1\Omega</math>  <math>t_r \leq 50\mu s, t_f \leq 50\mu s</math> Collector Current</p>
3.6.2 Clamped Inductive Load	<p><u>JS-6-T5.1</u> or MIL-STD-750A</p> <p>Method 3053 [see figure 4]</p> <p><u>Test Points:</u></p> <p><math>I_C = 5A, V_{CC} = 100V, R_L = 19.5\Omega</math>  <math>L = 1mH, R_{BB1} = 5\Omega, R_{BB2} = 5\Omega</math>  <math>V_{BB1} = 9V, V_{BB2} = 2.5V, t_p = 1ms,</math>  <math>CR = 1N1204, T_C = 25^\circ C, t_r \leq 50\mu s</math>  <math>t_f \leq 50\mu s, \text{Duty Cycle} = 2\%</math>  <math>R_S = 0.1\Omega</math></p>
3.6.3 Unclamped Inductive Load	<p><u>JS-6-T5.1</u> or MIL-STD-750A</p> <p>Method 3053 with CR disconnected</p> <p><u>Test Points:</u> [see figure 5]</p> <p><math>R_{BB1} = 5\Omega, R_{BB2} = 5\Omega, R_S = 0.1\Omega</math>  <math>V_{BB1} = 9V, V_{BB2} = 2.5V, f = 20Hz</math></p>

Item

Test Methods and Test Conditions

3.6.3 [Cont'd]

$$T_C = 25^{\circ}\text{C}$$

1.  $I_C = 4\text{A}$ ,  $V_{CC} = 30\text{V}$ ,  $R_L = 7\Omega$

$L = 125\mu\text{H}$  - Two Miller 7825-3 in parallel

2.  $I_C = 0.5\text{A}$ ,  $V_{CC} = 10\text{V}$ ,  $R_L = 19\Omega$

$L = 10\text{mH}$  - Stancor C-2688

3.7.0 Shorted Class B  
SOAR

[see figure 6]

Test Points:

$$I_C (\text{peak}) = 0.3\text{A}, V_{CC} = 70\text{V},$$

$$R_S = 0.1\Omega, R_{BB1} = 1\Omega, R_{BB2} = 3\Omega,$$

$$f = 20\text{Hz}, T_C = 100^{\circ}\text{C}$$

4.0.0 Electrical  
Characteristics

Maximum limits  
unless otherwise  
noted.

$$T_C = 25^{\circ}\text{C} \text{ [unless otherwise noted]}$$

Techniques:

DC = Continuous Operation

C.T. = Curve Tracer

P = 300 $\mu\text{s}$  Pulse

2% Duty Cycle

4.1.0 Static

4.1.1  $I_{CEX} = 50\mu\text{A}$

$$V_{CE} = 60\text{V}, V_{BE} = -0.5\text{V},$$

$$T_C = 150^{\circ}\text{C}, \text{Techniques} - \text{C.T.}$$

ItemTest Methods and Test Conditions

4.1.2  $I_{CEX} = 10\mu A$

$V_{CE} = 100V, V_{BE} = -0.5V$

Technique - C.T.

4.1.3  $I_{CBO} = 50\mu A$

$V_{CB} = 60V, T_C = 150^\circ C$

Technique - C.T.

4.1.4  $I_{CBO} = 0.1\mu A$

$V_{CB} = 60V$

Technique - C.T.

4.1.5  $I_{EBO} = 10\mu A$

$V_{EB} = 8V$

Technique - C.T.

4.1.6  $I_{EBO} = 0.1\mu A$

$V_{EB} = 5V$

Technique - C.T.

4.1.7  $V_{(BR)CEO} = 80V \text{ min}$

$I_C = 10mA$

Technique - C.T.

4.1.8  $V_{(BR)CEO} = 70V \text{ min}$

$I_C = 0.1A$

Technique - C.T.

4.1.9  $I_{CEO} = 100\mu A$

$V_{CEO} = 50V$

Technique - C.T.

4.1.10  $h_{FE} = 30 \text{ min}$   
120 max

$V_{CE} = 2V, I_C = 10mA$

Technique - P

4.1.11  $h_{FE} = 40 \text{ min}$   
120 max

$V_{CE} = 2V, I_C = 1A$

Technique - P

4.1.12  $h_{FE} = 15 \text{ min}$   
60 max

$V_{CE} = 2V, I_C = 1A, T_C = -55^\circ C$

Technique - P

4.1.13  $h_{FE} = 60 \text{ min}$   
200 max

$V_{CE} = 2V, I_C = 1A, T_C = 150^\circ C$

Technique - P

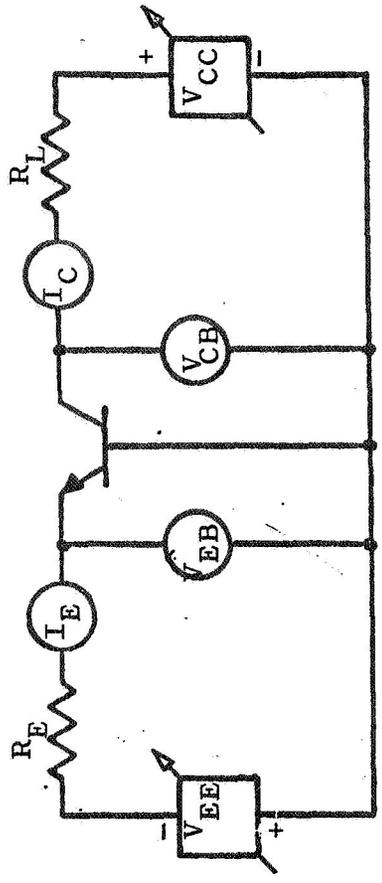
4.1.14  $h_{FE} = 15 \text{ min}$   
45 max

$V_{CE} = 5V, I_C = 5A$

Technique - P

<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.1.15 $V_{CE(sat)} = 0.25V \text{ max}$	$I_C = 1A, I_B = 0.1A$ Technique - C.T.
4.1.16 $V_{CE(sat)} = 2.0V \text{ max}$	$I_C = 5A, I_B = 0.5A$ Technique - C.T.
4.1.17 $V_{BE(sat)} = 1.2V \text{ max}$	$I_C = 1A, I_B = 0.1A$ Technique - C.T.
4.1.18 $V_{BE(sat)} = 2V \text{ max}$	$I_C = 5A, I_B = 0.5A$ Technique - C.T.
4.1.19 $V_{BE} = 1.2V \text{ max}$	$V_{CE} = 2V, I_C = 1A$ Technique - C.T.
4.2.0 Dynamic	
4.2.1 $t_{ON} = 300ns$	$V_{CC} = 20V, I_C = 1A$
4.2.2 $t_{OFF} = 2.0\mu s$	$I_{B1} = - I_{B2} = 100mA$
4.2.3 $\left  h_{FE} \right  = 2 \text{ min}$ $= 9 \text{ max}$	$V_{CE} = 10V, I_C = 1A, f = 10MHz$
4.2.4 $C_{obo} = 150 \text{ pF max}$	$V_{CB} = 10V, f = 1MHz$
5.0.0 <u>Thermal</u> <u>Characteristics</u>	
5.1.0 $\tau_J = 5ms \text{ min}$	MIL-STD-750, method 3146.1 $V_{CE} = 10V, I_C = 2A, T_C = 25^\circ C$
5.2.0 $\theta_{J-C} = 3.33^\circ C/W$	MIL-STD-750A, method 3136 $V_{CE} = 5V, I_C = 2A$

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ C$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

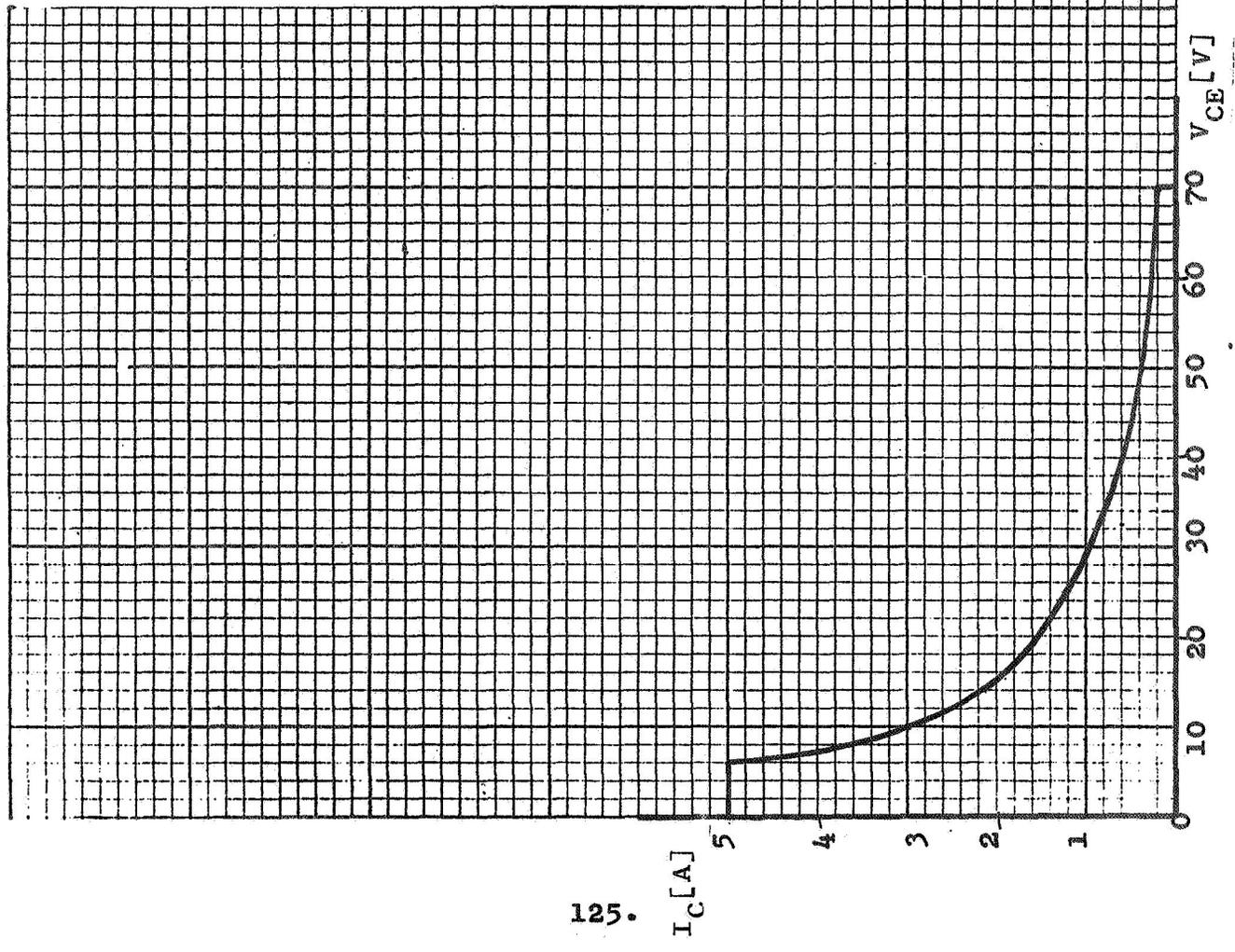
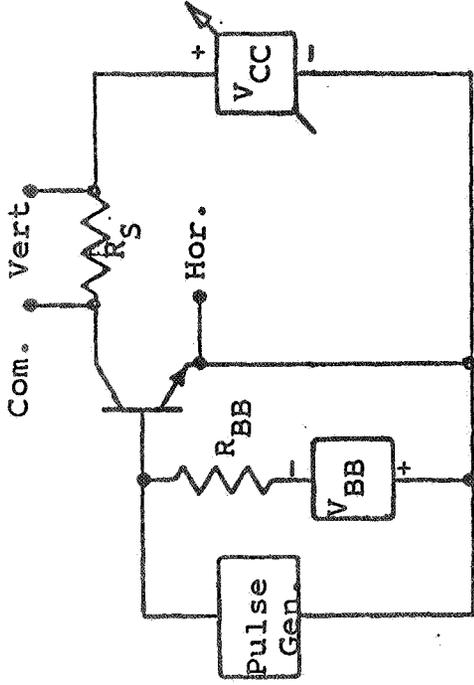


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

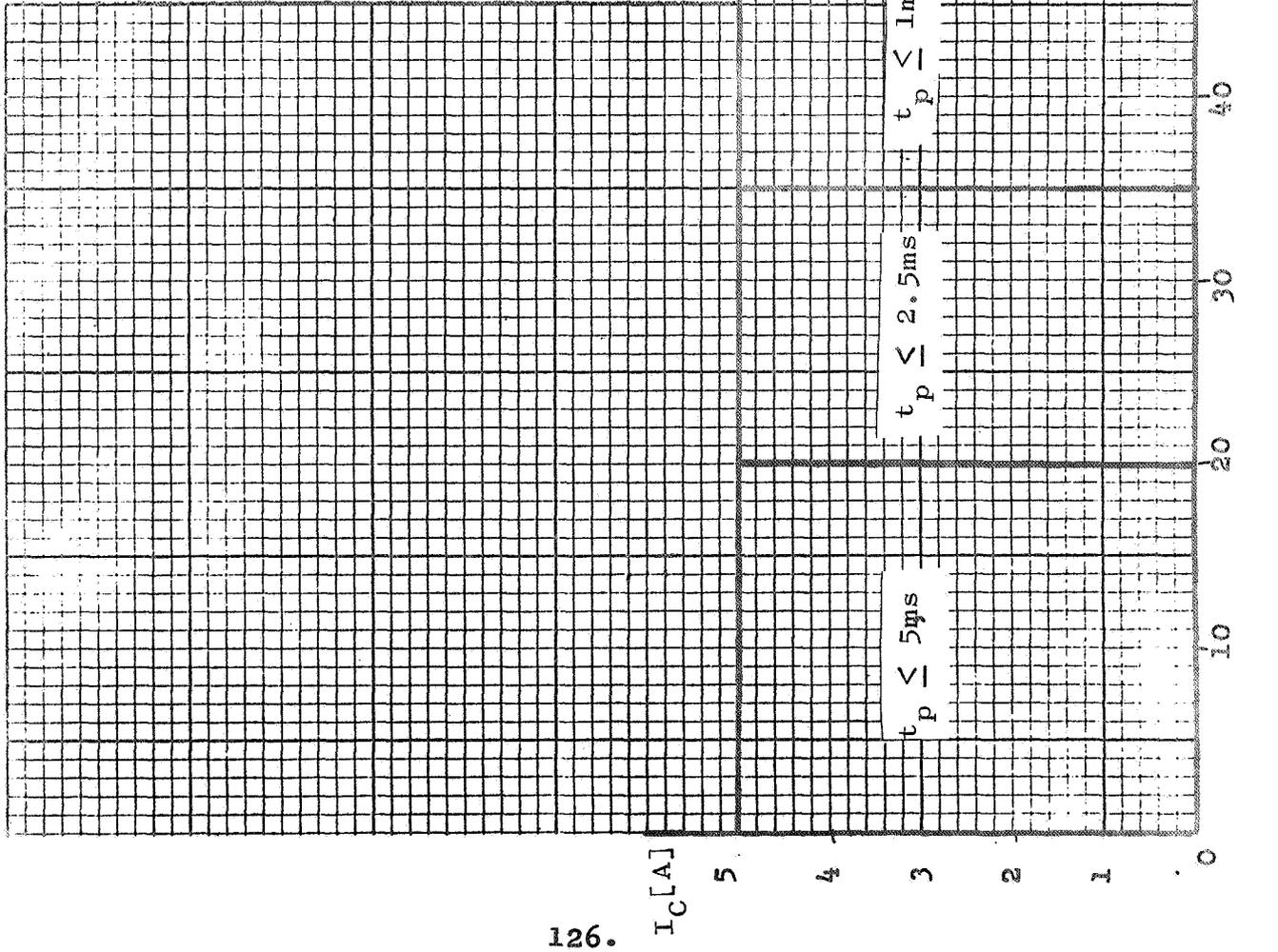
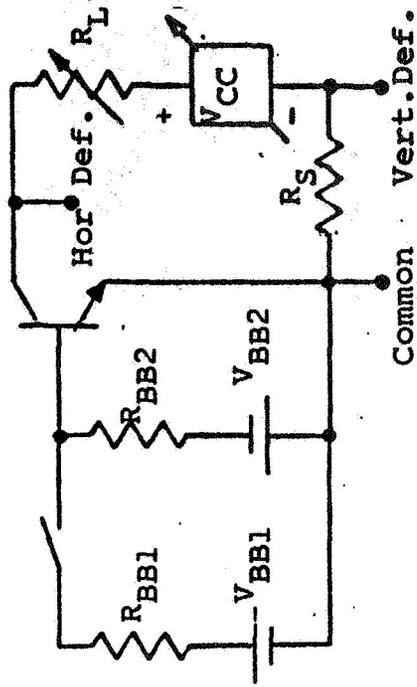


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

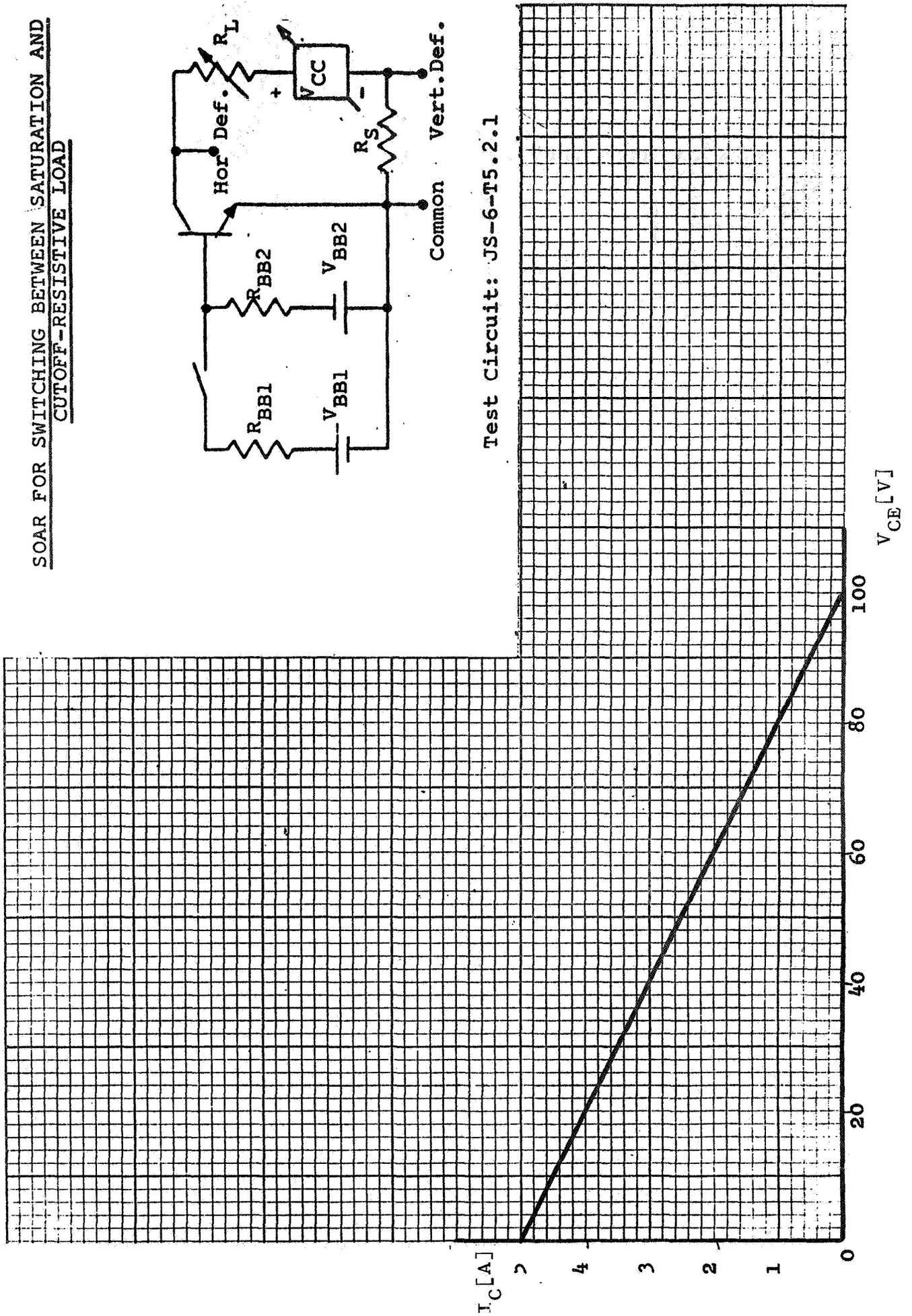
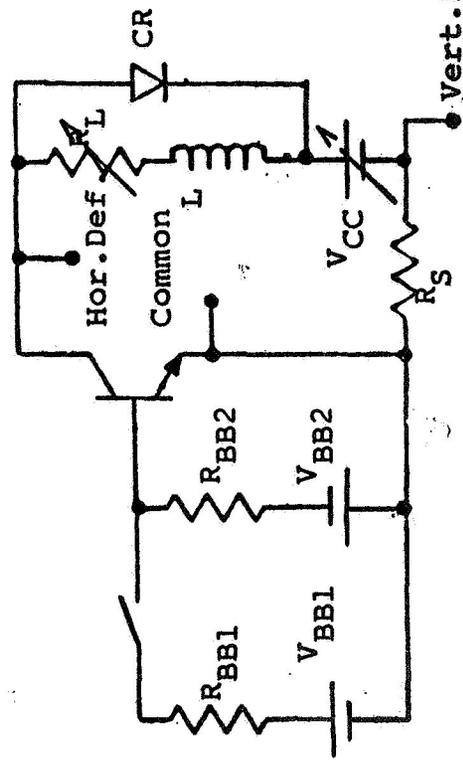
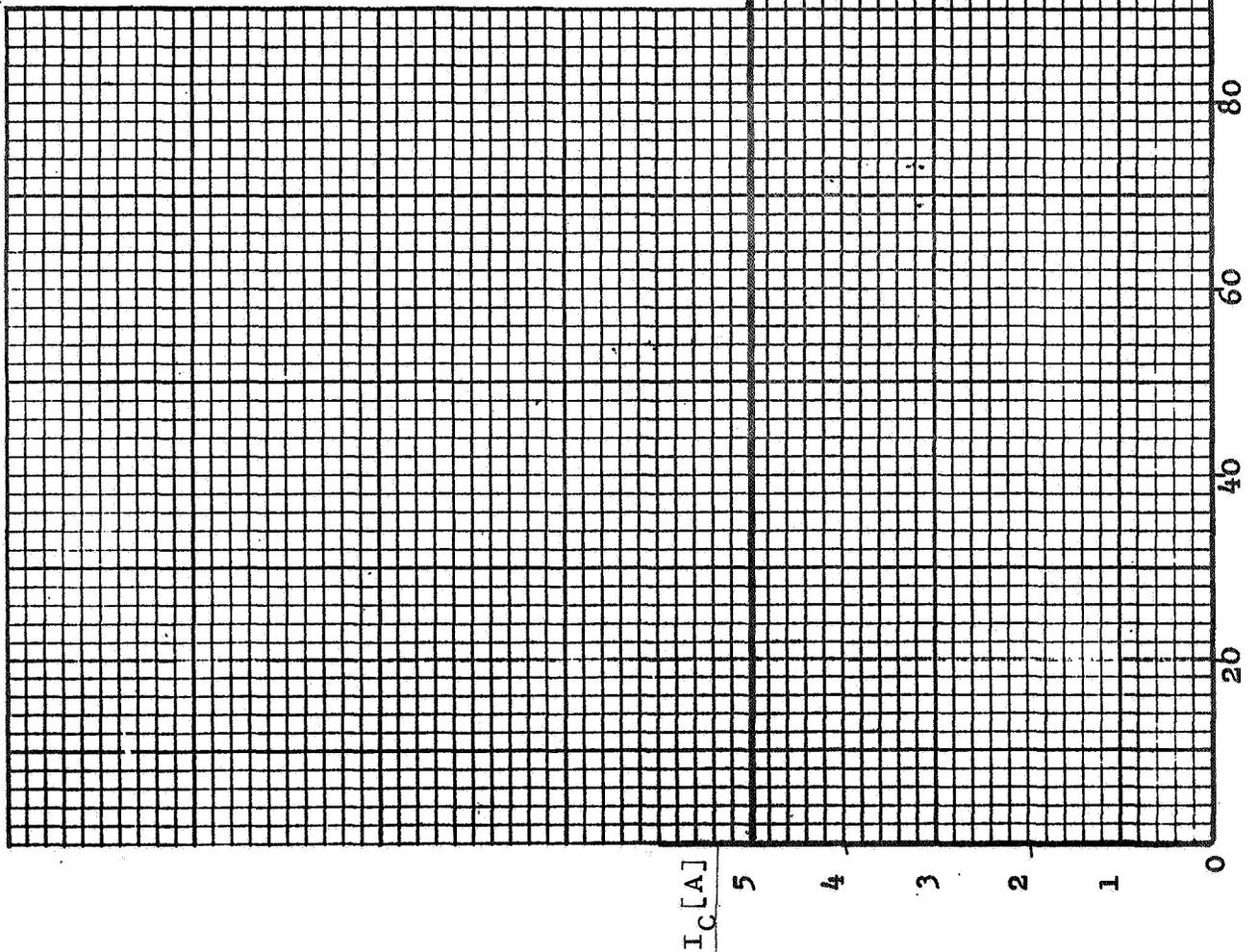


Figure 3

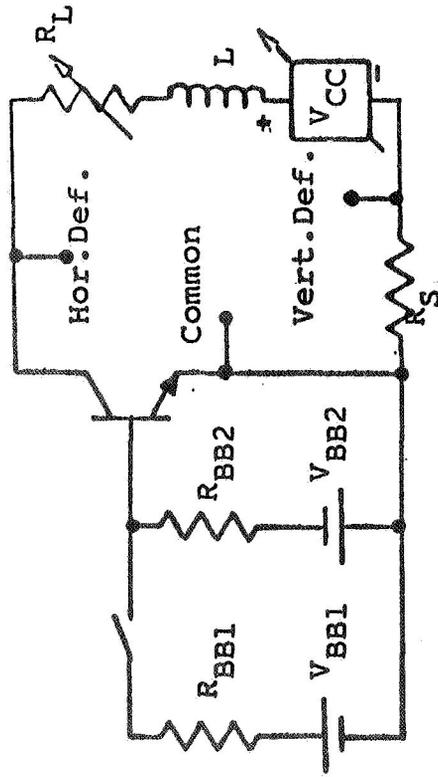
SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

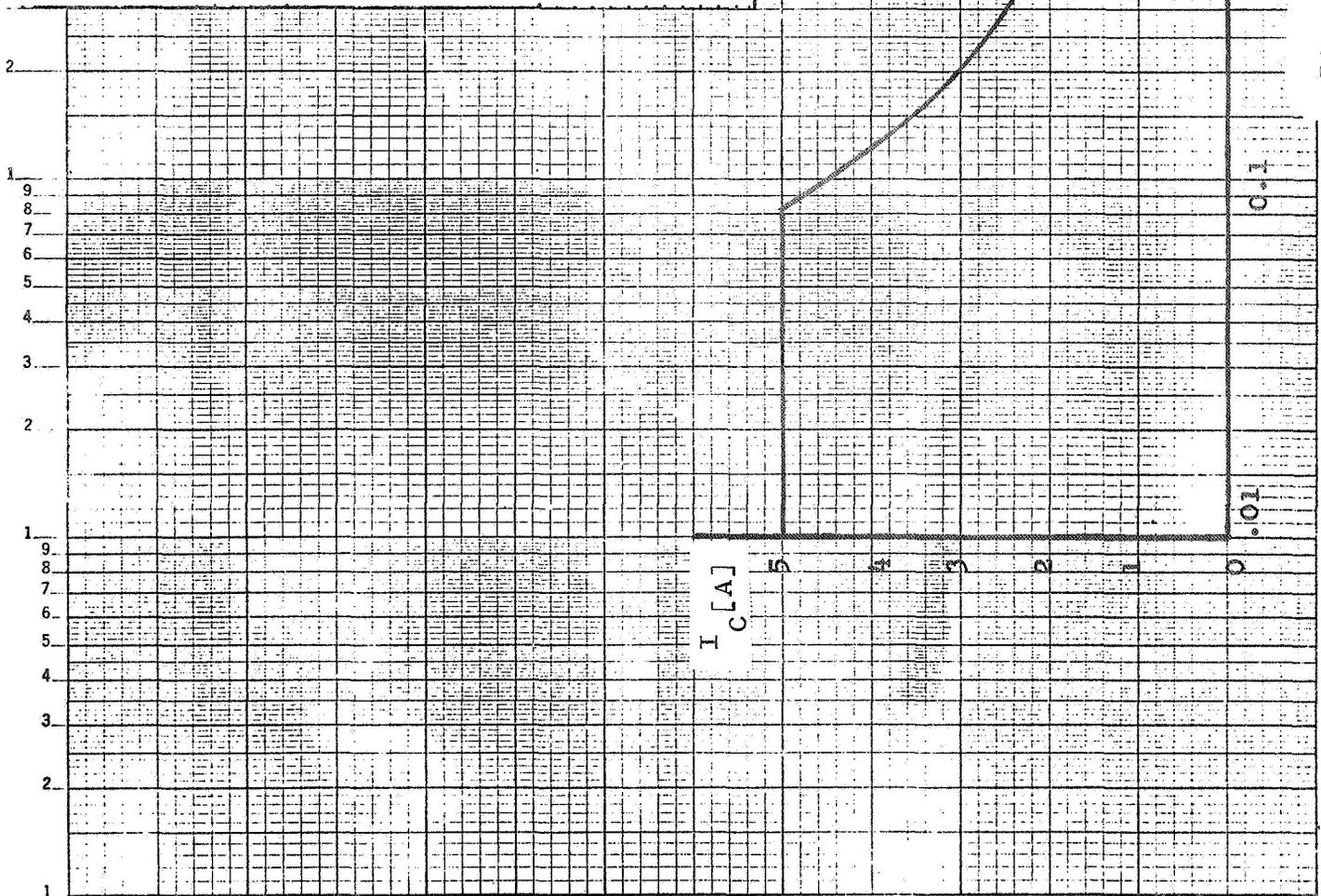


Figure 5

SHORTED CLASS B SOAR

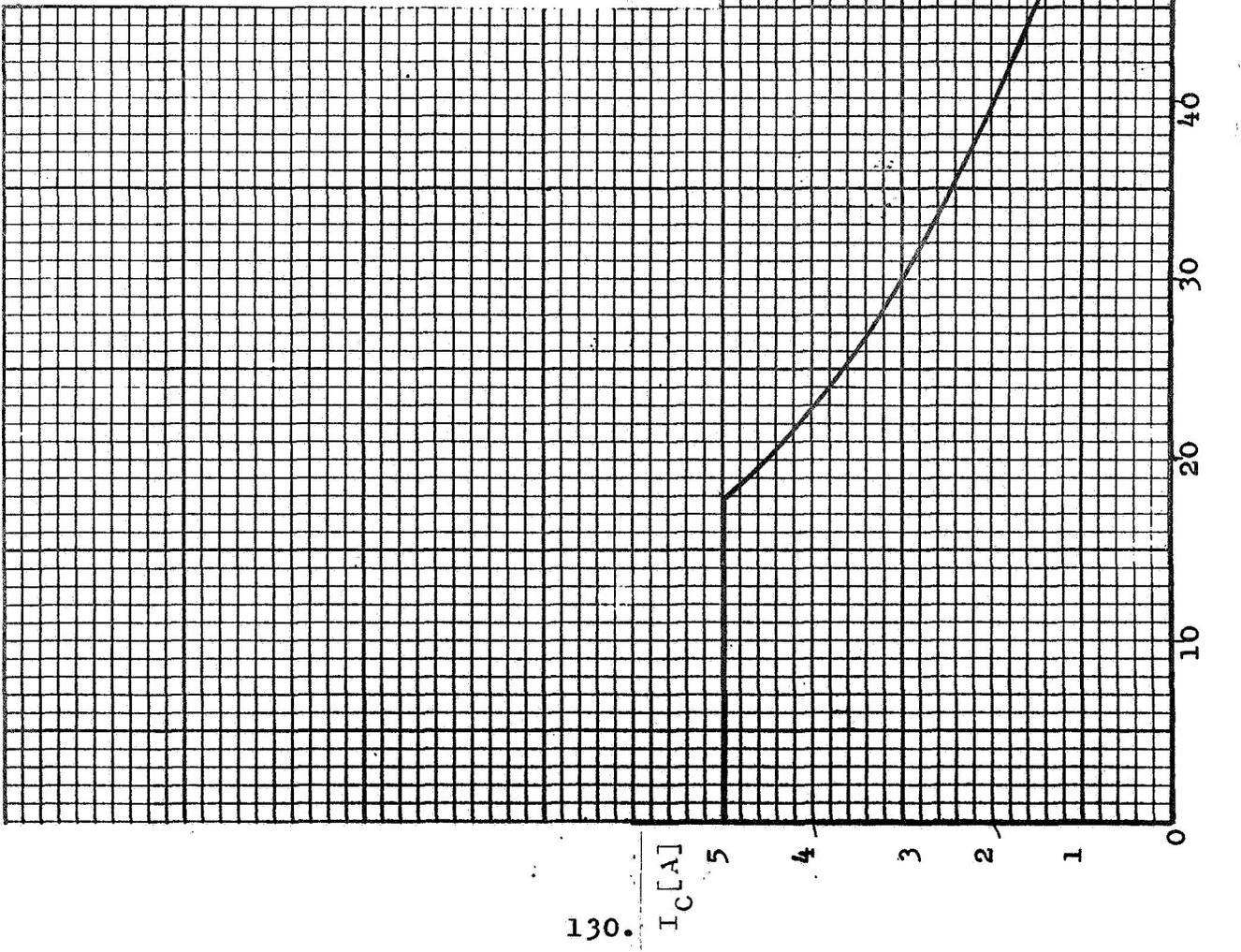
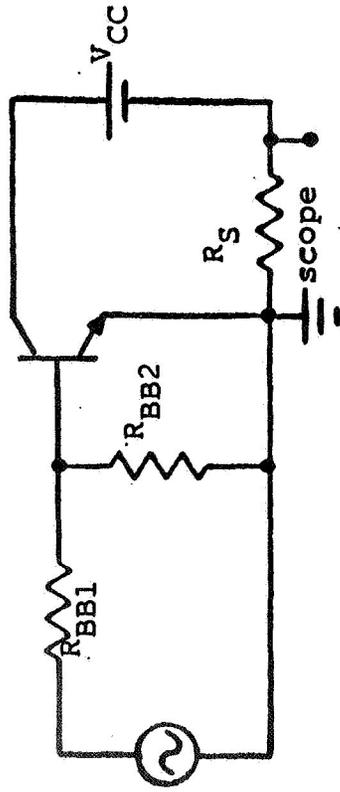


Figure 6

-- TEST REPORT --

SILICON POWER TRANSISTOR

< S2N4150 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer H --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Condition</u>
1.0.0	<u>General Description</u>
1.1.0	Type -- NPN
1.2.0	Material -- Silicon
2.0.0	<u>Mechanical Data</u>
2.1.0	Outline TO-5
2.2.0	Terminal Designation
	1 --- Base
	2 --- Emitter
	3 --- Collector
	Case--Collector
3.0.0	<u>Maximum Ratings</u>
3.1.0	Temperature
3.1.1	$T_{STG(min)} = -55^{\circ}C$
	$T_{STG(max)} = +200^{\circ}C$
	<u>JS-6-T1.1</u> [JEDEC Suggested standard: "Test Procedure for Verification of Maximum Ratings." JEDEC Publication No. 65.]
	<u>JS-6-T1.2</u>
3.1.2	$T_{J(max)} = +200^{\circ}C$
	<u>JS-6-T2</u> or MIL-STD-750A Method 3051
	$T_C = 100^{\circ}C, P_T = 5W, I_C = 0.1A,$
	$V_{CE} = 50V$
3.1.3	T (Lead) = $230^{\circ}C$
	Distance from Case 1/16"
	Time = 3 sec.
3.2.0	Voltage

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.1 $V_{(BR)CBO} = 120V$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1
3.2.2 $V_{(BR)EBO} = 7V$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1
3.2.3 $V_{(BR)CEX} = 70V$	<u>JS-6-T5.1</u> or MIL-STD-750A Method 3053 $I_C \leq 10A, V_{CE} = 70V, R_{BB1} = 10\Omega,$ $R_{BB2} = 20\Omega. V_{BB1} = 16V, V_{BB2} = 5.0V$ $R_L = 7\Omega, L^* = 1.0mH, R_S = 0.1\Omega$ $t_r \leq 10\mu s, t_f \leq 10\mu s, t_p = 300\mu s$ Duty cycle $\leq 0.2\%$ *J.W. Miller: 7871 in series with 7825-3
3.3.0 Current	
3.3.1 $I_C = 3.0A$	<u>JS-6-T-6</u> $I_B = 0.3A, T_C = 25^\circ C$
3.3.2 $I_{CM} = 10A$	<u>JS-6-T7</u> $T_C = 25^\circ C, R_S = 0.1\Omega$ $V_{BB} = 5V, R_{BB} = 20\Omega$ $I_B = 1A, t_p = 300\mu s, d \leq 0.2\%$ $t_r \leq 10\mu s, t_f \leq 10\mu s$
3.3.3 $I_B = 0.5A$	<u>JS-6-T8</u> $T_C = 25^\circ C$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.3.4 $I_{BM} = 1.0A$	<u>JS-6-T4</u> $T_C = 25^{\circ}C$ , $R_S = 1.0\Omega$ , $t_p = 300\mu s$ , $t_r \leq 10\mu s$ $t_f \leq 10\mu s$ , $d \leq 0.2\%$
3.3.5 $I_E = 3.3A$	<u>JS-6-T10</u> $I_B = 0.3A$ , $T_C = 25^{\circ}C$ [see 3.3.2]
3.3.6 $I_{EM} = 11A$	[see 3.3.2]
3.4.0 Power	
3.4.1 $P_T = 5.0W$	<u>JS-6-T12</u> <u>Test Point:</u> [See 3.1.2]
3.4.2 $P_{TM} = I_C V_{CC} = 700W$	<u>JS-6-T13</u> or MIL-STD-750A Method 3052 $T_C = 100^{\circ}C$ , $V_{CC} = 70V$ , $V_{BBI} = 16V$ , $R_{BB} = 10\Omega$ , $I_C = 10A$ , Pulse Width = $100\mu s$ Duty Cycle $\leq 0.2\%$ $t_r \leq 10\mu s$ $t_f \leq 10\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> or MIL-STD-750A Method 3051 Test Points: [See 3.1.2]

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.2 Pulsed Forward Biased SOAR	<p><u>JS-6-T14</u> or MIL-STD-750A</p> <p>Method 3052</p> <p><u>Test Points:</u></p> <p><math>T_C = 100^\circ\text{C}</math>, <math>V_{BB} = 5\text{V}</math>, <math>R_{BB} = 20\Omega</math>,  <math>t_r \leq 10\mu\text{s}</math>, <math>t_f \leq 10\mu\text{s}</math>, <math>I_C = 10\text{A}</math>,  Duty Cycle <math>\leq 0.2\%</math>, <math>R_S = 0.1\Omega</math>,</p> <ol style="list-style-type: none"> <li>1. <math>t_p = 100\mu\text{s}</math>: <math>V_{CC} = 70\text{V}</math></li> <li>2. <math>t_p = 200\mu\text{s}</math>: <math>V_{CC} = 50\text{V}</math></li> <li>3. <math>t_p = 300\mu\text{s}</math>: <math>V_{CC} = 30\text{V}</math></li> </ol>
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<p><u>JS-6-T5-5.1</u> or MIL-STD-750A</p> <p>Method 3053 with <math>L = 0</math> and  CR disconnected</p> <p><u>Test Points:</u></p> <p><math>R_{BB1} = 10\Omega</math>, <math>R_{BB2} = 20\Omega</math>, <math>V_{BB1} = 16\text{V}</math>,  <math>V_{BB2} = 5.0\text{V}</math>, <math>T_C = 100^\circ\text{C}</math>, <math>t_f \leq 10\mu\text{s}</math>,  <math>t_r \leq 10\mu\text{s}</math>, <math>R_S = 0.1\Omega</math>, <math>R_L = 12\Omega</math>,  <math>V_{CC} = 120</math>, <math>d \leq 0.2\%</math>, <math>t_p \leq 300\mu\text{s}</math></p>
3.6.2 Clamped Inductive Load	<p><u>JS-6-T5.1</u> or MIL-STD-750A</p> <p>Method 3053</p> <p>Test Point: [see 3.2.3]</p>

Item

3.6.3 Unclamped  
Inductive Load

Test Methods and Test Conditions

JS-6-T5.1 or MIL-STD-750A

Method 3053 and CR disconnected

Test Points:

- $V_{BB1} = 16V$        $L^* = 1.0mH$   
 $R_{BB1} = 10\Omega$        $R_L = .35\Omega$   
 $V_{BB2} = 5.0V$        $V_{CC} = \text{adjust to}$   
 $I_C = 10A$   
 $R_{BB2} = 20\Omega$        $t_p = 300\mu s$   
 $R_S = 0.1\Omega$        $d \leq 0.2\%$

\*J.W.Miller:7871 in series with 7825-3

- $V_{BB1} = 6.0V$        $L^* = 10mH$   
 $R_{BB1} = 10\Omega$        $R_L = .11\Omega$   
 $V_{BB2} = 5.0V$        $V_{CC} = \text{adjust to}$   
 $d \leq 0.2\%$        $I_C = 0.5A$   
 $R_{BB2} = 20\Omega$        $t_p = 300\mu s$

\*Chicago Standard Transformer Corp.

C-2688

3.7.0 Shorted Class B  
SOAR

[See Figure 6]

Test Points:

- $I_C(\text{peak}) = 0.43A$ ,  $V_{CC} = 35V$   
 $R_S = 0.1\Omega$ ,  $R_{BB1} = 10\Omega$ ,  $R_{BB2} = 20\Omega$   
 $f = 20Hz$ ,  $T_C = 100^\circ C$

ItemTest Methods and Test Conditions4.0.0 Electrical  
Characteristics

Maximum limits  
unless otherwise  
noted.

$T_C = 25^{\circ}\text{C}$  [unless otherwise noted]

Technique:

MIL-STD-750A \*  
JS-6

C.T. = Curve Tracer

P = 300 $\mu\text{s}$  Pulse  
2% Duty Cycle

## 4.1.0 Static

4.1.1  $I_{\text{CBO}} = 100\text{nA max}$  $V_{\text{CB}} = 80\text{V}$ , Technique \*Method 3036.1D4.1.2  $I_{\text{CBO}} = 10\mu\text{A max}$  $V_{\text{CB}} = 80\text{V}$ ,  $T_C = 150^{\circ}\text{C}$ 

Technique \*Method 3036.1 D

4.1.3  $I_{\text{CBO}} = 10\mu\text{A max}$  $V_{\text{CB}} = 100\text{V}$ , Technique \*Method 3036.1 D4.1.4  $I_{\text{CEV}} = 100\mu\text{A max}$  $V_{\text{CE}} = 60\text{V}$ ,  $V_{\text{EB}} = 0.5\text{V}$ ,  $T_C = 150^{\circ}\text{C}$ 

Technique \*Method 3041.1A

4.1.5  $I_{\text{CEO}} = 10\mu\text{A max}$  $V_{\text{CE}} = 60\text{V}$ , Technique \*Method 3041.1 A4.1.6  $I_{\text{EBO}} = 10\mu\text{A max}$  $V_{\text{EB}} = 5\text{V}$ , Technique \*Method 3061.1 D4.1.7  $V_{\text{CEO}} = 70\text{V min}$  $I_C = 100\text{ma}$ , Technique C.T. [half wave]4.1.8  $h_{\text{FE}} = 40 \text{ min } 145 \text{ max}$  $I_C = 10\text{mA}$ ,  $V_{\text{CE}} = 5\text{V}$ 

Technique C.T.

4.1.9  $h_{\text{FE}} = 45 \text{ min } 170 \text{ max}$  $I_C = 100\text{mA}$ ,  $V_{\text{CE}} = 5\text{V}$ 

Technique P

4.1.10  $h_{\text{FE}} = 50 \text{ min } 175 \text{ max}$  $I_C = 1.0\text{A}$ ,  $V_{\text{CE}} = 5\text{V}$ 

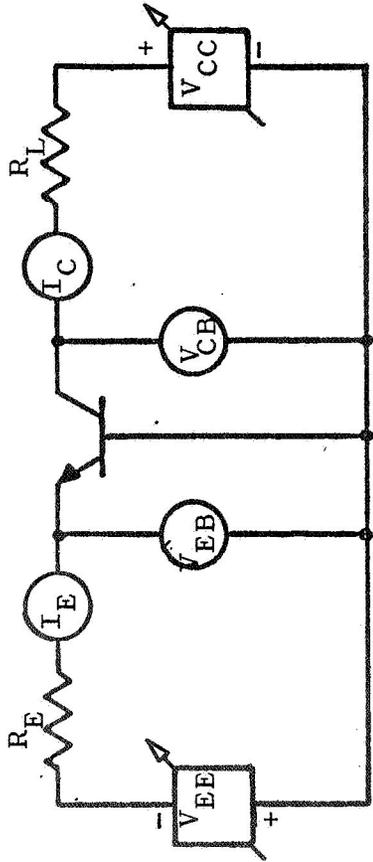
Technique P

<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.1.11 $h_{FE} = 40 \text{ min } 120 \text{ max}$	$I_C = 5.0A, V_{CE} = 5V$ Technique P
4.1.12 $h_{FE} = 10 \text{ min}$	$I_C = 10A, V_{CE} = 5V$ Technique P
4.1.13 $h_{FE} = 75 \text{ min } 350 \text{ max}$	$I_C = 100mA, V_{CE} = 5V, T_C = 150^\circ C$ Technique P
4.1.14 $h_{FE} = 70 \text{ min } 320 \text{ max}$	$I_C = 1.0A, V_{CE} = 5V, T_C = 150^\circ C$ Technique P
4.1.15 $h_{FE} = 30 \text{ min } 150 \text{ max}$	$I_C = 5.0A, V_{CE} = 5V, T_C = 150^\circ C$ Technique P
4.1.16 $h_{FE} = 30 \text{ min } 90 \text{ max}$	$I_C = 100mA, V_{CE} = 5V, T_C = -55^\circ C$ Technique P
4.1.17 $h_{FE} = 30\text{min } 100 \text{ max}$	$I_C = 1.0A, V_{CE} = 5V, T_C = -55^\circ C$ Technique P
4.1.18 $h_{FE} = 20 \text{ min } 75 \text{ max}$	$I_C = 5.0A, V_{CE} = 5V, T_C = -55^\circ C$ Technique P
4.1.19 $V_{CE(S)} = 0.55V \text{ max}$	$I_C = 5.0A, I_B = 0.5A$ Technique * P
4.1.20 $V_{CE(S)} = 2.0V \text{ max}$	$I_C = 10A, I_B = 1.0A$ Technique* P
4.1.21 $V_{BE(S)} = 1.4V \text{ max}$	$I_C = 5.0A, I_B = 0.5A$ Technique* P
4.1.22 $V_{BE(S)} = 2.0V \text{ max}$	$I_C = 10A, I_B = 1.0A$ Technique* P

<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.2.0	Dynamic
4.2.1	$h_{FE} = 1.5 \text{ min } 8.0 \text{ max}$
4.2.2	$C_{obo} = 350 \text{ pF max}$
4.2.3	$t_{ON} = 0.5\mu\text{s max}$
4.2.4	$t_{OFF} = 2.5\mu\text{s max}$
5.0.0	Thermal Characteristics
5.1.1	$\tau_J = 20 \text{ ms min}$
5.1.2	$\theta_{JC} = 20 \text{ }^\circ\text{C/W max}$
5.1.3	$\theta_{JA} = 175 \text{ }^\circ\text{C/W max}$

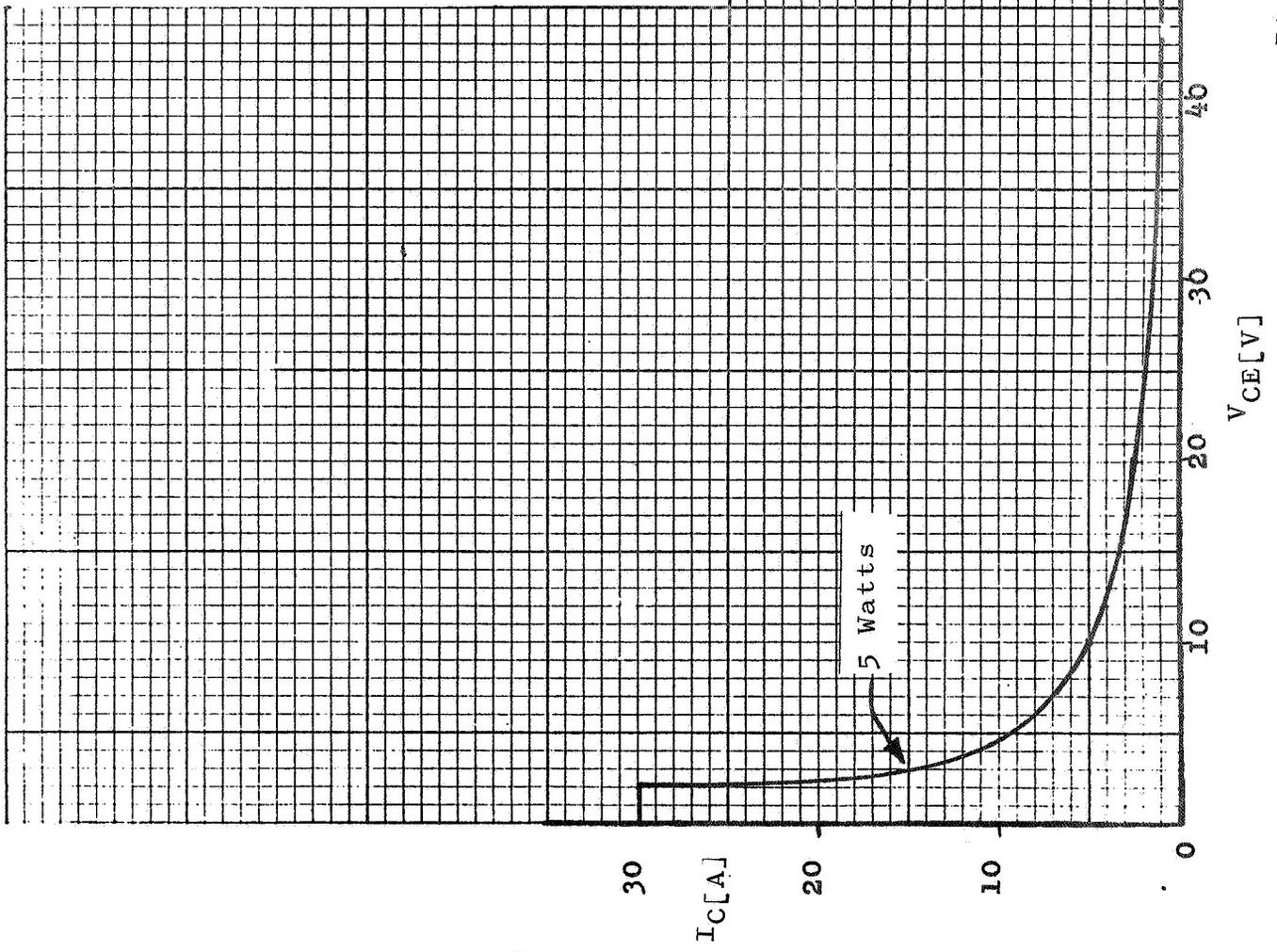
\*Test clips 1/4" from case

FORWARD BIASED CONTINUOUS SOAR

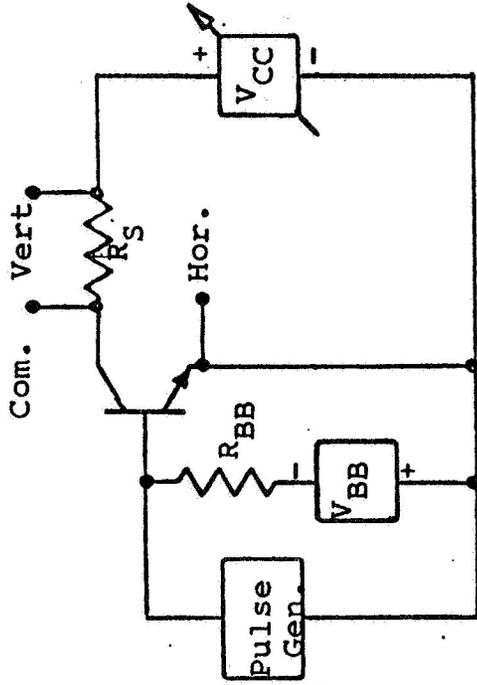


Conditions:  $T_C \leq 100^\circ C$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12.



PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

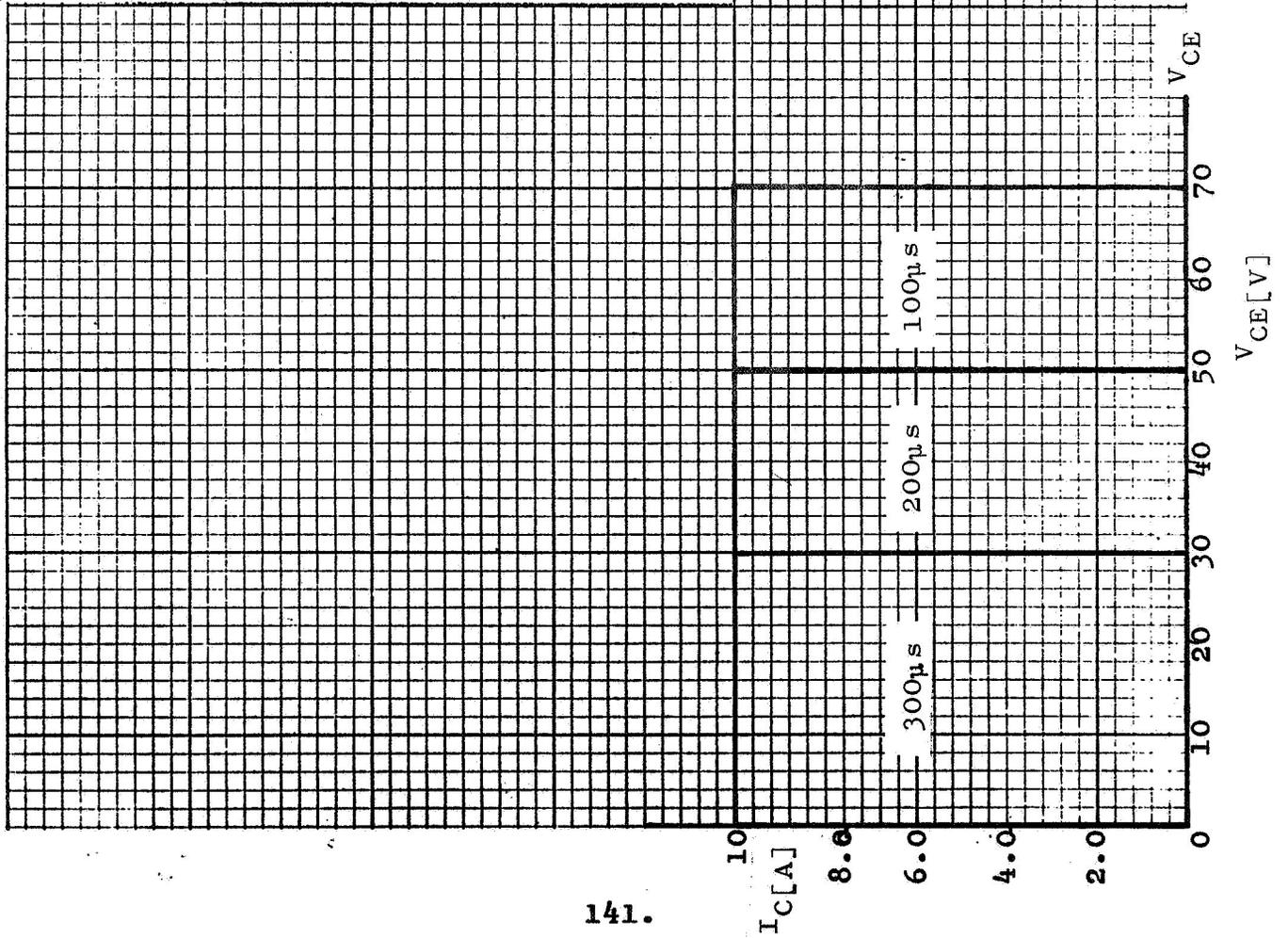
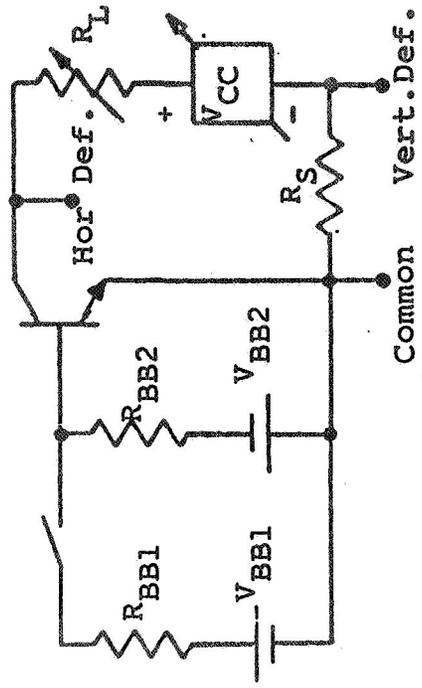


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

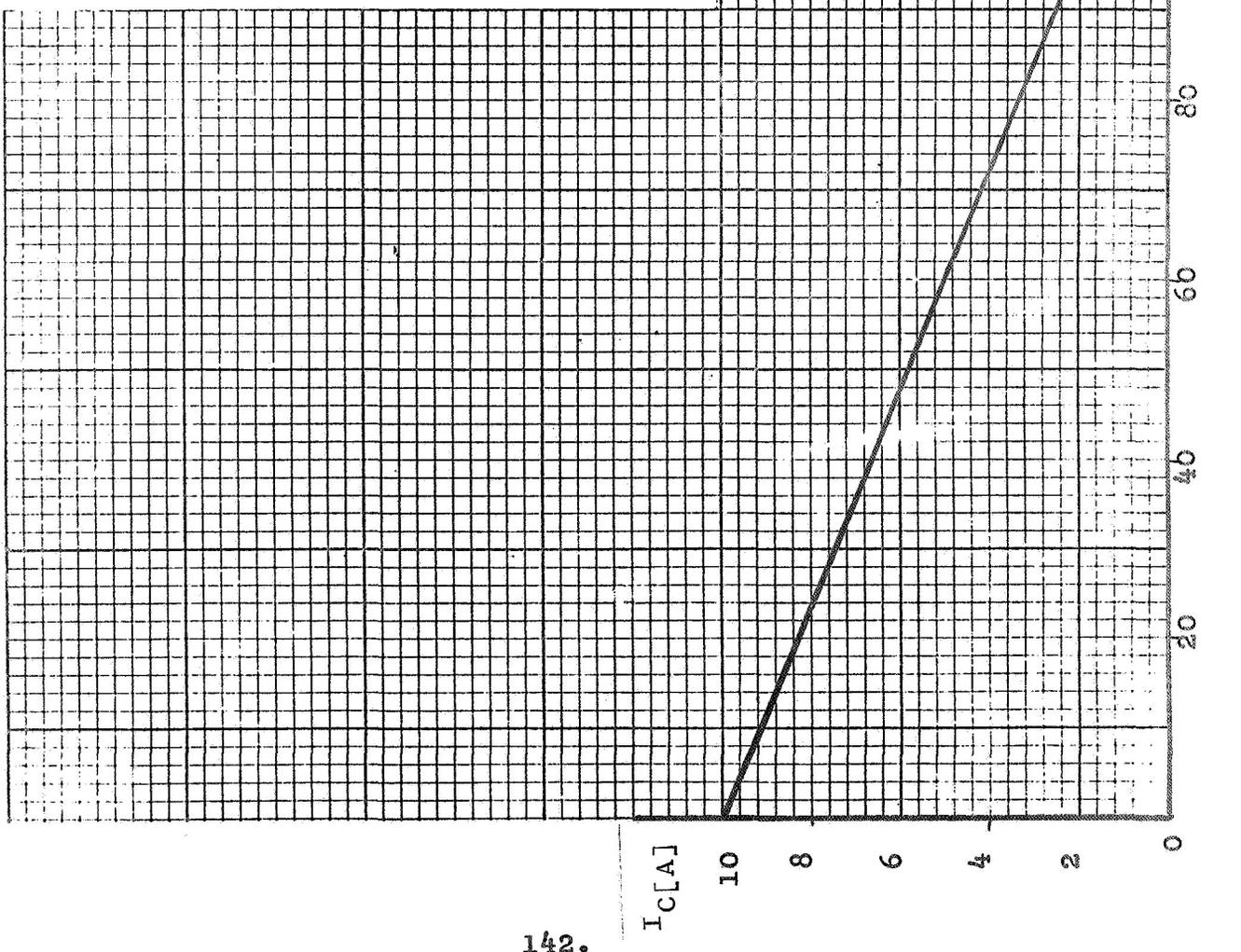
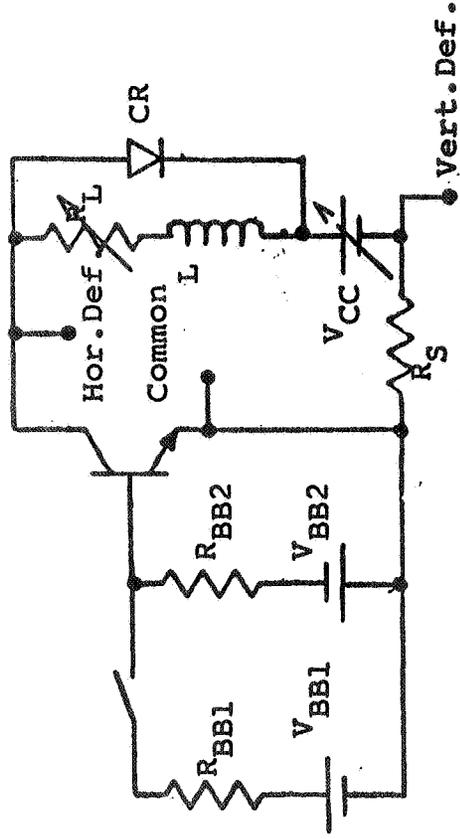


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

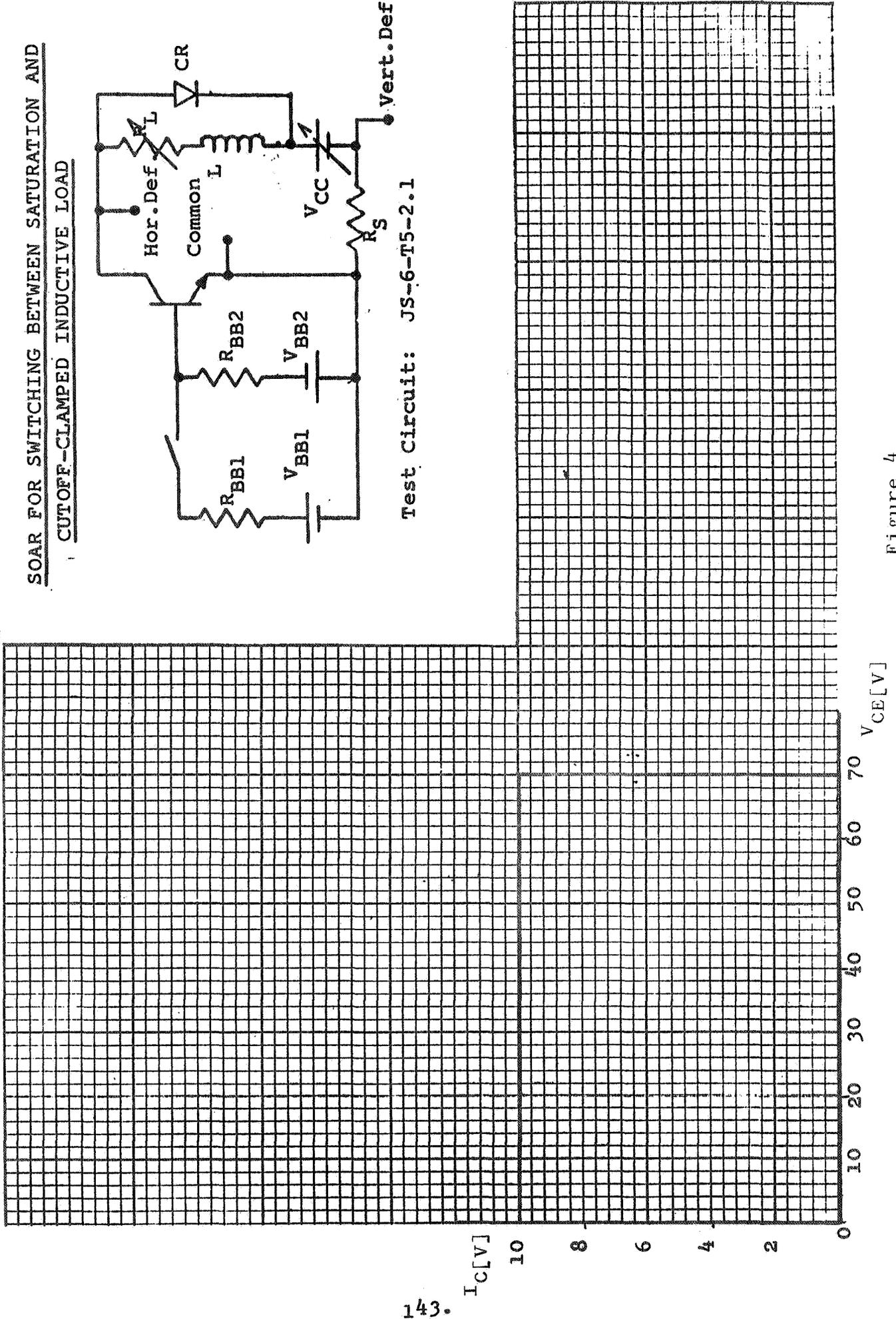
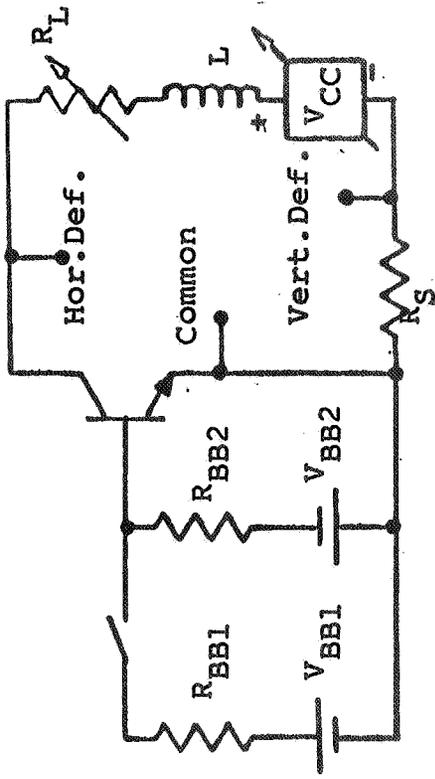


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

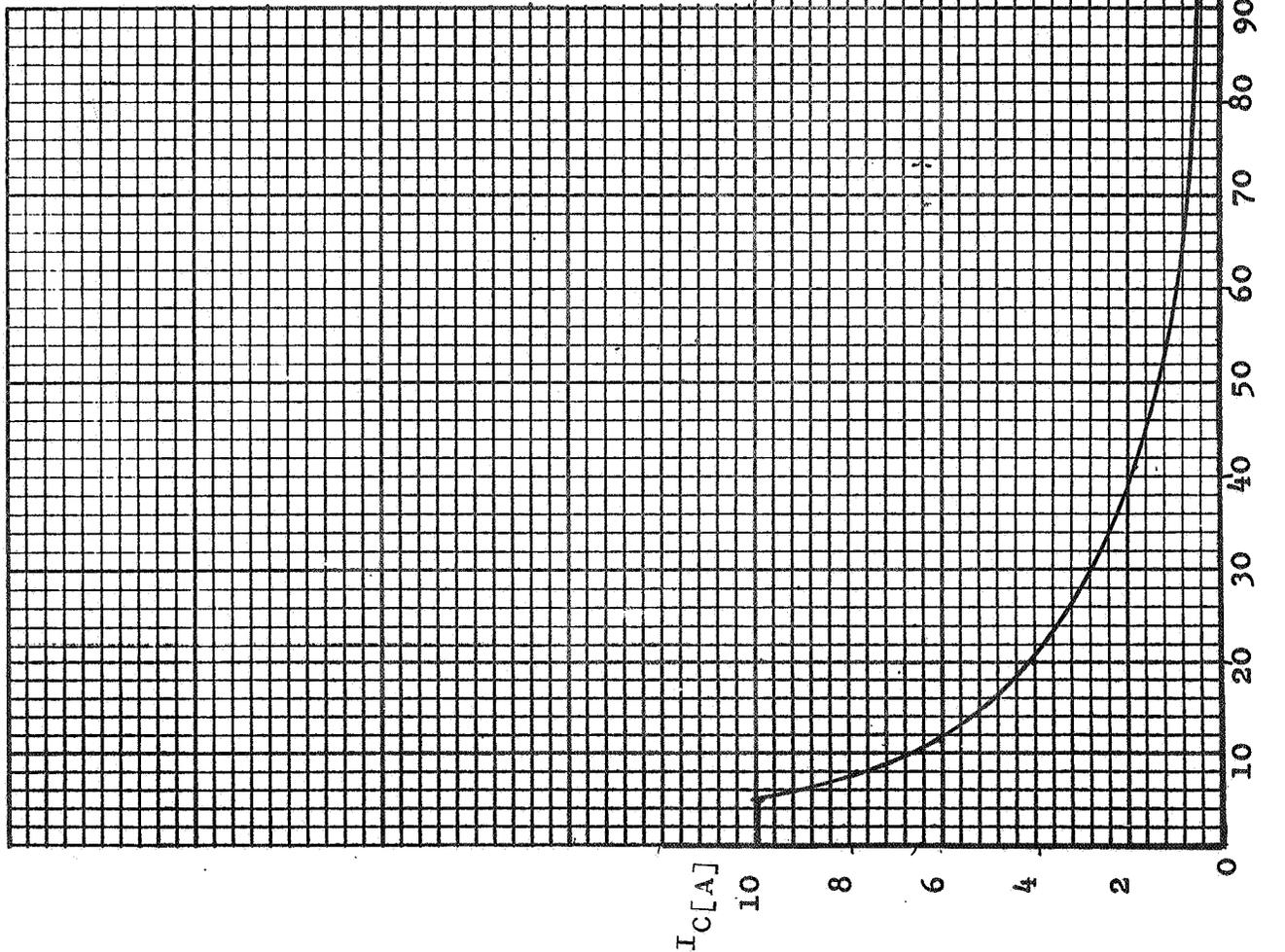


Figure 5

SHORTED CLASS B SOAR

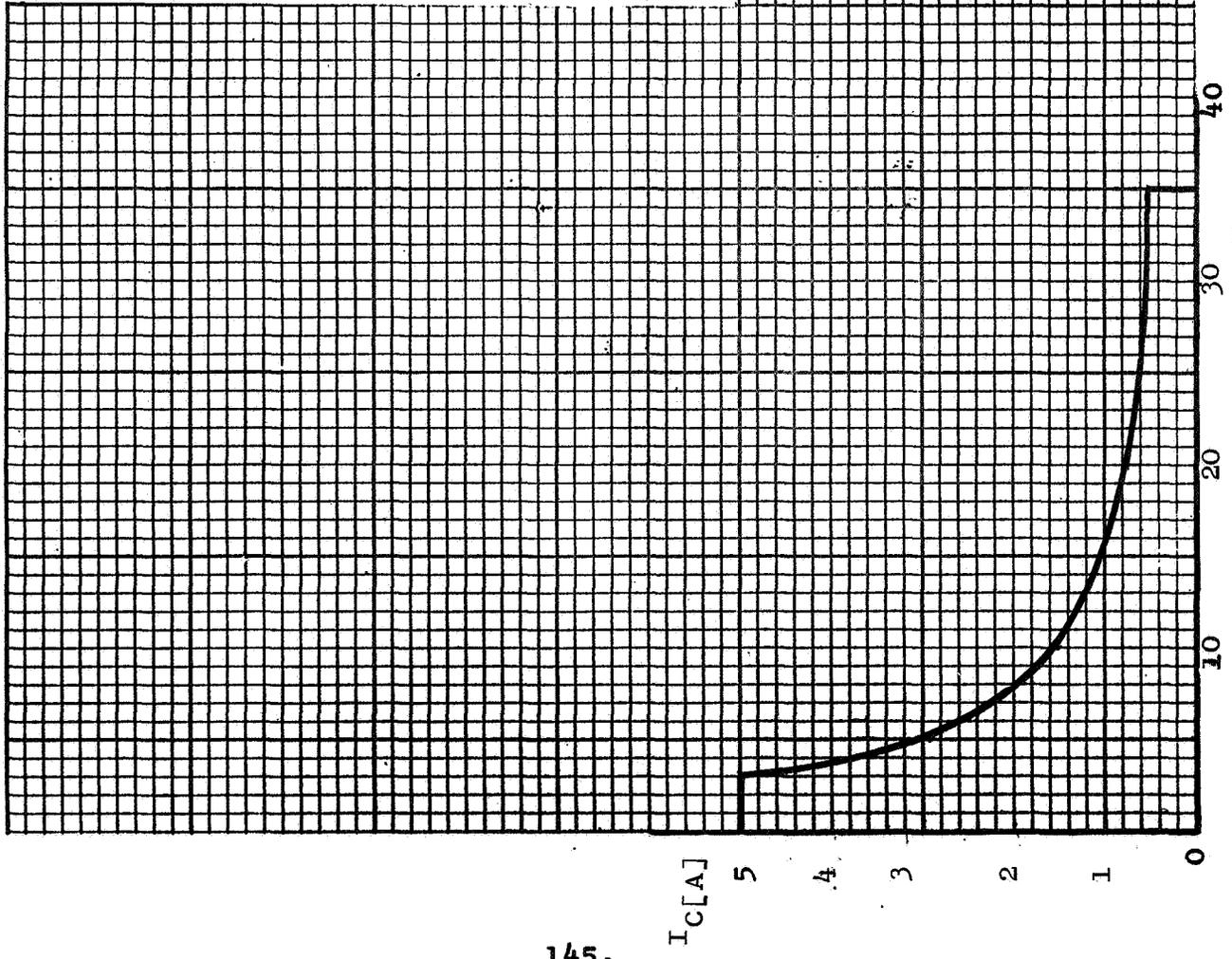
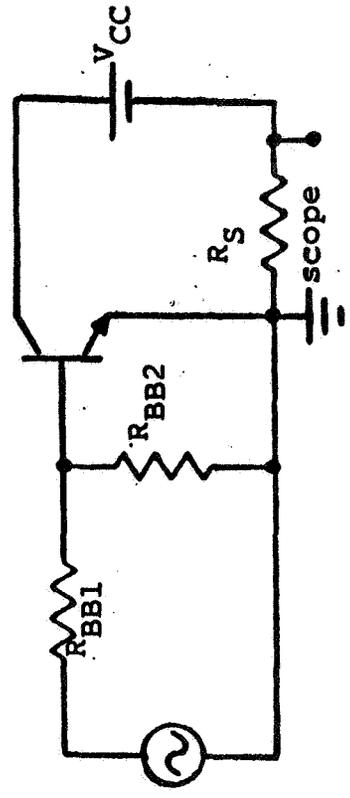


Figure 6

-- TEST REPORT --

SILICON POWER TRANSISTOR

< 2N5559 >

EXAMPLE DEVICE SPECIFICATIONS

-- Manufacturer Bendix --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

GEORGE C. MARSHALL SPACE FLIGHT CENTER

HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

The format used in the presentation of this data was recently developed for the registration of transistor specifications.

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

Item	Registered Data	Test Methods & Test Conditions	Remarks
1.0.0	GENERAL DESCRIPTION		Triode Transistor, Power Switching
1.1.0	Type <input type="text" value="NPN"/>		NPN, PNP, etc.
1.2.0	Material <input type="text" value="Silicon"/>		Ge., Si., etc.
2.0.0	MECHANICAL DATA		Note 1
2.1.0	Outline <input type="text" value="TO-3"/>		Note 2.
2.2.0	Terminal Designation 1 <input type="text" value="Base"/> 2 <input type="text" value="Emitter"/> 3 <input type="text"/> case <input type="text" value="Collector"/>		Indicate all un-connected terminals as "NC".  Indicate "I" if all leads insulated from case.
3.0.0	MAXIMUM RATINGS		Note 3
3.1.0	Temperature		
3.1.1	T <sub>stg</sub> (max) <input type="text" value="200 °C"/>	JS-6-T1.2	Test Methods JS-6-T see "Test Procedures for Verification of Maximum Ratings of Power Transistors". JEDEC Publication No. 65
	T <sub>stg</sub> (min) <input type="text" value="-65 °C"/>	JS-6-T1.1	
3.1.2	T <sub>J</sub> (max) <input type="text" value="200 °C"/>	JS-6-T2	
		T <sub>C</sub> <input type="text" value="150 °C"/> V <sub>CB</sub> <input type="text" value="≈ 20 V"/> I <sub>C</sub> <input type="text" value="2.5 A"/>	T <sub>C</sub> = 75% to 90% T <sub>J</sub> Max
3.1.3	T (Lead) <input type="text" value="235 °C"/>	Distance from case <input type="text" value="1/32 in."/> Time <input type="text" value="10 s"/>	Item 3.1.3 is not required on transistors whose storage temperature is sufficiently high so that the lead temperature test becomes redundant.



Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.0	Current		
3.3.1	$I_C$ <input type="text" value="10"/> A	JS-6-T6 $I_B$ <input type="text" value="2"/> A $T_C$ <input type="text" value="≤"/> °C	Continuous collector current
3.3.2	$I_{CM}$ <input type="text" value="15"/> A	JS-6-T7 $T_C = 25^\circ\text{C}$ $R_S$ <input type="text" value="0.1"/> Ω $V_{BB}$ <input type="text" value="0"/> V $R_{BB}$ <input type="text" value="∞"/> Ω  <u>Input Pulse Characteristics</u> Pulse Amplitude <input type="text" value="5A"/> Pulse Width <input type="text" value="1000"/> ms Duty Cycle <input type="text" value="1"/> % $t_r$ <input type="text" value="≤ 5"/> μs $t_f$ <input type="text" value="≤ 5"/> μs	Peak collector current
3.3.3	$I_B$ <input type="text" value="5"/> A	JS-6-T8 $T_C$ <input type="text" value="≤ 25"/> °C	Continuous base current
3.3.4	$I_{BM}$ <input type="text" value="7"/> A	JS-6-T9 $T_C = 25^\circ\text{C}$  <u>Input Pulse Characteristics</u> Pulse Width <input type="text" value="1000"/> ms Duty Cycle <input type="text" value="10"/> % $t_r$ <input type="text" value="≤ 5"/> μs $t_f$ <input type="text" value="≤ 5"/> μs	Peak base current
3.3.5	$I_E$ <input type="text" value="12"/> A	JS-6-T10 $I_B$ <input type="text" value="2"/> A $T_C$ <input type="text" value="25"/> °C	Continuous Emitter current

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.6	$I_{EM}$ <span style="border: 1px dashed black; padding: 2px;">A</span>	JS-6-T11  $T_C = 25^\circ C$ $R_S$ <span style="border: 1px solid black; padding: 2px;">Ω</span>  $V_{BB}$ <span style="border: 1px solid black; padding: 2px;">V</span> $R_{BB}$ <span style="border: 1px solid black; padding: 2px;">Ω</span>  <u>Input Pulse Characteristics</u>  Pulse Width <span style="border: 1px solid black; padding: 2px;">ms</span>  Duty Cycle <span style="border: 1px solid black; padding: 2px;">%</span>  $t_r \leq$ <span style="border: 1px solid black; padding: 2px;">μs</span> $t_f \leq$ <span style="border: 1px solid black; padding: 2px;">μs</span>	Peak Emitter Current
3.4.0	Power		
3.4.1	$P_T$ <span style="border: 1px solid black; padding: 2px;">100 W</span>  Derating Factor <span style="border: 1px solid black; padding: 2px;">1 W/°C</span>	JS-6-T12  $T_C$ <span style="border: 1px solid black; padding: 2px;">100 °C</span>  $V_{CB}$ <span style="border: 1px solid black; padding: 2px;">50 V</span> $I_C$ <span style="border: 1px solid black; padding: 2px;">2 A</span>	$T_C = 55^\circ C$ (for device with $T_J (\max) \leq 125^\circ C$ )  $T_C = 100^\circ C$ (for devices with $T_J (\max) > 125^\circ C$ )
3.4.2	$P_{TM}$ <span style="border: 1px dashed black; padding: 2px;">900 W</span>	JS-6-T13  $T_C = 25^\circ C$  $V_{CC}$ <span style="border: 1px solid black; padding: 2px;">90 V</span>  $V_{BB}$ <span style="border: 1px solid black; padding: 2px;">0 V</span> $R_{BB}$ <span style="border: 1px solid black; padding: 2px;">5 Ω</span>  <u>Input Pulse Characteristics</u>  Pulse Width <span style="border: 1px solid black; padding: 2px;">0.25 ms</span>  Duty Cycle <span style="border: 1px solid black; padding: 2px;">1 %</span>  $t_r \leq$ <span style="border: 1px solid black; padding: 2px;">5 μs</span> $t_f \leq$ <span style="border: 1px solid black; padding: 2px;">5 μs</span>	$P_{TM} = I_C V_{CC}$

Item	Registered Data	Test Methods & Test Conditions	Remarks															
3.5.0	Maximum Operating Conditions		Refer to Appendix A															
3.5.1	DC - Attach drawing of operating area $V_{CE}$ vs $I_C$	$T_C$ <input type="text" value="100 °C"/> Fig. 1 1. $I_C = 0.5A$ ; $V_{CE} = 80V$ 2. $I_C = 2A$ ; $V_{CE} = 50V$	$T_C = T_C$ (3.4.1) The circuit of JS-6-T12 is recommended.															
3.5.2	Pulsed (Forward Bias Drive) Attach drawing of operating area. $V_{CE}$ vs $I_C$ for one or more pulse widths	JS-6-T14, $T_C = 25^\circ C$ ; Fig. 2 $V_{BB}$ <input type="text" value="0 V"/> $R_{BB}$ <input type="text" value="5 Ω"/>	Pulse width shall be 1,2,3, or $5 \times 10^x$ sec.															
		<u>Input Pulse Characteristics</u> Pulse Width <input type="text" value="_____ ms"/> Duty Cycle <input type="text" value="2 %"/> $t_r$ <input type="text" value="≤ 5 μs"/> <input type="text" value="≤ 5 μs"/>	<table border="1"> <thead> <tr> <th>Pulse Width</th> <th><math>V_{CC}</math></th> <th><math>I_C</math></th> </tr> <tr> <th><input type="text" value="ms"/></th> <th><input type="text" value="V"/></th> <th><input type="text" value="A"/></th> </tr> </thead> <tbody> <tr> <td>1. 1 ms @</td> <td>60</td> <td>10</td> </tr> <tr> <td>2. 0.5 ms @</td> <td>80</td> <td>10</td> </tr> <tr> <td>3. 0.25 ms @</td> <td>90</td> <td>10</td> </tr> </tbody> </table>	Pulse Width	$V_{CC}$	$I_C$	<input type="text" value="ms"/>	<input type="text" value="V"/>	<input type="text" value="A"/>	1. 1 ms @	60	10	2. 0.5 ms @	80	10	3. 0.25 ms @	90	10
Pulse Width	$V_{CC}$	$I_C$																
<input type="text" value="ms"/>	<input type="text" value="V"/>	<input type="text" value="A"/>																
1. 1 ms @	60	10																
2. 0.5 ms @	80	10																
3. 0.25 ms @	90	10																
3.6.0	Maximum Operating Conditions for Switching between Saturation and Cutoff		For example refer to Appendix B															
3.6.1	Resistive Load	JS-6-T5.1 with $L = 0$ and CR disconnected $T_C =$ <input type="text" value="25 °C"/> ; Fig. 3 <u>Input Pulse Characteristics</u> Pulse Width <input type="text" value="1 ms"/> Duty Cycle <input type="text" value="2 %"/> $t_r$ <input type="text" value="≤ 5 μs"/> $t_f$ <input type="text" value="≤ 5 μs"/> $R_{BB1}$ <input type="text" value="3 Ω"/> $R_{BB2}$ <input type="text" value="5 Ω"/> $V_{BB1}$ <input type="text" value="6.2 V"/> $V_{BB2}$ <input type="text" value="0 V"/>	Supply graph of Safe Operating Area on the $I_C - V_{CE}$ plane. Safe Operating Area graph must include: $V_{CE}$ (3.2.3) $I_C$ (3.3.1)  If one test condition cannot satisfy $V_{CE}$ (3.2.3) and $I_C$ (3.3.1) specify conditions for each test.															
	OR																	

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.6.2	<div style="border: 1px dashed black; padding: 5px;">Clamped Inductive Load</div> <p style="text-align: center; margin-top: 20px;">OR</p>	<p>JS-6-T5.1</p> <p><math>T_C = 25\text{ }^\circ\text{C}</math> Fig. 4</p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <span style="border: 1px solid black; padding: 2px;">1 ms</span></p> <p>Duty Cycle <span style="border: 1px solid black; padding: 2px;">2 %</span></p> <p><math>t_r \leq 5\text{ }\mu\text{s}</math> <math>t_f \leq 5\text{ }\mu\text{s}</math></p> <p><math>R_{BB1}</math> <span style="border: 1px solid black; padding: 2px;">3 <math>\Omega</math></span></p> <p><math>R_{BB2}</math> <span style="border: 1px solid black; padding: 2px;">5 <math>\Omega</math></span></p> <p><math>V_{BB1}</math> <span style="border: 1px solid black; padding: 2px;">6.2 V</span></p> <p><math>V_{BB2}</math> <span style="border: 1px solid black; padding: 2px;">0 V</span></p> <p>L <span style="border: 1px solid black; padding: 2px;">1 mH</span></p> <p style="text-align: center;"><i>JEDEC</i></p> <p>CR1N1204 The/Type Number of the characteristics must be specified.</p>	<p>Supply graph of Safe Operating Area on the <math>I_C</math>-<math>V_{CE}</math> plane. Safe Operating Area graph must include:</p> <p><math>V_{CE}</math> (3.2.3)</p> <p><math>I_C</math> (3.3.1)</p> <p>If one test condition cannot satisfy <math>V_{CE}</math> (3.2.3) and <math>I_C</math> (3.3.1) specify conditions for each test.</p>
3.6.3	<div style="border: 1px dashed black; padding: 5px;">Unclamped Inductive Load</div>	<p>JS-6-T5.1 and CR Disconnected</p> <p><math>T_C = 25\text{ }^\circ\text{C}</math> Fig. 5</p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <span style="border: 1px solid black; padding: 2px;">20 ms</span></p> <p>Duty Cycle <span style="border: 1px solid black; padding: 2px;">30 %</span></p> <p><math>t_r \leq 5\text{ }\mu\text{s}</math> <math>t_f \leq 5\text{ }\mu\text{s}</math></p> <p><math>R_{BB1}</math> <span style="border: 1px solid black; padding: 2px;">3 <math>\Omega</math></span></p> <p><math>R_{BB2}</math> <span style="border: 1px solid black; padding: 2px;">5 <math>\Omega</math></span></p> <p><math>V_{BB1}</math> <span style="border: 1px solid black; padding: 2px;">9.2 V</span></p> <p><math>V_{BB2}</math> <span style="border: 1px solid black; padding: 2px;">5 V</span></p> <p>L <span style="border: 1px solid black; padding: 2px;">40 mH</span></p> <p>Q of L <span style="border: 1px solid black; padding: 2px;"><math>\geq 1500</math> @ <math>f = 1\text{ MHz}</math></span></p> <p><math>f_{\text{RESON}}</math> of L <span style="border: 1px solid black; padding: 2px;"><math>\geq 8\text{ MHz}</math></span></p> <p><math>I_C</math> <span style="border: 1px solid black; padding: 2px;">4.0 A</span></p> <p><math>V_{CC}</math> <span style="border: 1px solid black; padding: 2px;">22 V</span></p>	<p>For L = 6.4 mH; <math>I_C = 10\text{ A}</math></p> <p><math>I_C \geq I_C</math> (4.1.7)</p>

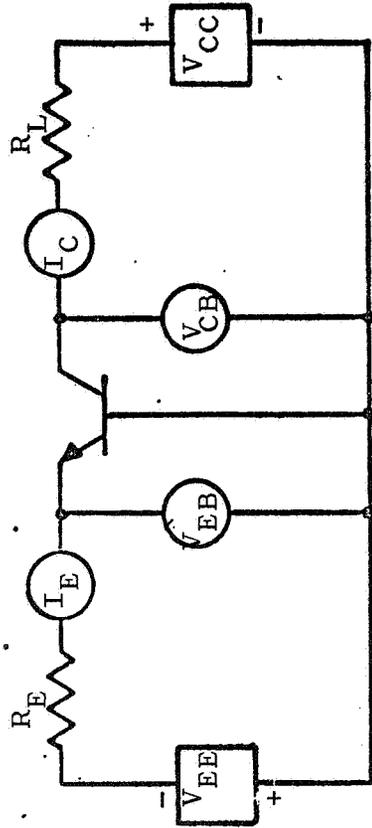
Item	Registered Data	Test Methods & Test Conditions	Remarks
4.0.0	Electrical Characteristics	$T_C = 25^{\circ}\text{C}$ (unless otherwise noted)	Maximum limits unless otherwise noted.
4.1.0	Static		Note 4
4.1.1	$I_{CEV}$ <input type="text" value="2"/> mA	$T_C$ <input type="text" value="150"/> $^{\circ}\text{C}$ $V_{CE}$ <input type="text" value="150"/> V  $V_{BE}$ (fwd., rev.) <input type="text" value="0"/> V  Technique <input type="text" value="C.T."/>	$T_C \geq 1/2 T_J$ (3.1.2)
4.1.2	$I_{CEV}$ <input type="text" value="0.5"/> mA  or  $I_{CBO}$ <input type="text" value=""/> mA  and  $V_{EBF}$ <input type="text" value=""/> V	$V_{CE}$ <input type="text" value="150"/> V  $V_{BE}$ (fwd., rev.) <input type="text" value="0"/> V  Technique <input type="text" value="C.T."/>  or	$V_{CE} \geq 0.9 V_{CBO}$ (3.2.1) Specify 4.1.2 or 4.1.3 and 4.1.4
4.1.3	$I_{CBO}$ <input type="text" value=""/> mA  and	$V_{CB}$ <input type="text" value=""/> V  and	$V_{CB} = V_{CBO}$ (3.2.1)
4.1.4	$V_{EBF}$ <input type="text" value=""/> V	$V_{CB}$ <input type="text" value=""/> V  Technique <input type="text" value=""/>	$V_{CB} = V_{CBO}$ (3.2.1)

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.1.5	$I_{EBO}$ <input type="text" value="0.01 mA"/>	$V_{EB}$ <input type="text" value="7 V"/> Technique <input type="text" value="C.T."/>	$V_{EB} = V_{EBO}$ (3.2.2)
4.1.6	$V_{(BR)CEO}$ <input type="text" value="100 Min V"/>	$I_C$ <input type="text" value="0.2 A"/> $I_B$ <input type="text" value="0 mA"/> Technique <input type="text" value="C.T."/>	Note 5
4.1.7	$h_{FE}$ <input type="text" value="20 Min"/> <input type="text" value="60 Max"/>	$V_{CE}$ <input type="text" value="2 V"/> $I_C$ <input type="text" value="4 A"/> Technique <input type="text" value="C.T."/>	$V_{CE} \leq 2.0V$ or $2 \times V_{CE(sat)}$ (4.1.8) whichever is greater
4.1.8	$V_{CE(sat)}$ <input type="text" value="0.75 Max V"/>	$I_C$ <input type="text" value="4 A"/> $I_B$ <input type="text" value="0.4 A"/> Technique <input type="text" value="C.T."/>	$I_C = I_C$ (4.1.7) Measured 0.064 inches from case.
4.1.9	$V_{BE(sat)}$ <input type="text" value="1.5 Max V"/>	$I_C$ <input type="text" value="4 A"/> $I_B$ <input type="text" value="0.4 A"/> Technique <input type="text" value="C.T."/>	$I_C = I_C$ (4.1.7) Measured 0.064 inches from case.
4.2.0	Dynamic		
4.2.1	$t_r$ <input type="text" value="μs"/>	$V_{CC}$ <input type="text"/> $I_C$ <input type="text"/> $I_{B1}$ <input type="text"/>	Specify 4.2.1, 4.2.2 and 4.2.3 or 4.2.4 and 4.2.5 $I_C = I_C$ (4.1.7) Switching circuit shall be attached. $I_{B1} = I_B$ (4.1.8)
4.2.2	$t_s$ <input type="text" value="μs"/>	$V_{CC}$ <input type="text"/> $I_C$ <input type="text"/> $I_{B1}$ <input type="text"/> $I_{B2}$ <input type="text"/>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.3	$t_f$ <input type="text" value="μs"/> or	$V_{CC}$ <input type="text"/> $I_C$ <input type="text"/> $I_{B1}$ <input type="text"/> $I_{B2}$ <input type="text"/>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.2.4	$t_{on}$ <span style="border: 1px dashed black; padding: 5px;">6.0 <math>\mu</math>s</span> and	$V_{CC}$ <span style="border: 1px solid black; padding: 2px;">31V</span> $I_C$ <span style="border: 1px solid black; padding: 2px;">4A</span> Fig. 6	$I_C = I_C$ (4.1.7)
4.2.5	$t_{off}$ <span style="border: 1px dashed black; padding: 5px;">8.0 <math>\mu</math>s</span>	$V_{CC}$ <span style="border: 1px solid black; padding: 2px;">31V</span> $I_C$ <span style="border: 1px solid black; padding: 2px;">4A</span> $I_{B1}$ <span style="border: 1px solid black; padding: 2px;">0.4A</span> $I_{B2}$ <span style="border: 1px solid black; padding: 2px;">-0.4A</span>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.6	$f_{hfe}$ <span style="border: 1px dashed black; padding: 5px;">[ ] kHz</span> or	$I_C$ <span style="border: 1px solid black; padding: 2px;">[ ] A</span> $V_{CE}$ <span style="border: 1px solid black; padding: 2px;">[ ] V</span>	Specify 4.2.6 or 4.2.7
4.2.7	$ h_{fe} $ <span style="border: 1px solid black; padding: 5px;">[ 8 min. ]</span> 40 max	$V_{CE}$ <span style="border: 1px solid black; padding: 2px;">4 V</span> $I_C$ <span style="border: 1px solid black; padding: 2px;">1 A</span>  $f$ <span style="border: 1px solid black; padding: 2px;">0.1 MHz</span>	Specify 4.2.6 or 4.2.7  Note 6
<u>ADDITIONAL DATA</u>			
3.6.4	Shorted Class B Safe Operating Area	Fig. 7 $I_{Cpeak} = 1A$ $R_S = 0.1\Omega$ ; $V_{CC} = 80V$ Input Characteristics $R_{BB1} = 1\Omega$ ; $R_{BB2} = 3\Omega$ $f = 20$ Hz; $T_C = 100^\circ C$	
3.6.5	$P_T = 120W$	JS-6-T12; $V_{CE} = 60V$ ; $I_C = 2A$ $t_p = 1s$ ; $T_A = 25^\circ C$	Single Pulse
3.6.6	$P_T = 120W$	JS-6-T12; $V_{CE} = 8V$ ; $I_C = 15A$ $t_p = 1s$ ; $T_A = 25^\circ C$	Single Pulse
4.1.10	$I_{CEO} = 100 \mu A$ max	$V_{CE} = 80V$ , Technique C.T.	
4.1.11	$V_{CES} = 125V$ min.	$I_C = 10$ mA; $R_{CC} = 5K \Omega$ Technique C.T.	
4.1.12	$V_{EBO} = 7V$ min.	$I_E = 10$ mA; $R_{BB} = 5K \Omega$ Technique C.T.	
4.1.13	$h_{FE} = 40$ min.	$I_C = 0.1A$ ; $V_{CE} = 2V$ ; Technique C.T.	
4.1.14	$V_{CE(sat)} = 1.2V$ max.	$I_C = 10A$ ; $I_B = 1A$ ; Technique C.T.	Measured 0.064 inches from case
4.1.15	$V_{BE(sat)} = 2.0V$ max.	$I_C = 10A$ ; $I_B = 1A$ ; Technique C.T.	
4.1.16	$V_{BE} = 1.4V$ max.	$I_C = 4A$ ; $V_{CE} = 2V$ ; Technique C.T.	

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.1.17	$V_{BE} = 0.55 \text{ V min.}$ $V_{BE} = 0.65 \text{ V max.}$	$I_C = 0.1\text{A}; V_{CE} = 2\text{V};$ Technique C.T.	Measured 0.064" from case
4.1.18	$h_{FE} = 40 \text{ min.}$	$I_C = 0.5\text{A}; V_{CE} = 2\text{V};$ Technique C.T.	
4.1.19	$h_{FE} = 15 \text{ min.}$	$I_C = 4\text{A}, V_{CE} = 2\text{V};$ Technique C.T. $T_C = -55^\circ\text{C}$	
4.1.20	$C_{obo} = 400 \text{ pF max.}$	$V_{CB} = 10\text{V}; f = 1 \text{ MHz}$	
4.3.0	$\theta_{JC} = 1^\circ\text{C/W max.}$	$I_C = 1\text{A}; V_{CE} = 20\text{V}$	
4.3.1	$\theta_{JA} = 25^\circ\text{C/W max.}$	$I_C = 1\text{A}; V_{CE} = 2\text{V}$	
4.3.2	$\tau_J = 15 \text{ ms}$	$I_C = 1\text{A}; V_{CE} = 20\text{V}$	Time to reach 63% of equilibrium temperature for $P_T$ step input.

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

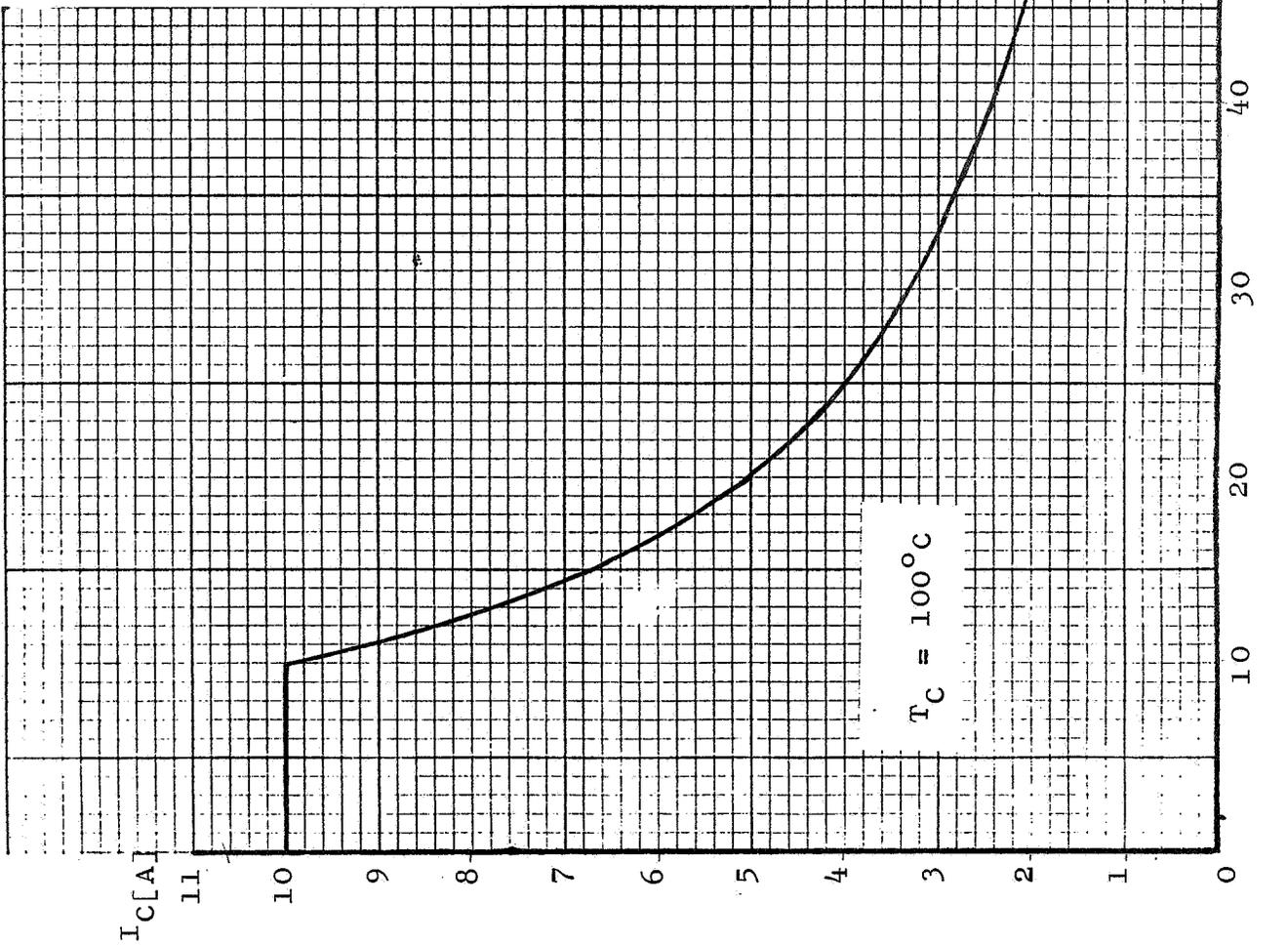


Figure 1

PULSED OPERATION - FORWARD BIASED PULSED SOAR

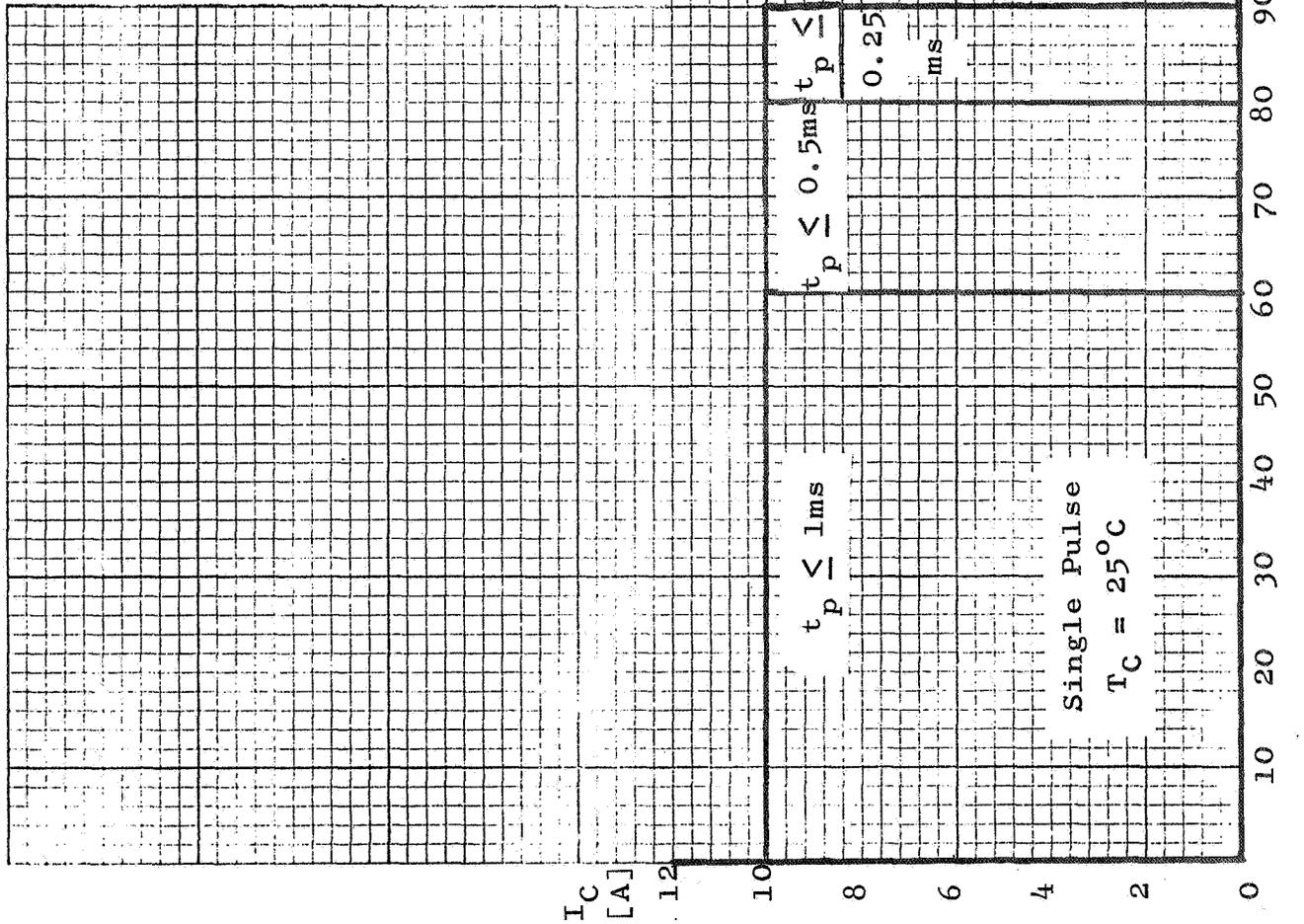
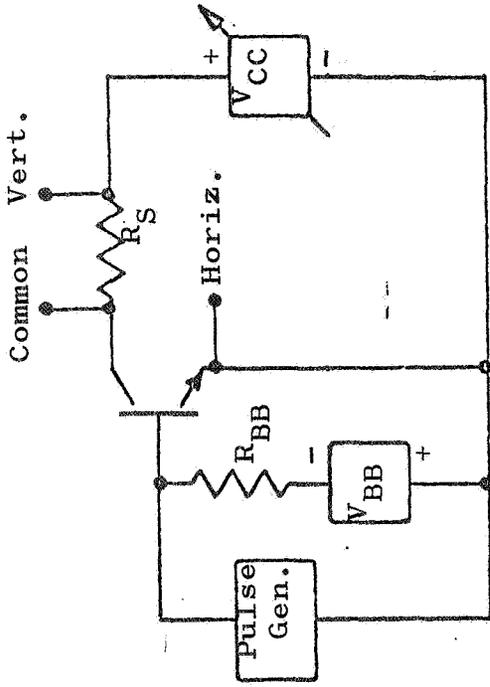
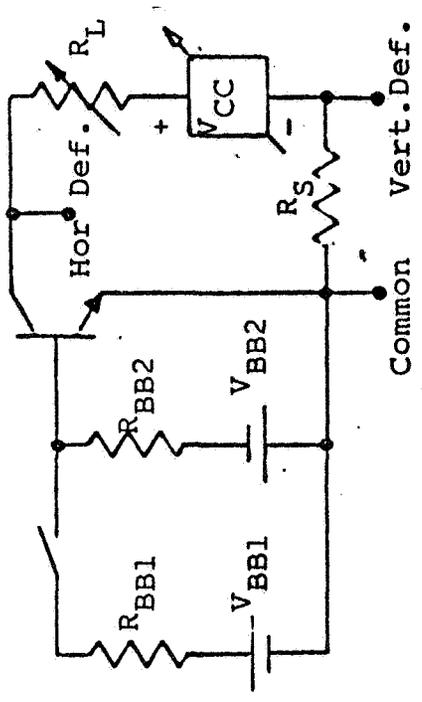
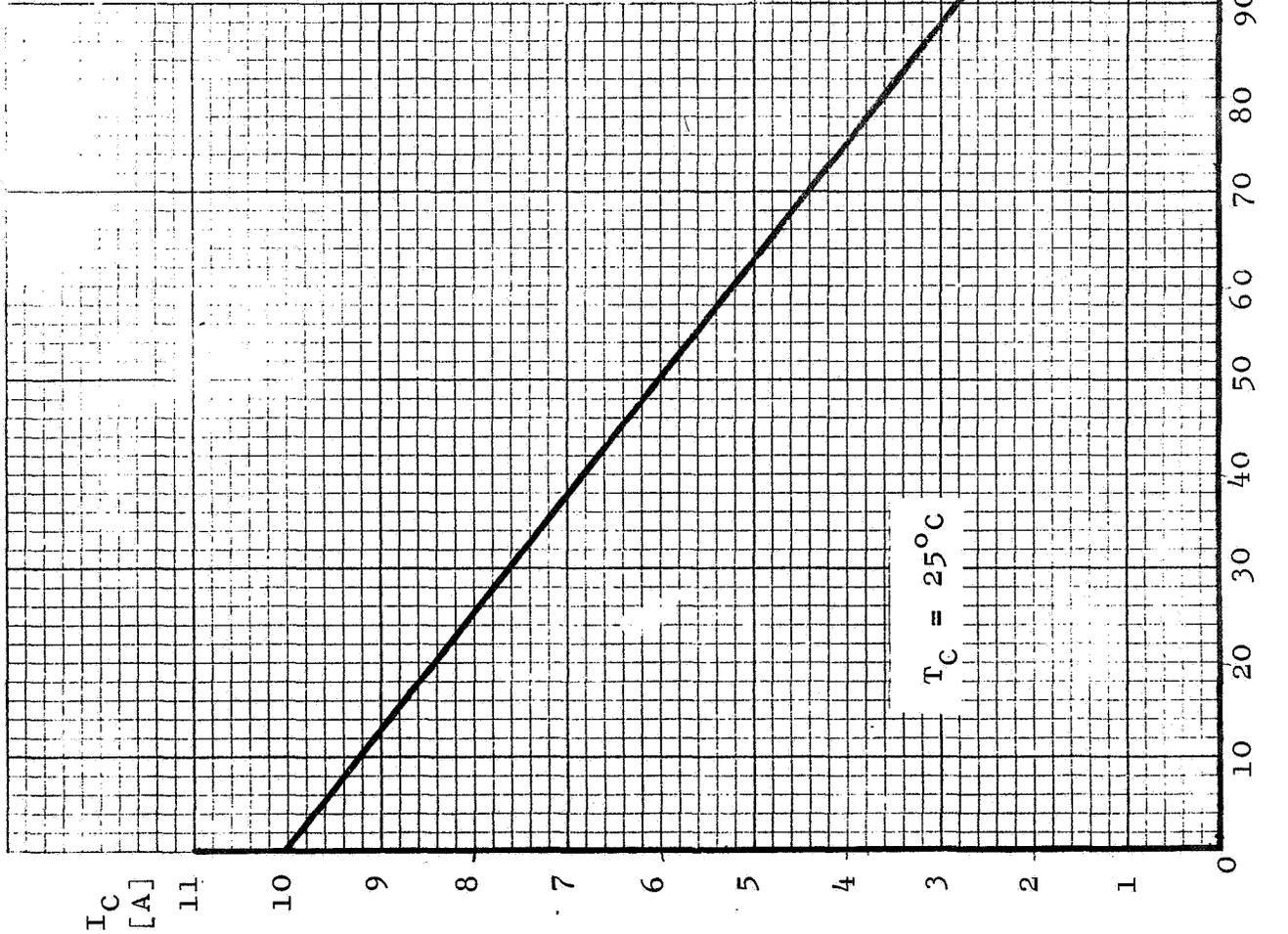


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

SOAR FOR SWITCHING BETWEEN SATURATION &  
CUTOFF - CLAMPED INDUCTIVE LOAD

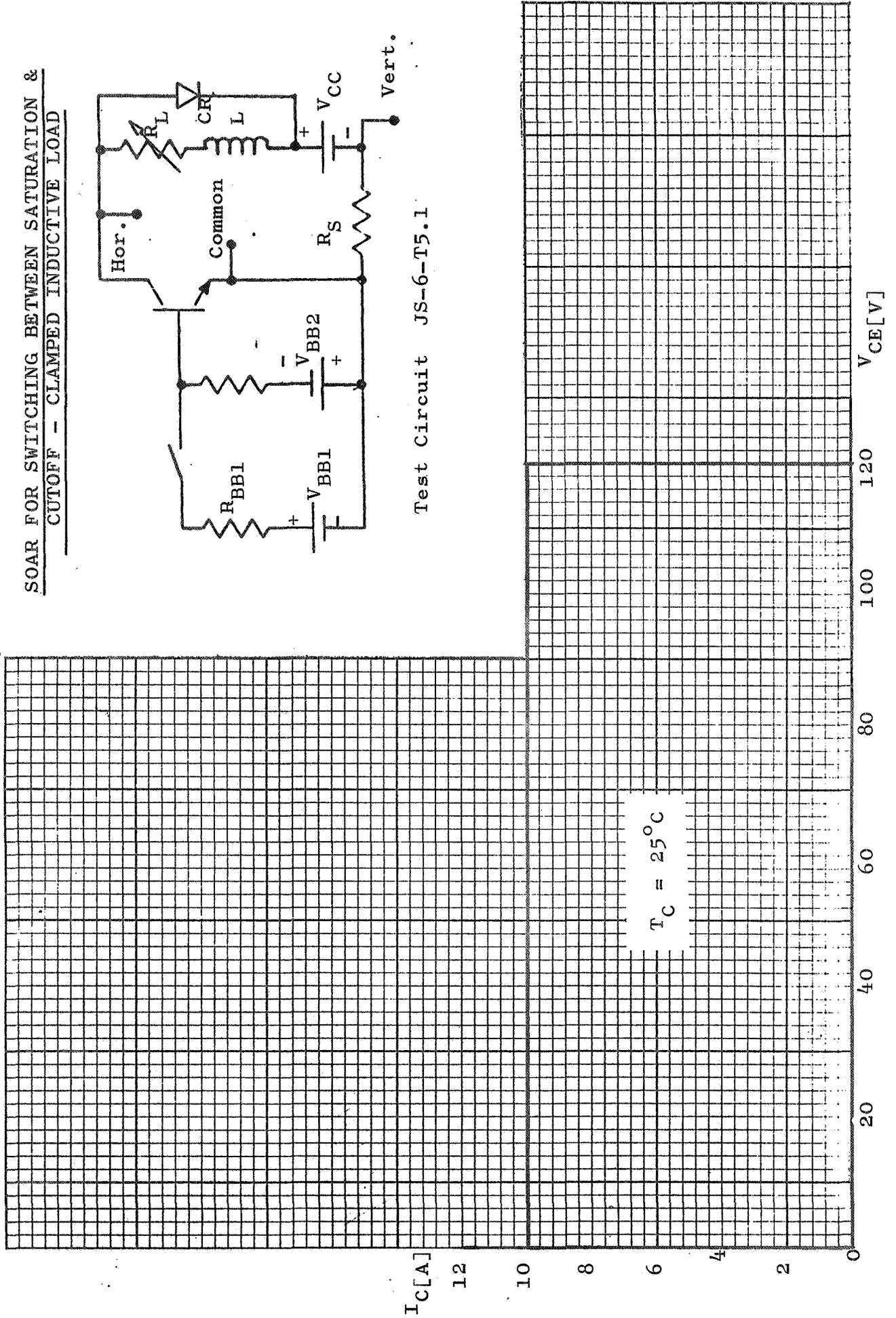
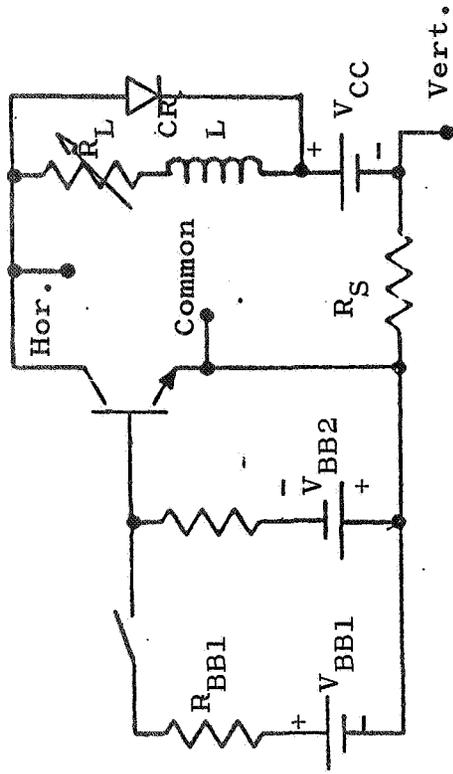
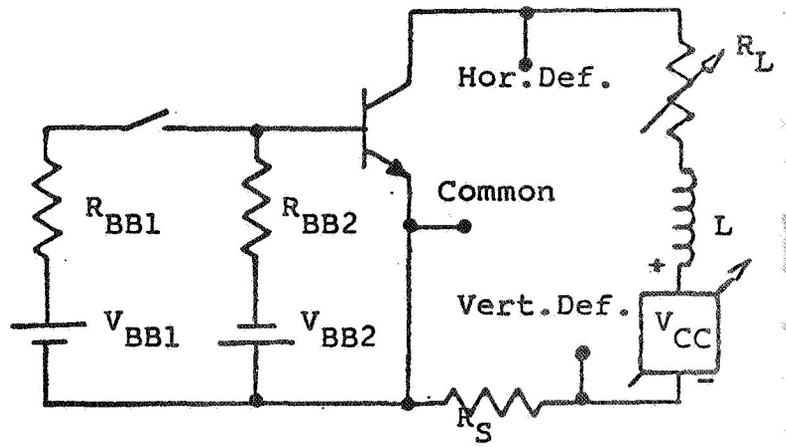


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

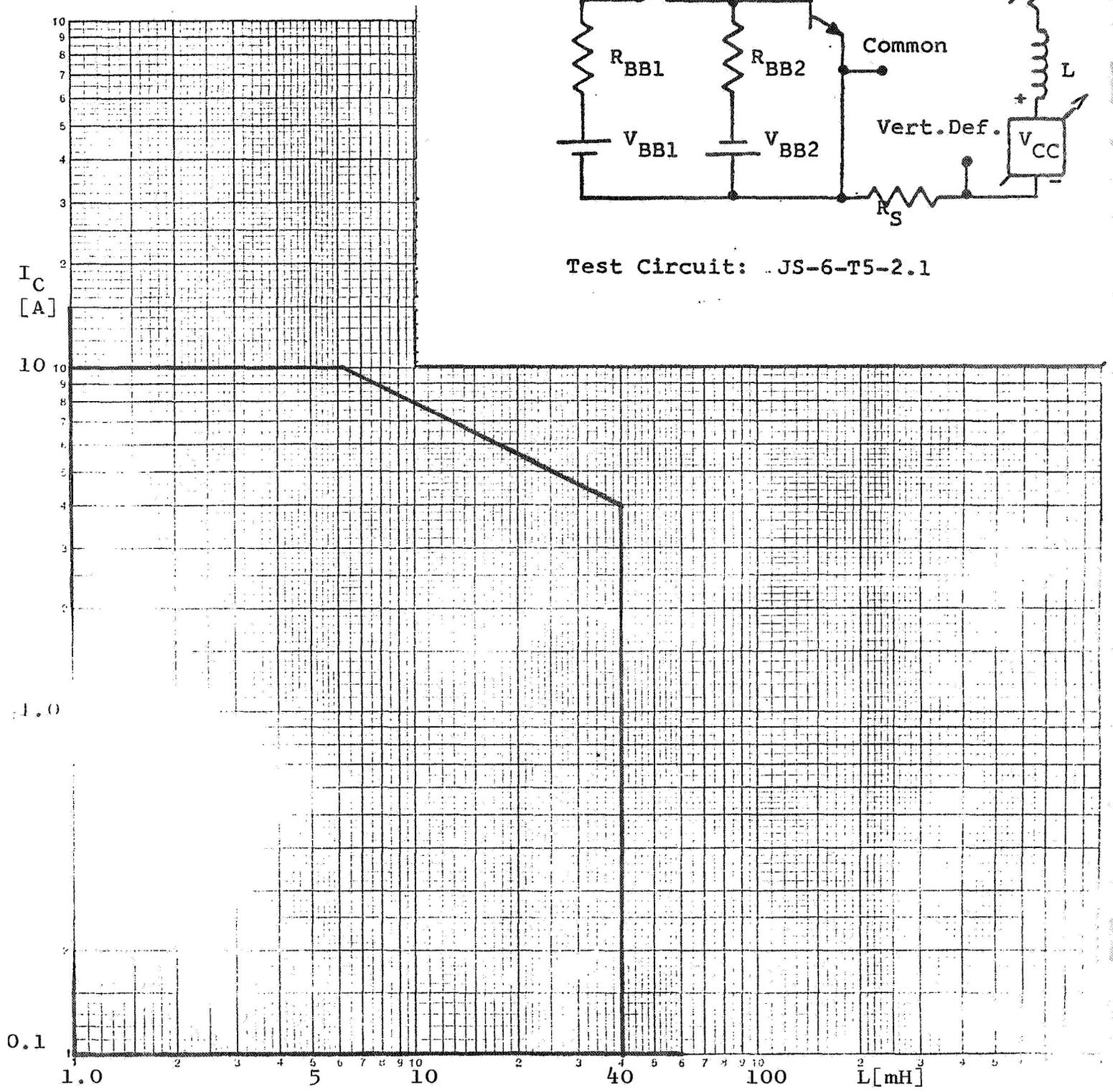


Figure 5

SWITCHING TEST CIRCUIT

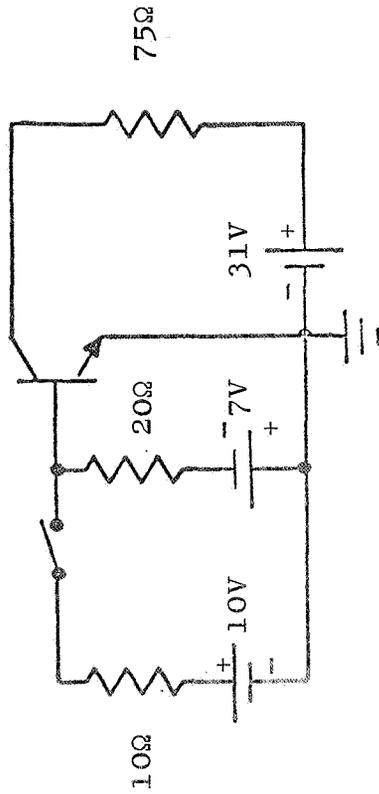
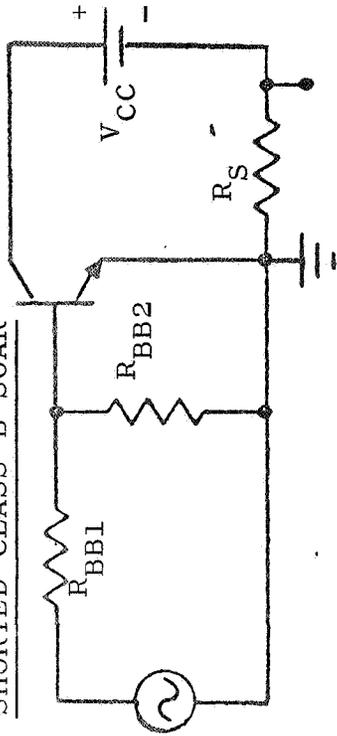
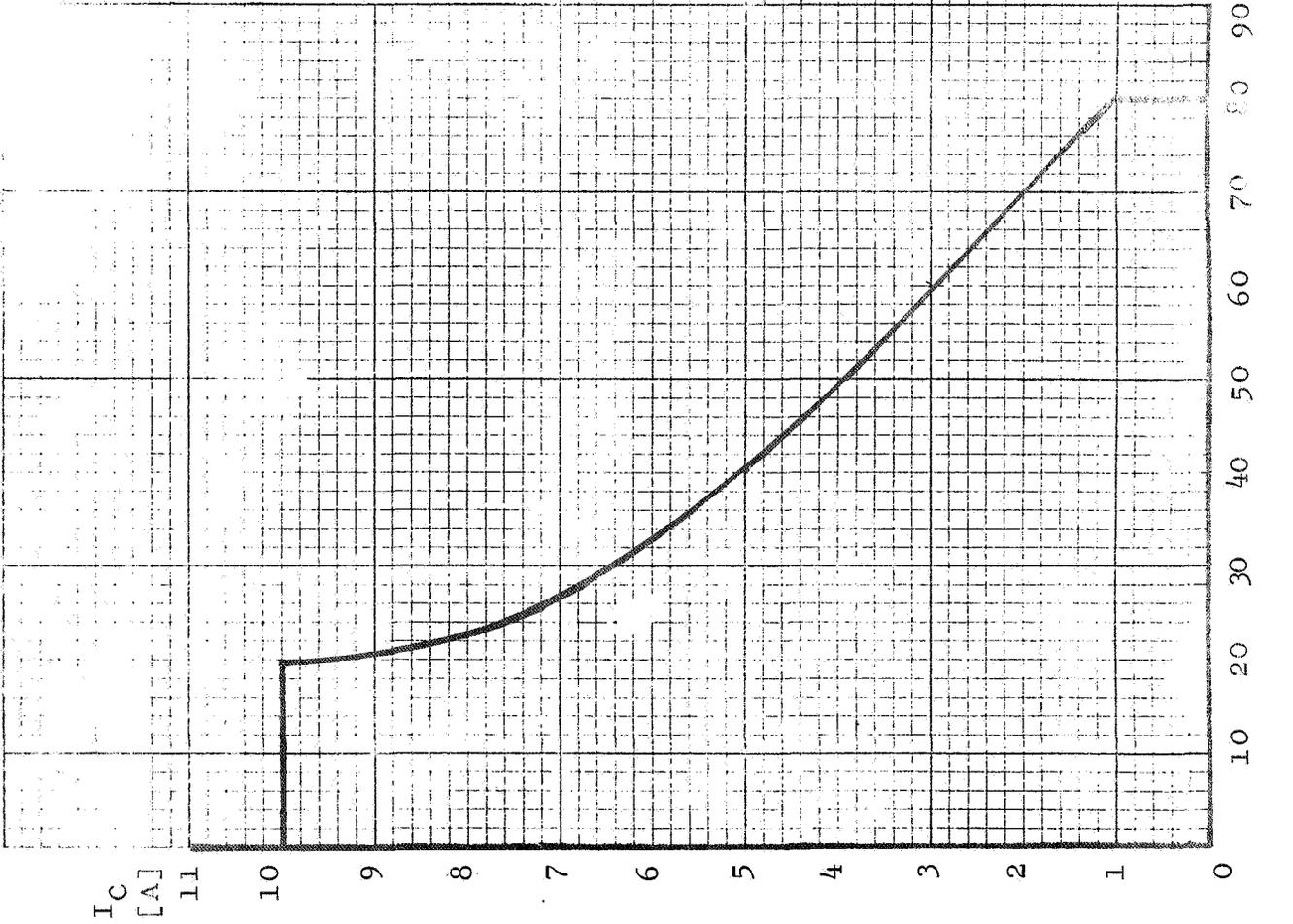


Figure 6

SHORTED CLASS B SOAR



Test Circuit:  $T_C \leq 100^\circ\text{C}$ ,  
 $f \geq 20\text{Hz}$



-- TEST REPORT --

SILICON POWER TRANSISTOR  
< 2N5560 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer Bendix --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

The format used in the presentation of this data  
was recently developed for the registration of  
transistor specifications.

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

JOINT ELECTRON DEVICE ENGINEERING COUNCIL REGISTRATION DATA - JS-6-RDF-1

Item	Registered Data	Test Methods & Test Conditions	Remarks
1.0.0	GENERAL DESCRIPTION		Triode Transistor Power Switching
1.1.0	Type <input type="text" value="NPN"/>		NPN, PNP, etc.
1.2.0	Material <input type="text" value="Silicon"/>		Ge., Si., etc.
2.0.0	MECHANICAL DATA		Note 1
2.1.0	Outline <input type="text" value="TO-63"/>		Note 2
2.2.0	Terminal Designation 1 <input type="text" value="Emitter"/> 2 <input type="text" value="Base"/> 3 <input type="text" value="Collector"/> case <input type="text" value="Collector"/>		Indicate all un-connected terminals as "NC".  Indicate "I" if all leads insulated from case.
3.0.0	MAXIMUM RATINGS		Note 3
3.1.0	Temperature		
3.1.1	T <sub>stg</sub> (max) <input type="text" value="200 °C"/>	JS-6-T1.2	Test Methods JS-6-T____ See "Test Procedures for Verification of Maximum Ratings of Power Transistors" JEDEC Publication No.65
	T <sub>stg</sub> (min) <input type="text" value="-65 °C"/>	JS-6-T1.1	
3.1.2	T <sub>J(max)</sub> <input type="text" value="200 °C"/>	JS-6-T2	
		T <sub>C</sub> <input type="text" value="150 °C"/> P <sub>T</sub> = 75W V <sub>CB</sub> <input type="text" value="≈ 4 V"/> I <sub>C</sub> <input type="text" value="15 A"/>	
3.1.3	T (Lead) <input type="text" value="230 °C"/>	Distance from case <input type="text" value="1/16 in."/> Time <input type="text" value="10 s"/>	Item 3.1.3 is not required on transistors whose storage temperature is sufficiently high so that the lead temperature test becomes redundant.

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.2.0	Voltage	$T_C = 25^\circ\text{C}$	
3.2.1	$V_{CBO}$ <input type="text" value="175 V"/>	JS-6-T3	
3.2.2	$V_{EBO}$ <input type="text" value="8 V"/>	JS-6-T4	
3.2.3	<div style="border: 1px solid black; padding: 5px; width: fit-content;"> <input type="text" value="120 V"/> </div>	<p>JS-6-T5.1</p> <p><math>I_C</math> (<math>V_{CE} = V_{CEX}</math>) <input type="text" value="30 A"/></p> <p><math>V_{CC}</math> <input type="text" value="120 V"/> <math>R_L</math> <input type="text" value="3.8 &lt;math&gt;\Omega&lt;/math&gt;"/></p> <p><math>L</math> <input type="text" value="1 mH"/> <math>CR</math> <input type="text" value="1N1202"/></p> <p><math>V_{BB1}</math> <input type="text" value="12.2 V"/> <math>R_{BB1}</math> <input type="text" value="3 &lt;math&gt;\Omega&lt;/math&gt;"/></p> <p><math>V_{BB2}</math> <input type="text" value="6 V"/> <math>R_{BB2}</math> <input type="text" value="20 &lt;math&gt;\Omega&lt;/math&gt;"/></p> <p>Pulse Width <input type="text" value="1 ms"/> Duty Cycle <input type="text" value="2 %"/></p> <p style="text-align: center;">or</p> <p>JS-6-T5.2</p> <p><math>I_C</math> <input type="text" value=""/> <math>R_{BB}</math> <input type="text" value=""/></p> <p><math>V_{BB(\text{off})}</math> <input type="text" value=""/></p> <p>Pulse Width <input type="text" value=""/> <math>\mu\text{s}</math> Duty Cycle <input type="text" value=""/></p>	<p>Inductive Method</p> <p><math>R_{BB2}</math> may be infinite</p> <p><math>V_{BB2}</math> may be zero</p> <p>Equivalent registered type number of CR, if used, must be given.</p> <p>Pulsed Method</p> <p><math>R_{BB}</math> may be zero</p>

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.0	Current		
3.3.1	$I_C$ <input type="text" value="30"/> A	JS-6-T6 $I_B$ <input type="text" value="3"/> A $T_C$ <input type="text" value="≤ 25 °C"/>	Continuous collector current
3.3.2	$I_{CM}$ <input type="text" value="4"/> A	JS-6-T7 $T_C = 25^\circ\text{C}$ $R_S$ <input type="text" value=""/> $\Omega$ $V_{BB}$ <input type="text" value=""/> V $R_{BB}$ <input type="text" value=""/> $\Omega$ <u>Input Pulse Characteristics</u> Pulse Amplitude <input type="text" value=""/> V Pulse Width <input type="text" value=""/> ms Duty Cycle <input type="text" value=""/> % $t_r$ <input type="text" value=""/> $\mu\text{s}$ $t_f$ <input type="text" value=""/> $\mu\text{s}$	Peak collector current
3.3.3	$I_B$ <input type="text" value="10"/> A	JS-6-T8 $T_C$ <input type="text" value="≤ 25 °C"/>	Continuous base current
3.3.4	$I_{BM}$ <input type="text" value="4"/> A	JS-6-T9 $T_C = 25^\circ\text{C}$ <u>Input Pulse Characteristics</u> Pulse Width <input type="text" value=""/> ms Duty Cycle <input type="text" value=""/> % $t_r$ <input type="text" value=""/> $\mu\text{s}$ $t_f$ <input type="text" value=""/> $\mu\text{s}$	Peak base current
3.3.5	$I_E$ <input type="text" value="33"/> A	JS-6-T10 $I_B$ <input type="text" value="3"/> A $T_C$ <input type="text" value="25 °C"/>	Continuous Emitter current

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.6	$I_{EM}$ [ ] A	JS-6-T11  $T_C = 25^\circ\text{C}$ $R_S$ [ ] $\Omega$  $V_{BB}$ [ ] V $R_{BB}$ [ ] $\Omega$  <u>Input Pulse Characteristics</u>  Pulse Width [ ] $\mu\text{s}$  Duty Cycle [ ] %  $t_r \leq$ [ ] $\mu\text{s}$ $t_f \leq$ [ ] $\mu\text{s}$	Peak Emitter Current
3.4.0	Power		
3.4.1	$P_T$ [ 150 W ]	JS-6-T12  $T_C$ [ 100 $^\circ\text{C}$ ]  $V_{CB}$ [ 4 V ] $I_C$ [ 30 A ]  Derating Factor [ 1.5 W/ $^\circ\text{C}$ ]	$T_C = 55^\circ\text{C}$ (for device with $T_J(\text{max}) \leq 125^\circ\text{C}$ )  $T_C = 100^\circ\text{C}$ (for devices with $T_J(\text{max}) > 125^\circ\text{C}$ )
3.4.2	$P_{TM}$ [ 3600 W ]	JS-6-T13  $T_C = 25^\circ\text{C}$  $V_{CC}$ [ 120 V ]  $V_{EB}$ [ 6 V ] $R_{EB}$ [ 20 $\Omega$ ]  <u>Input Pulse Characteristics</u>  Pulse Width [ 0.125 ms ]  Duty Cycle [ 0.4 % ]  $t_r \leq$ [ 5 $\mu\text{s}$ ] $t_f \leq$ [ 5 $\mu\text{s}$ ]	$P_{TM} = I_C V_{CC}$



Item	Registered Data	Test Methods & Test Conditions	Remarks
3.6.2	<div style="border: 1px dashed black; padding: 5px; margin-bottom: 10px;">Clamped Inductive Load</div> <p style="text-align: center;">OR</p>	<p>JS-6-T5.1; Fig. 4</p> <p><math>T_C = 25\text{ }^\circ\text{C}</math></p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <math>2\text{ ms}</math></p> <p>Duty Cycle <math>2\%</math></p> <p><math>t_r \leq 5\text{ }\mu\text{s}</math>    <math>t_f \leq 5\text{ }\mu\text{s}</math></p> <p><math>R_{BB1} 3\text{ }\Omega</math></p> <p><math>R_{BB2} 20\text{ }\Omega</math></p> <p><math>V_{BB1} 12.2\text{ V}</math></p> <p><math>V_{BB2} 6\text{ V}</math></p> <p><math>L 1\text{ mH}</math></p> <p style="text-align: center;">JEDEC</p> <p>CR 1N1202 <u>Part/Type Number of the characteristics must be specified.</u></p>	<p>Supply graph of Safe Operating Area on the <math>I_C</math>-<math>V_{CE}</math> plane. Safe Operating Area graph must include:</p> <p><math>V_{CE} (3.2.3) = 120\text{V}</math></p> <p><math>I_C (3.3.1) = 30\text{A}</math></p> <p>If one test condition cannot satisfy <math>V_{CE} (3.2.3)</math> and <math>I_C (3.3.1)</math> specify conditions for each test.</p>
3.6.3	<div style="border: 1px dashed black; padding: 5px;">Unclamped Inductive Load</div>	<p>JS-6-T5.1 and CR Disconnected</p> <p><math>T_C = 25\text{ }^\circ\text{C}</math>; Fig. 5</p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <math>5\text{ ms}</math></p> <p>Duty Cycle <math>5\%</math></p> <p><math>t_r \leq 5\text{ }\mu\text{s}</math>    <math>t_f \leq 5\text{ }\mu\text{s}</math></p> <p><math>R_{BB1} 3\text{ }\Omega</math></p> <p><math>R_{BB2} 20\text{ }\Omega</math></p> <p><math>V_{BB1} 12.2\text{ V}</math></p> <p><math>V_{BB2} 6\text{ V}</math></p> <p><math>L 10\text{ mH}</math></p> <p><math>Q\text{ of } L \geq 1500</math></p> <p><math>f_{\text{RESON}}\text{ of } L \geq 9.5\text{ MHz}</math></p> <p><math>I_C 1.4\text{ A}</math></p> <p><math>V_{CC} 36\text{ V}</math></p>	<p>For <math>L = 0.1\text{ mH}</math>; <math>I_C = 30\text{A}</math></p> <p><math>I_C \geq I_C (4.1.7)</math></p>

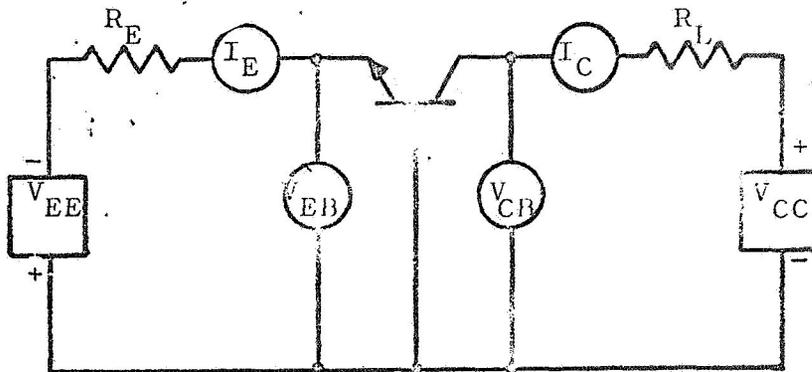
Item	Registered Data	Test Methods & Test Conditions	Remarks
4.0.0	Electrical Characteristics	$T_C = 25^{\circ}\text{C}$ (unless otherwise noted)	Maximum limits unless otherwise noted.
4.1.0	Static		Note 4
4.1.1	$I_{CEV}$ <span style="border: 1px solid black; padding: 2px;">0.100 mA</span>	$T_C$ <span style="border: 1px solid black; padding: 2px;">125 °C</span> $V_{CZ}$ <span style="border: 1px solid black; padding: 2px;">100 V</span>	$T_C \geq 1/2 T_J$ (3.1.2)
		$V_{BE}$ (fwd., rev.) <span style="border: 1px solid black; padding: 2px;">0 V</span>	
		Technique <span style="border: 1px solid black; padding: 2px;">G.T.</span>	
4.1.2	$I_{CEV}$ <span style="border: 1px dashed black; padding: 2px;">1.0 mA</span>	$V_{CE}$ <span style="border: 1px solid black; padding: 2px;">175 V</span>	$V_{CE} \geq 0.9 V_{CBO}$ (3.2.1) Specify 4.1.2 or 4.1.3 and 4.1.4
		$V_{BE}$ (fwd., rev.) <span style="border: 1px solid black; padding: 2px;">0 V</span>	
		Technique <span style="border: 1px solid black; padding: 2px;">G.T.</span>	
	or	or	
4.1.3	$I_{CBO}$ <span style="border: 1px dashed black; padding: 2px;">  mA</span>	$V_{CB}$ <span style="border: 1px solid black; padding: 2px;">  V</span>	$V_{CB} = V_{CBO}$ (3.2.1)
	and	and	
4.1.4	$V_{EBF}$ <span style="border: 1px dashed black; padding: 2px;">  V</span>	$V_{CB}$ <span style="border: 1px solid black; padding: 2px;">  V</span>	$V_{CB} = V_{CBO}$ (3.2.1)
		Technique <span style="border: 1px solid black; padding: 2px;">  </span>	

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.1.5	$I_{EBO}$ <input type="text" value="0.010 mA"/>	$V_{EB}$ <input type="text" value="8 V"/> Technique <input type="text" value="C.T."/>	$V_{EB} = V_{EBO}$ (3.2.2)
4.1.6	$V_{(BR)CEO}$ <input type="text" value="120 Min V"/>	$I_C$ <input type="text" value="25 mA"/> $I_B$ <input type="text" value="0 mA"/> Technique <input type="text" value="C.T."/>	Note 5
4.1.7	$h_{FE}$ <input type="text" value="30 Min"/> <input type="text" value="90 Max"/>	$V_{CE}$ <input type="text" value="2 V"/> $I_C$ <input type="text" value="15 A"/> Technique <input type="text" value="C.T."/>	$V_{CE} \leq 2.0V$ or $2 \times V_{CE(sat)}$ (4.1.8) whichever is greater
4.1.8	$V_{CE(sat)}$ <input type="text" value="0.8 Max V"/>	$I_C$ <input type="text" value="15 A"/> $I_B$ <input type="text" value="1.5 A"/> Technique <input type="text" value="C.T."/>	$I_C = I_C$ (4.1.7) Measured 5/16" from case.
4.1.9	$V_{BE(sat)}$ <input type="text" value="1.3 Max V"/>	$I_C$ <input type="text" value="15 A"/> $I_B$ <input type="text" value="1.5 A"/> Technique <input type="text" value="C.T."/>	$I_C = I_C$ (4.1.7)
4.2.0	Dynamic		
4.2.1	$t_T$ <input type="text" value=""/> $\mu s$	$V_{CC}$ <input type="text" value=""/> $I_C$ <input type="text" value=""/> $I_{B1}$ <input type="text" value=""/>	Specify 4.2.1, 4.2.2 and 4.2.3 or 4.2.4 and 4.2.5 $I_C = I_C$ (4.1.7) Switching circuit shall be attached. $I_{B1} = I_B$ (4.1.8)
4.2.2	$t_S$ <input type="text" value=""/> $\mu s$	$V_{CC}$ <input type="text" value=""/> $I_C$ <input type="text" value=""/> $I_{B1}$ <input type="text" value=""/> $I_{B2}$ <input type="text" value=""/>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.3	$t_F$ <input type="text" value=""/> $\mu s$ or	$V_{CC}$ <input type="text" value=""/> $I_C$ <input type="text" value=""/> $I_{B1}$ <input type="text" value=""/> $I_{B2}$ <input type="text" value=""/>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.2.4	$t_{on}$ <div style="border: 1px dashed black; padding: 5px; margin: 5px 0;"> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1.0 <math>\mu</math>s</div> </div> <p style="text-align: center;">end</p>	$V_{CC}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">31 V</div> $I_C$ <div style="border: 1px solid black; padding: 2px; display: inline-block;"><math>\approx 15A</math></div> $I_{B1}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;"><math>\approx 1.5 A</math></div> Fig. 6	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.5	$t_{off}$ <div style="border: 1px solid black; padding: 5px; margin: 5px 0;"> <div style="border: 1px solid black; padding: 2px; display: inline-block;">2.0 <math>\mu</math>s</div> </div>	$V_{CC}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">31 V</div> $I_C$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">15 A</div> $I_{B1}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;"><math>\approx 1.5 A</math></div> $I_{B2}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;"><math>\approx 1.5 A</math></div>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.6	$f_{hfe}$ <div style="border: 1px solid black; padding: 5px; margin: 5px 0;"> <div style="border: 1px dashed black; padding: 2px; display: inline-block;">[ ] kHz</div> <p style="text-align: center;">or</p> </div>	$I_C$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">A</div> $V_{CE}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">V</div>	Specify 4.2.6 or 4.2.7
4.2.7	$ h_{fe} $ <div style="border: 1px solid black; padding: 5px; margin: 5px 0;"> <div style="border: 1px solid black; padding: 2px; display: inline-block;">8 min</div>  <div style="border: 1px solid black; padding: 2px; display: inline-block;">20 max</div> </div>	$V_{CE}$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">10 V</div> $I_C$ <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 A</div>  <div style="border: 1px solid black; padding: 2px; display: inline-block; margin: 10px auto;">5 kHz</div>	Specify 4.2.6 or 4.2.7  Note 6

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.6.4	<u>ADDITIONAL DATA</u> Shorted Class B Safe Operating Area	Fig. 7 $R_S = 0.1\Omega$ 1. $I_C = 1.1A$ ; $V_{CC} = 60V$ 2. $I_C = 390\text{ mA}$ ; $V_{CC} = 120V$ Input Characteristics $R_{BB1} = 1\Omega$ ; $R_{BB2} = 3\Omega$ $f = 20\text{ Hz}$ ; $T_C = 100^\circ C$	
3.6.5	$P_T = 40W$	JS-6-T12; $V_{CE} = 60$ ; $I_C = 0.66A$ $t_p = 1s$ ; $T_A = 25^\circ C$	
4.1.10	$I_{CEO} = 25\ \mu A$ max.	$V_{CE} = 80V$ Technique C.T.	
4.1.11	$V_{CES} = 125V$ min.	$I_C = 10\text{ mA}$ ; $R_{CC} = 500\Omega$ Technique C.T.	
4.1.12	$V_{EBO} = 8V$ min	$I_E = 200\text{ mA}$ ; $R_{BB} = 500\Omega$ Technique C.T.	
4.1.13	$h_{FE} = 40$ min	$I_C = 0.1A$ ; $V_{CE} = 2V$ Technique C.T.	
4.1.14	$h_{FE} = 40$ min $h_{FE} = 100$ max	$I_C = 5A$ ; $V_{CE} = 1.5V$	
4.1.15	$h_{FE} = 10$ min	$I_C = 15A$ ; $V_{CE} = 2V$	After exposure level of $\phi = 1 \times 10^{13}$ nvt (Total integrated neutron flux with energy levels greater than 10 KeV)
4.1.16	$V_{CE(sat)} = 1.5V$ max	$I_C = 30A$ ; $I_B = 3A$ ; Technique C.T.	} Measured 5/16" from case.
4.1.17	$V_{BE(sat)} = 2.0V$ max	$I_C = 30A$ ; $I_B = 3A$ ; Technique C.T.	
4.1.18	$C_{obo} = 600\text{ pF}$ max.	$V_{CB} = 10V$ ; $f = 1\text{ MHz}$	
4.3.0	$\theta_{JC} = 0.67^\circ C/W$ max.	$I_C = 1A$ ; $V_{CE} = 20V$	
4.3.1	$\theta_{JA} = 30^\circ C/W$	$I_C = 1A$ ; $V_{CE} = 2V$	
4.3.2	$\tau_J = 25\text{ ms}$ min.	$I_C = 1A$ ; $V_{CE} = 20V$	Time to reach 63% of equilibrium temperature for $P_T$ step input.

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CE0}$

Test Circuit: JS-6-T12

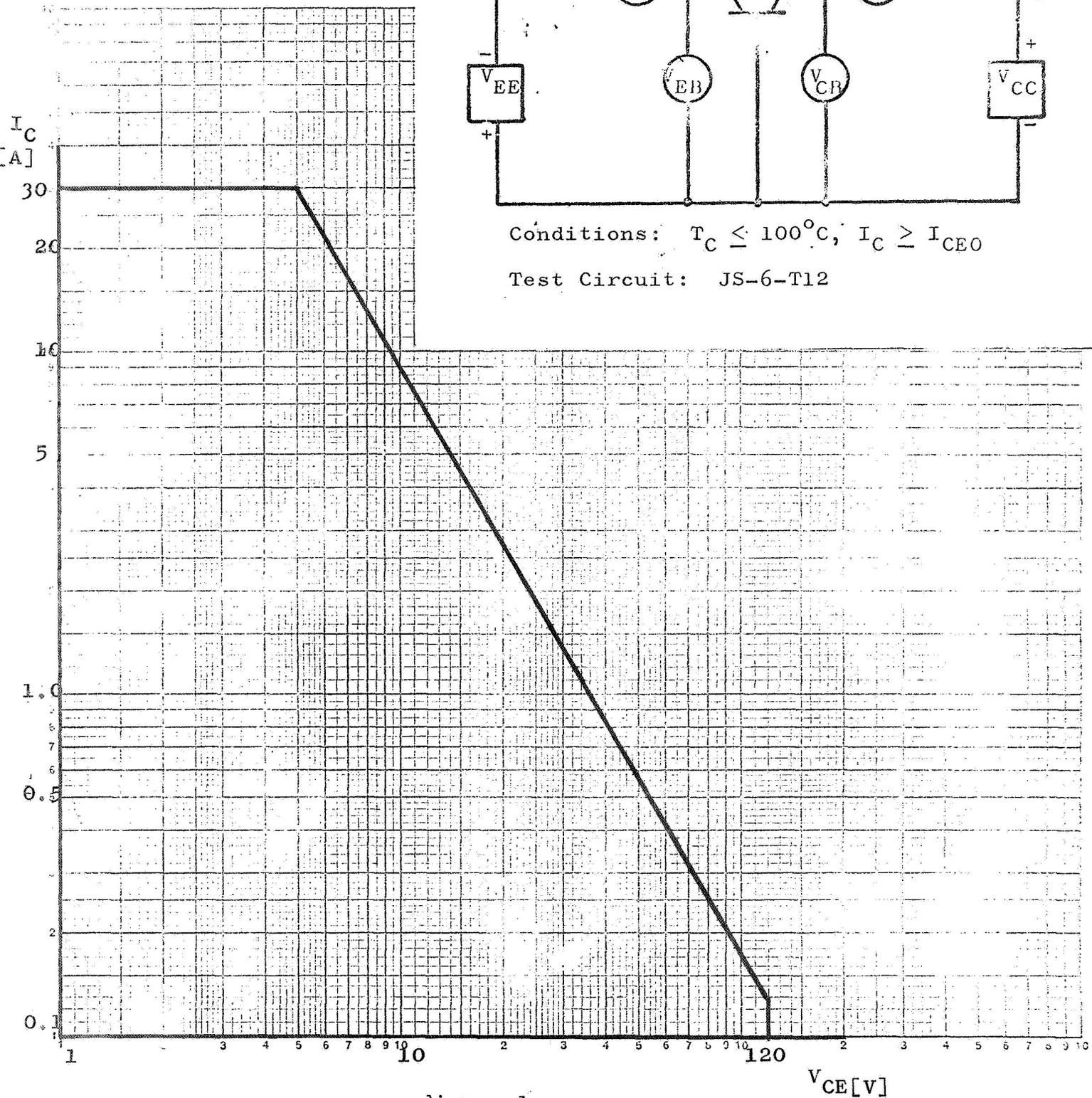
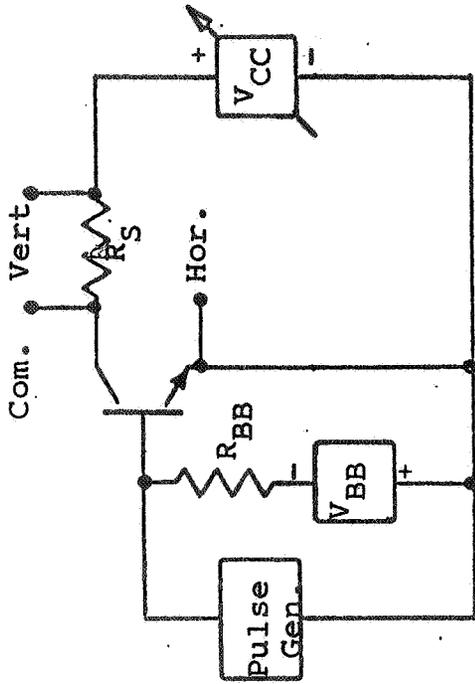


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

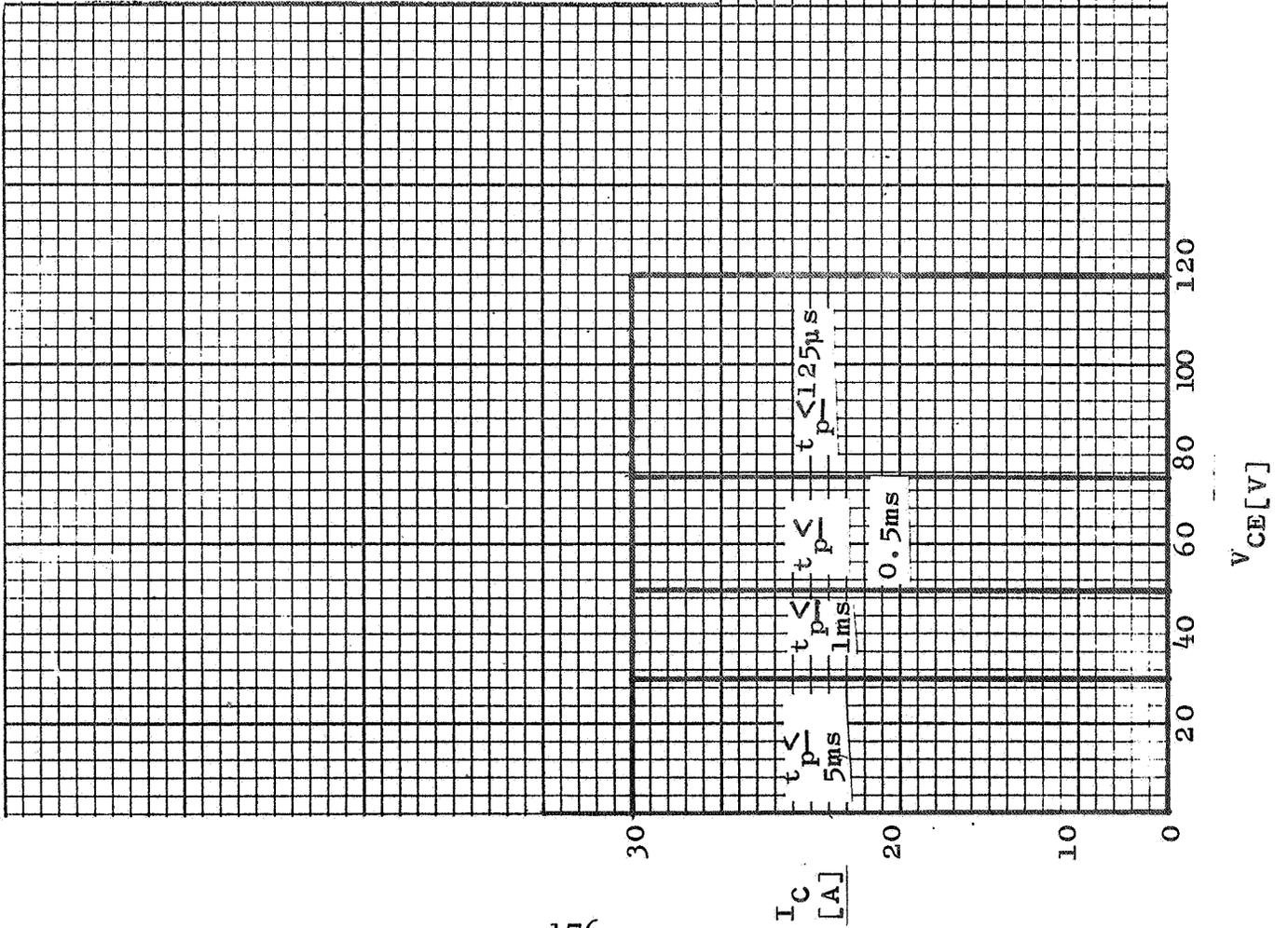
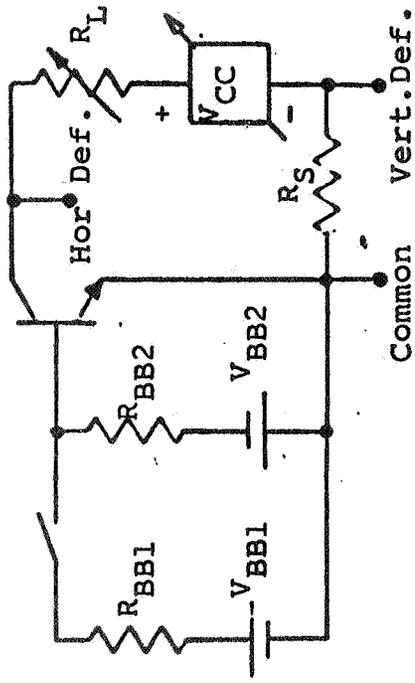


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

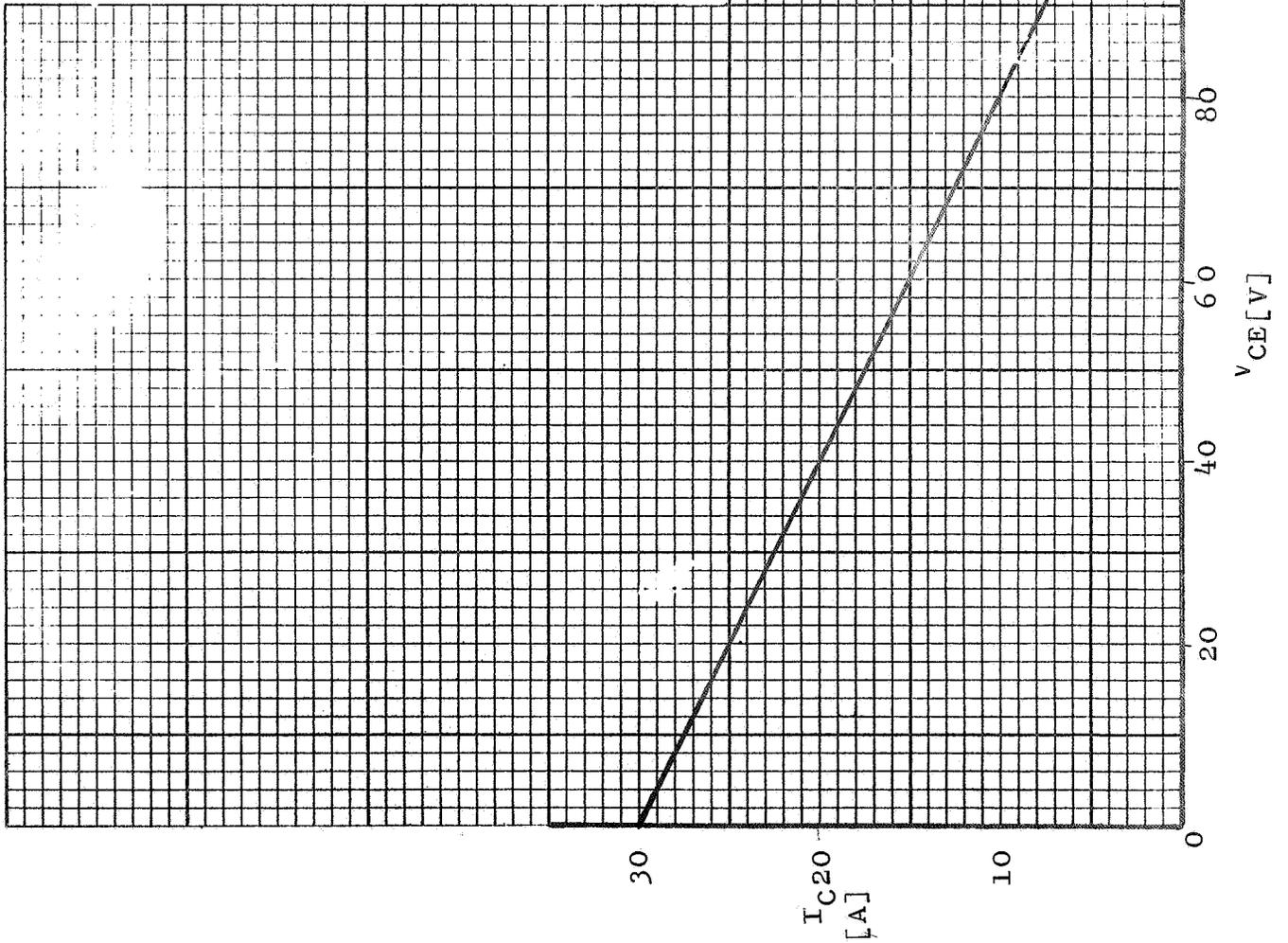


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-CLAMPED INDUCTIVE LOAD

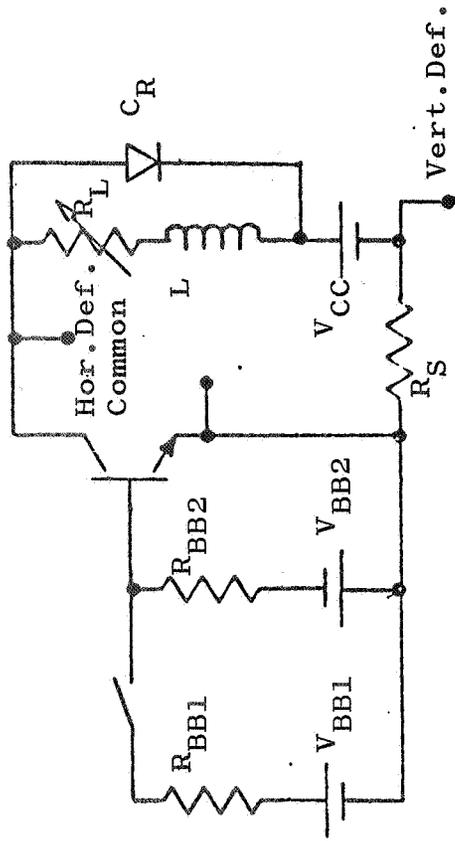
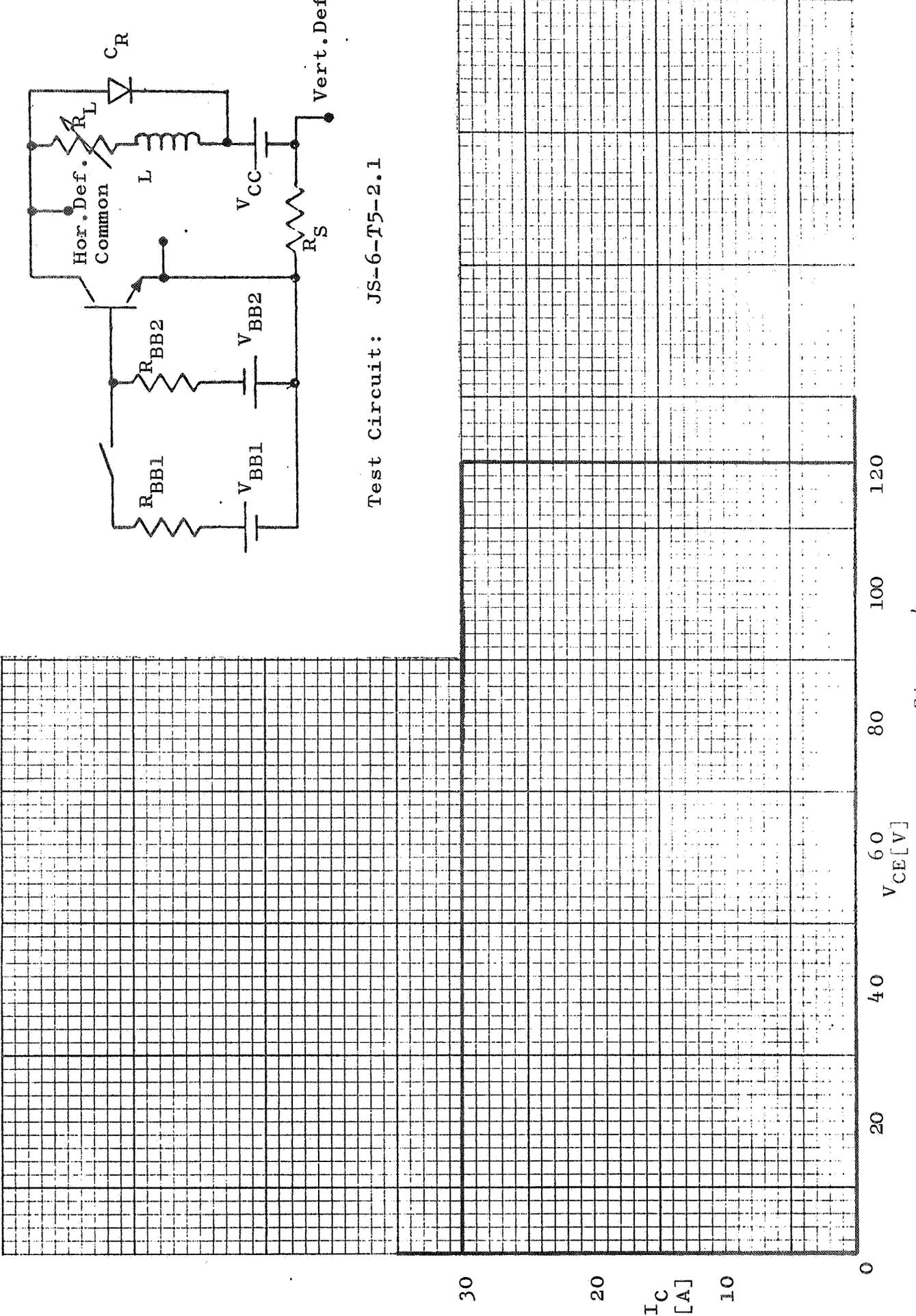
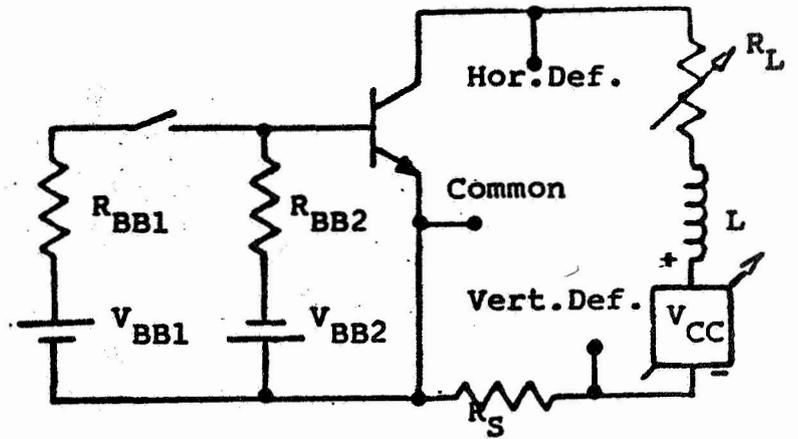


Figure 4

**SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD**



Test Circuit: JS-6-T5-2.1

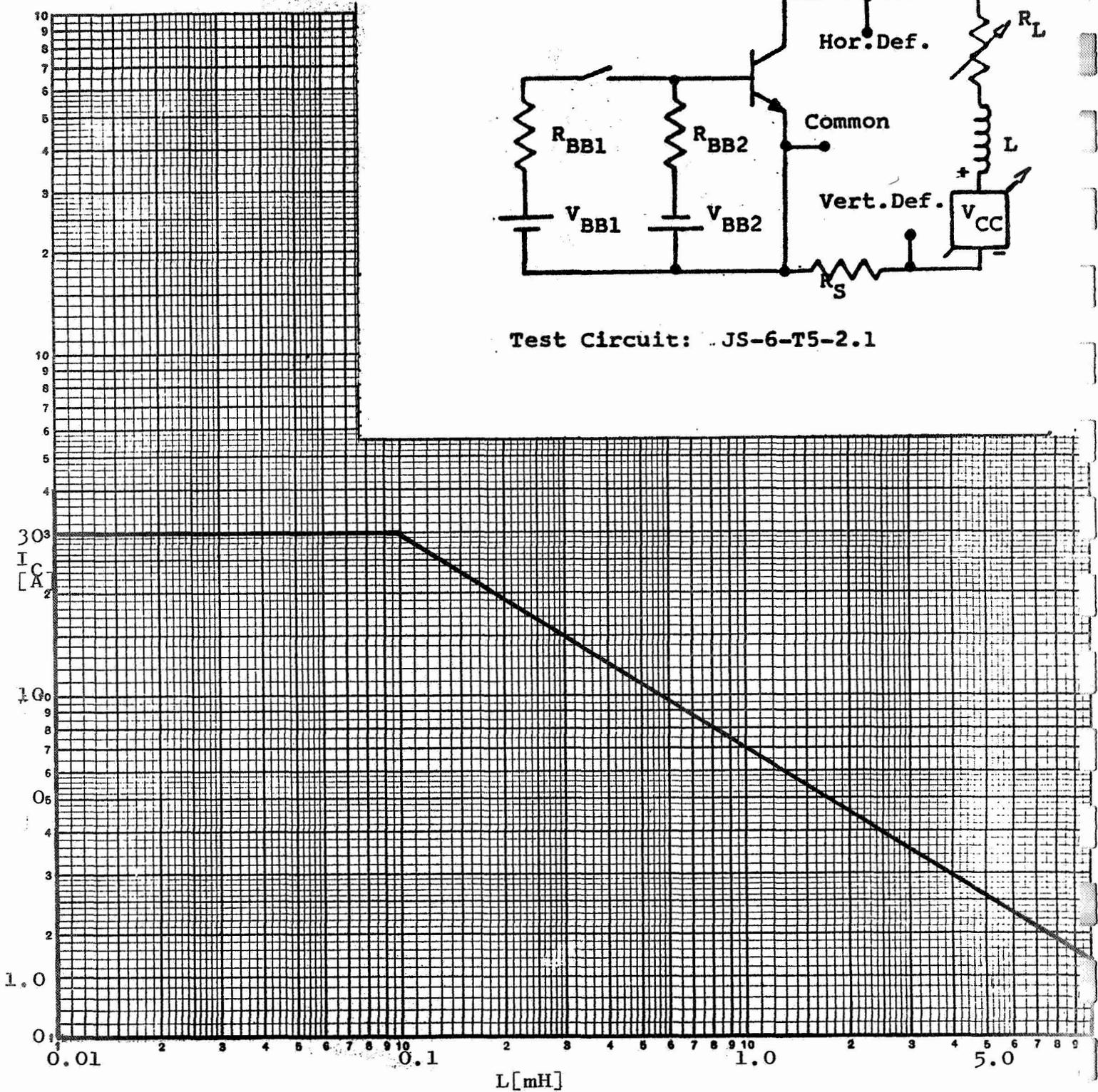
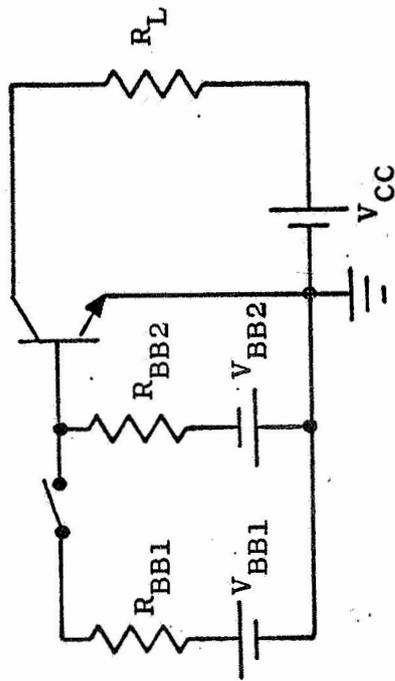


Figure 5

SWITCHING TEST CIRCUIT.



Input Pulse:  $t_r < 20\text{ns}$ ,  $t_f < 20\text{ns}$ ,  $t_p = 10\mu\text{s}$   
Duty Cycle = 1%  
 $R_{BB1} = 3\Omega$ ,  $V_{BB1} = 11.2\text{V}$   
 $R_{BB2} = 4\Omega$ ,  $V_{BB2} = 6\text{V}$   
 $R_L = 2\Omega$ ,  $V_{CC} = 31\text{V}$

Figure 6

SHORTED CLASS B SOAR

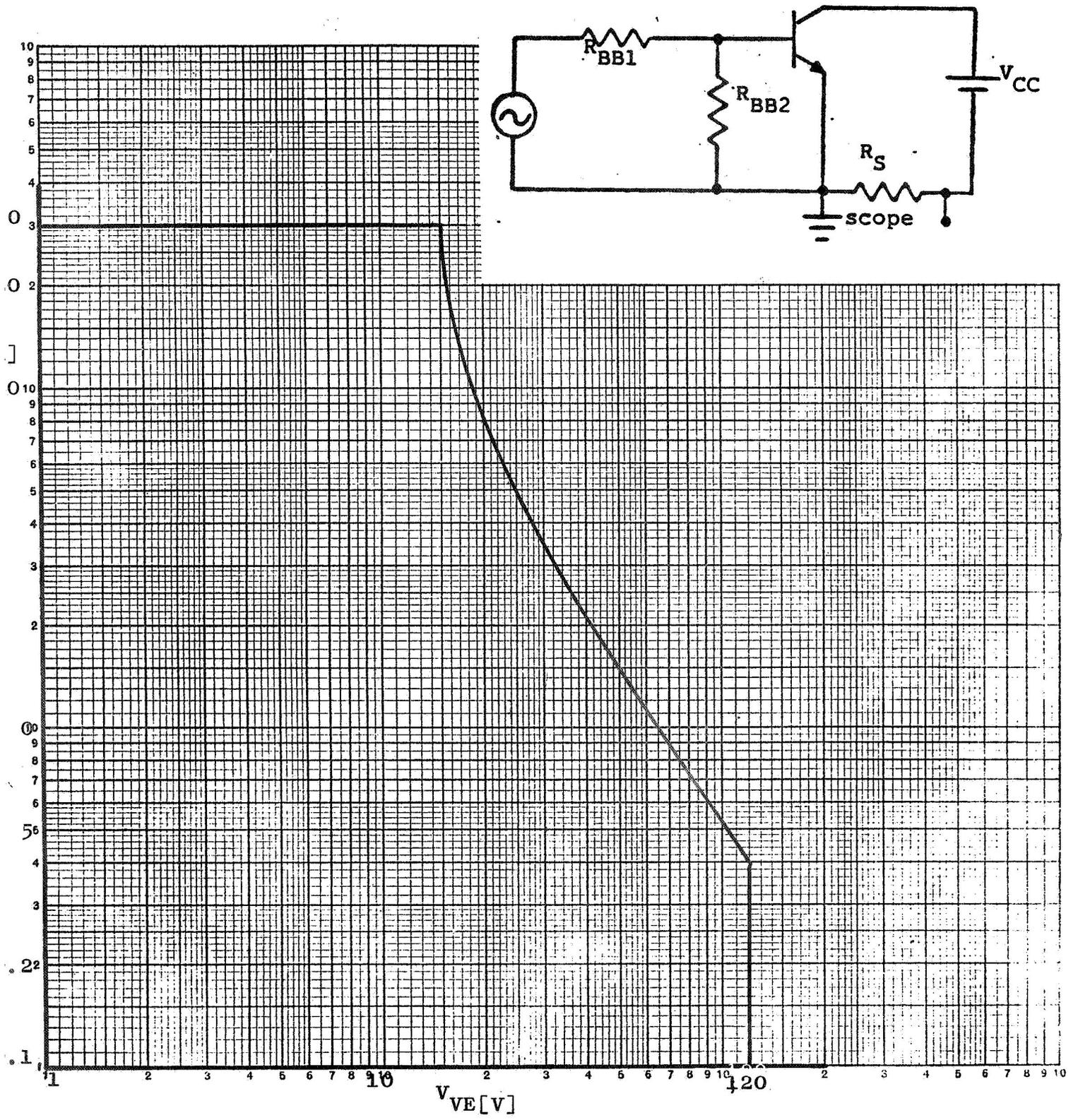


Figure 7

## APPENDIX I

### ADDENDUM

The reports in Sections 7 and 11 contain the results obtained from two groups of the same type of transistor from two different manufacturers.

This type of testing yielded a better device variation which indicates that wide differences do exist between manufacturers and approved products.

From the data obtained from both groups of devices a single SOAR specification was generated. The combined results expand the JEDEC registration and supplements the specification with complete SOAR curves and test conditions.

Although the test limits encompass both manufacturers devices, some manufacturers may have to re-evaluate their devices at the specified SOAR points.